

CMPSCI 670: Computer Vision

Color

University of Massachusetts, Amherst
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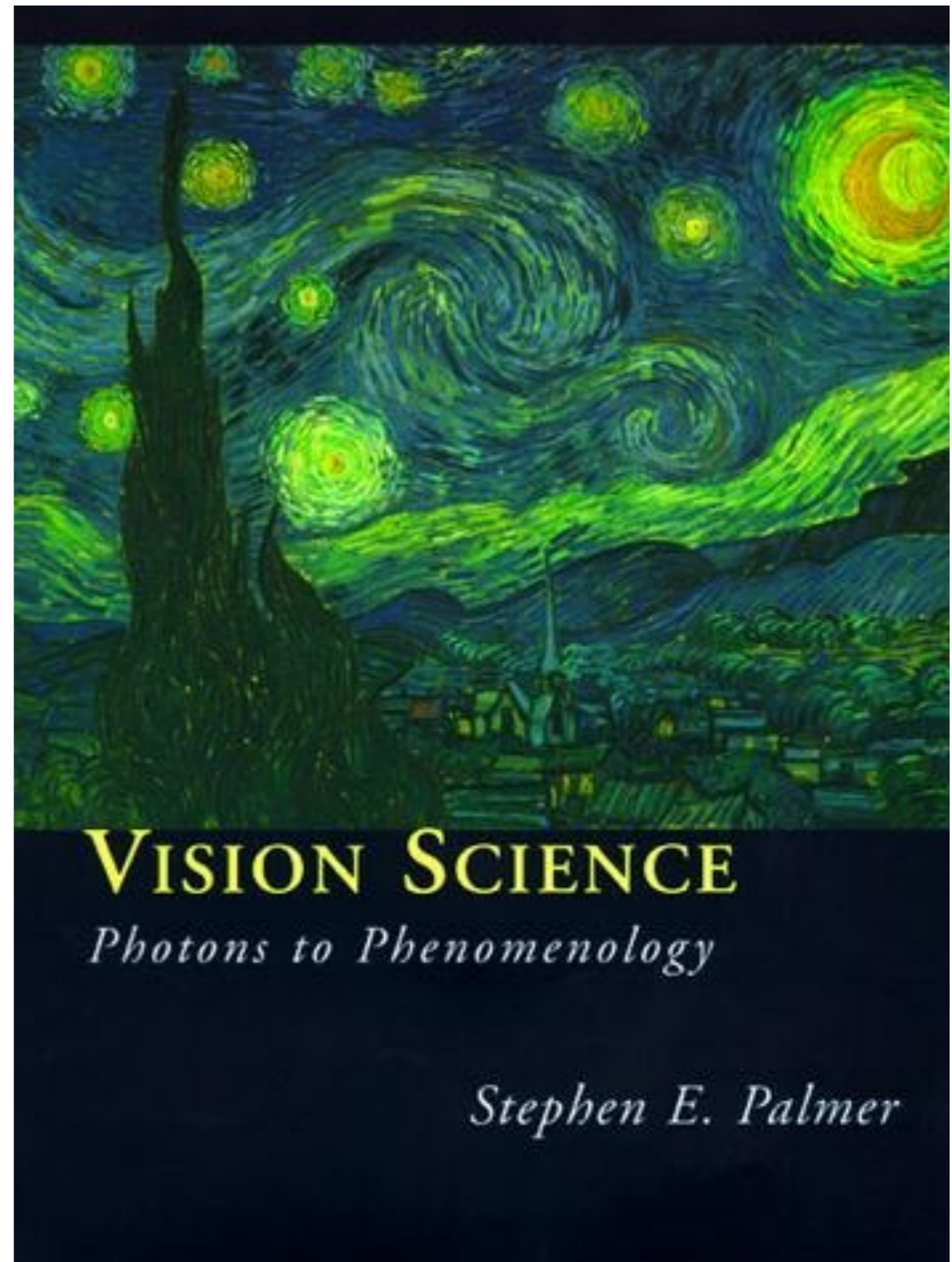
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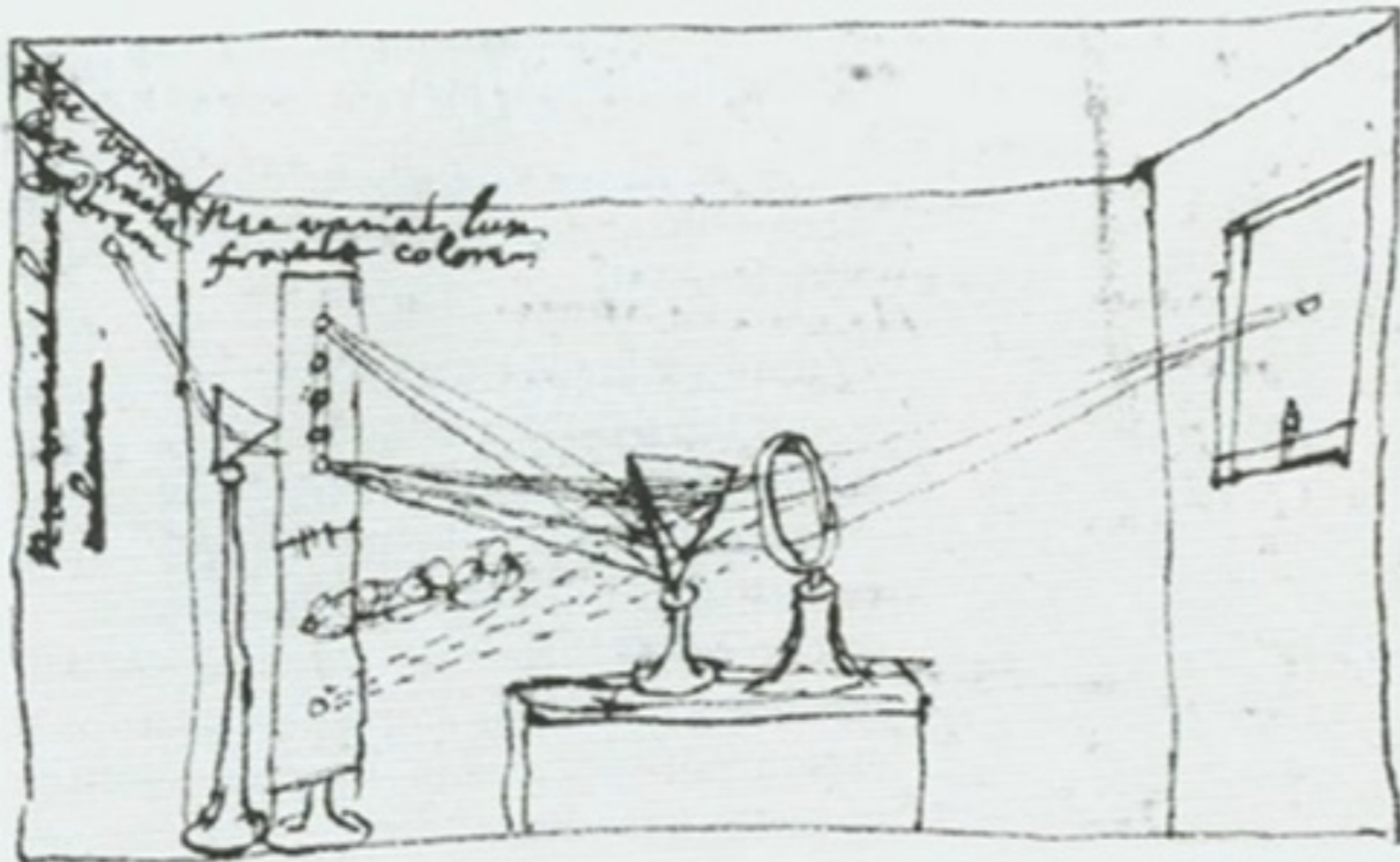
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GREEN
BLUE

What is color?

- “Color is the result of interaction between light in the environment and our visual system”
- “Color is a psychological property of our visual experiences when we look at objects and lights, not a physical property of those objects or lights” — S. Palmer, *Vision Science: Photons to Phenomenology*

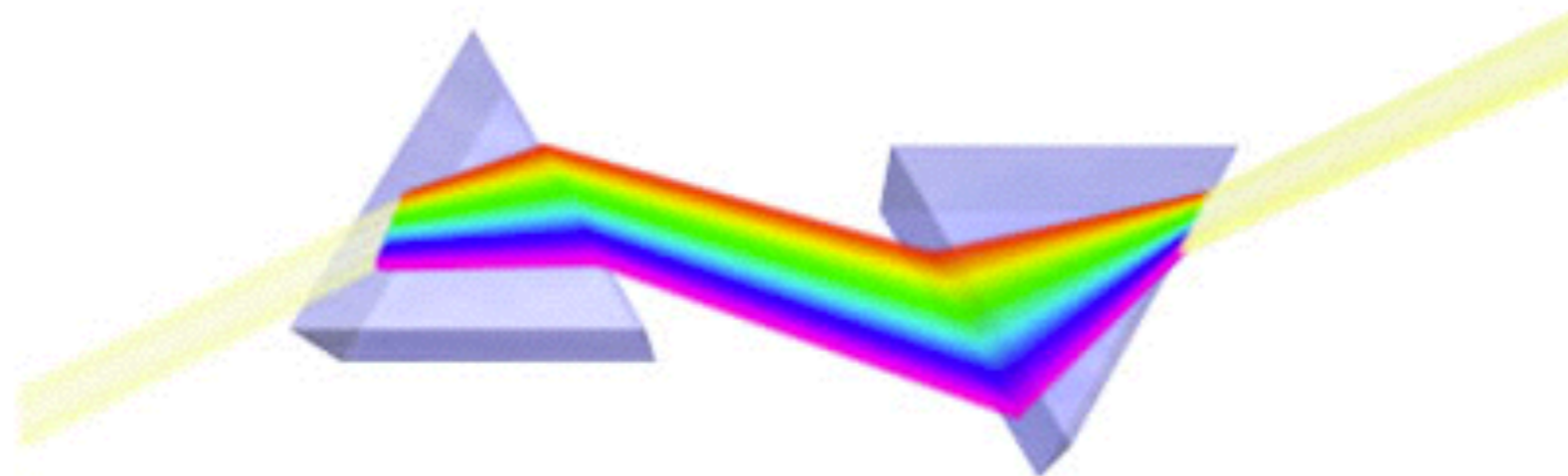


Newton's theory of light

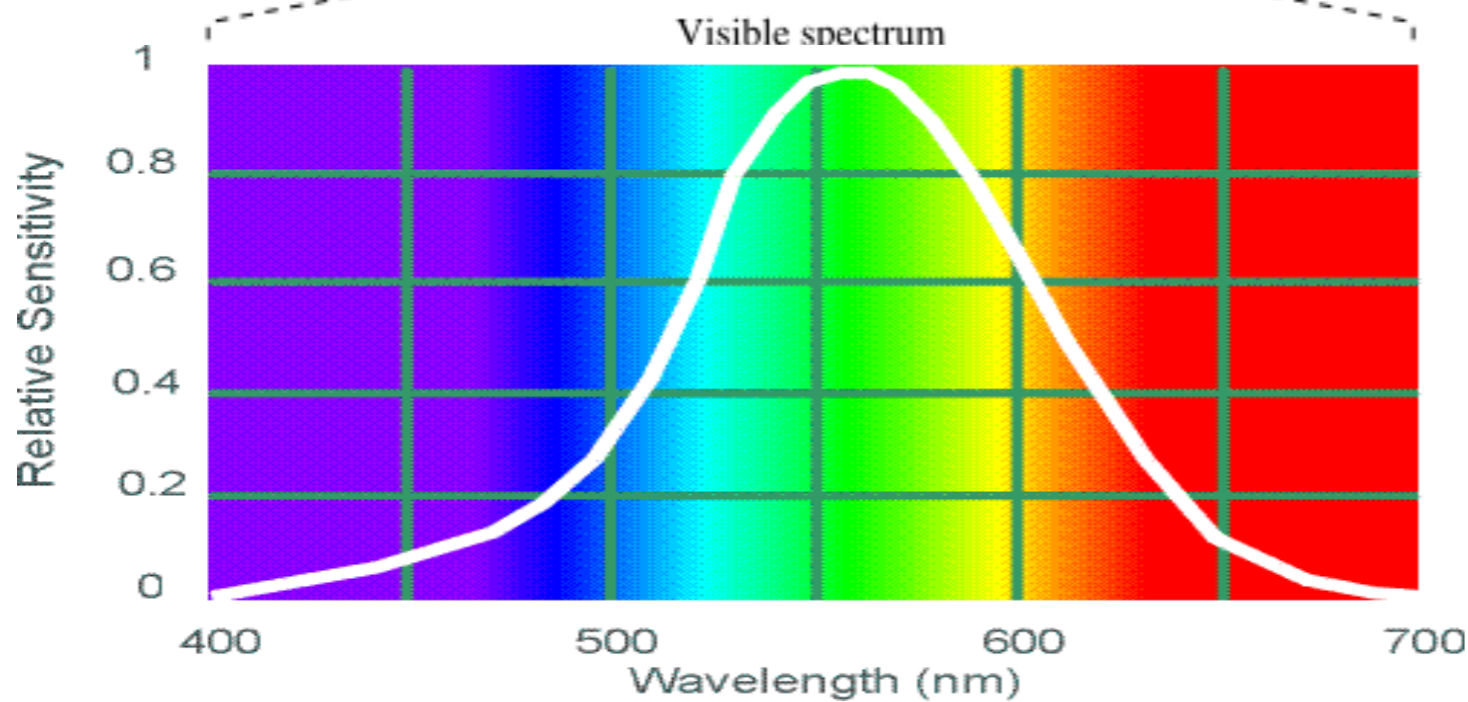
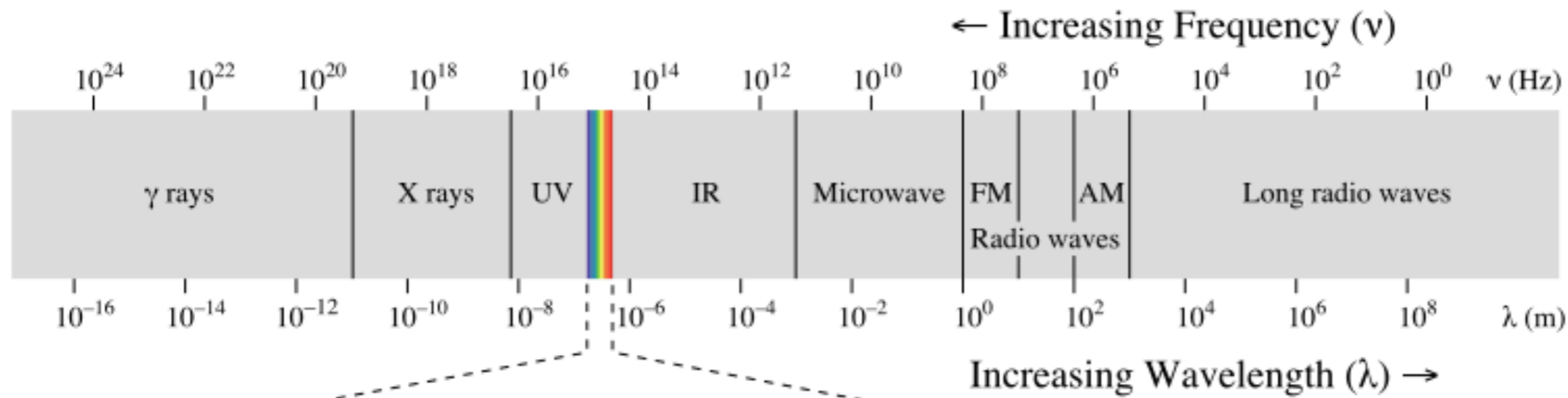


Newton's sketch of his crucial experiment in which light from the sun is refracted through a prism. One color is then refracted through a second prism to show that it undergoes no further change. Light is then shown to be composed of the colors refracted in the second prisms.

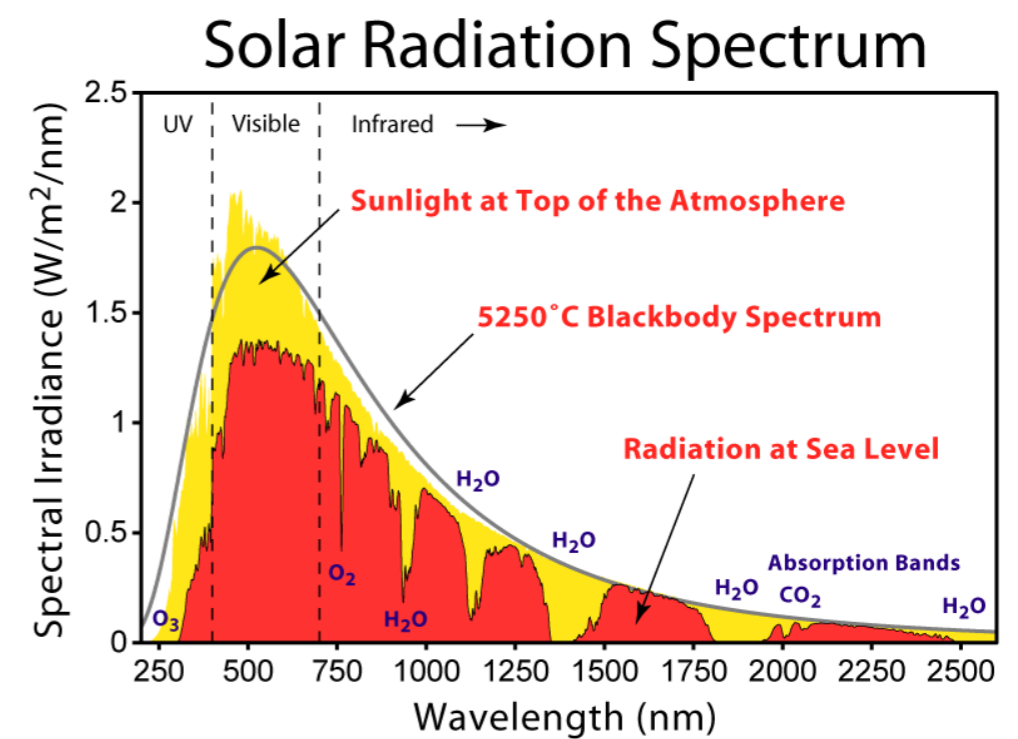
Image credit: [Warden and Fellows](#)



The electromagnetic spectrum

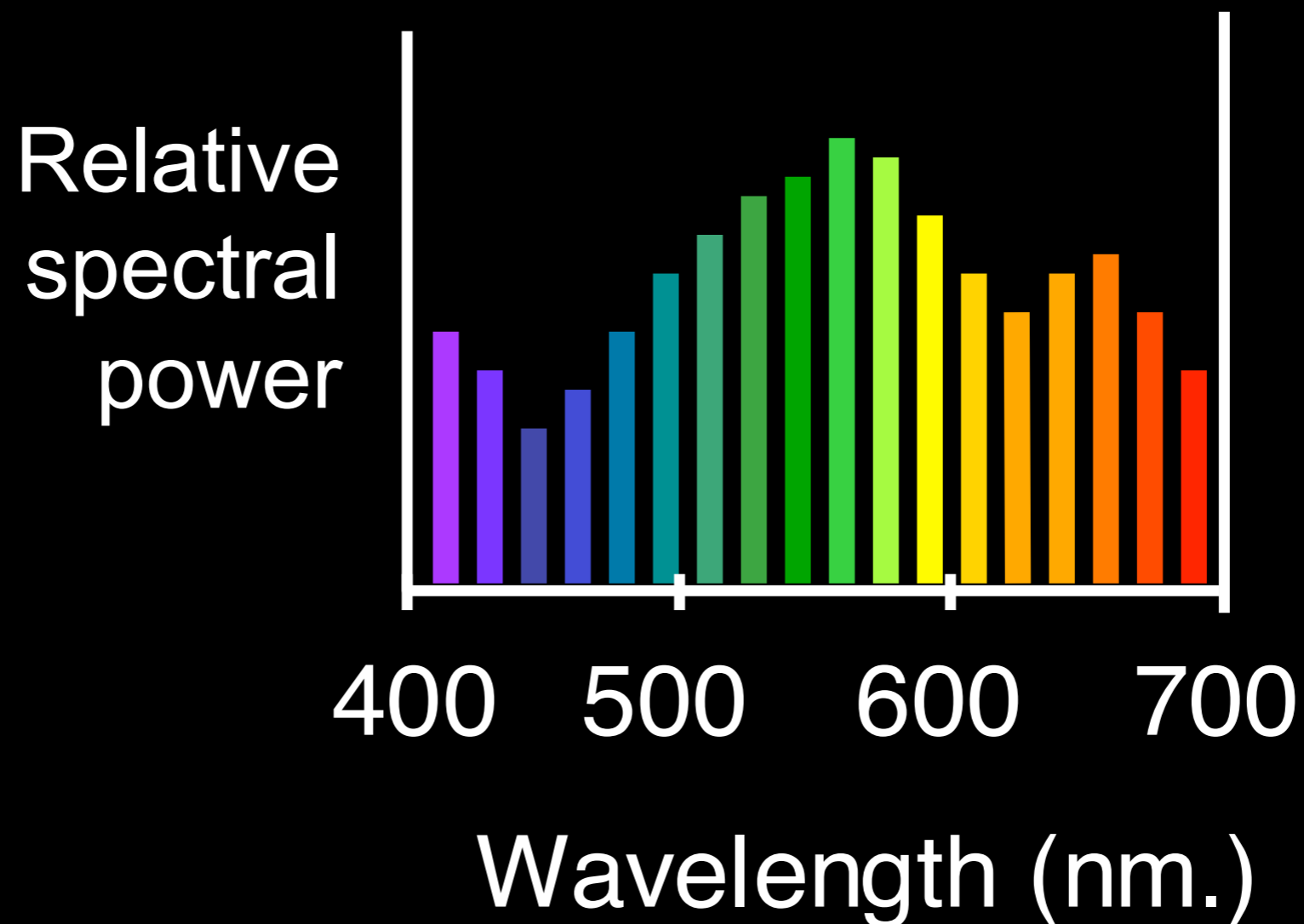


Human Luminance Sensitivity Function



The Physics of Light

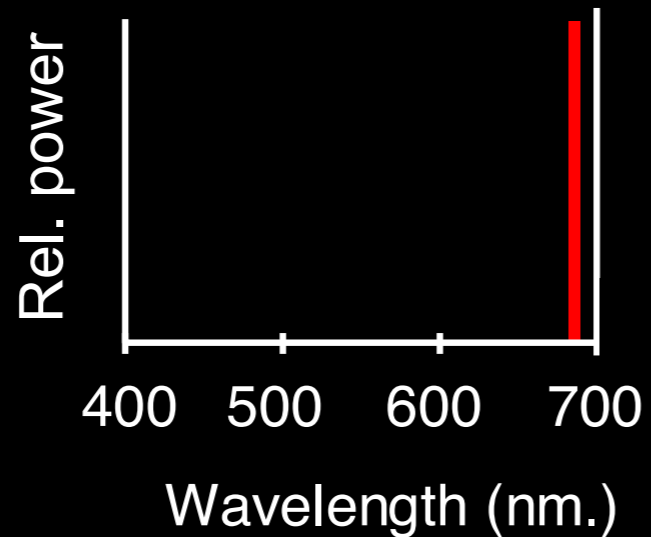
Any source of light can be completely described physically by its spectrum: the amount of energy emitted (per time unit) at each wavelength 400 - 700 nm.



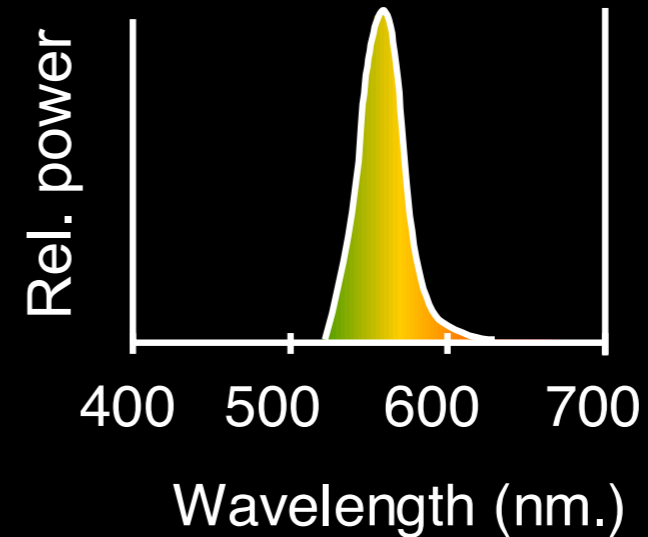
Spectra of Light Sources

Some examples of the spectra of light sources

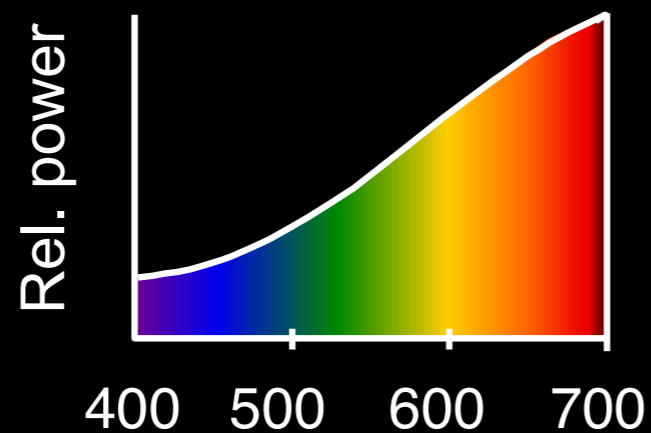
A. Ruby Laser



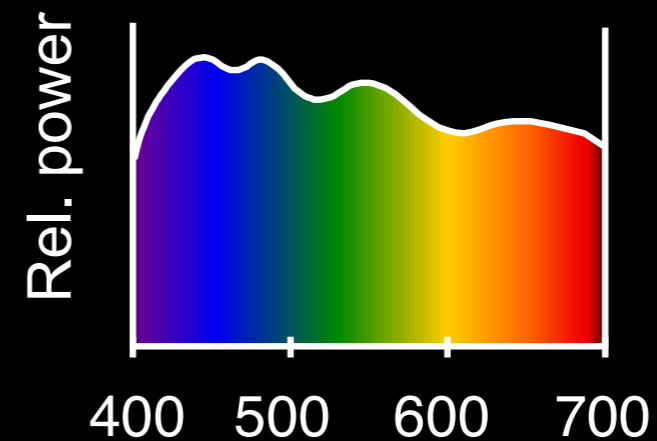
B. Gallium Phosphide Crystal



C. Tungsten Lightbulb

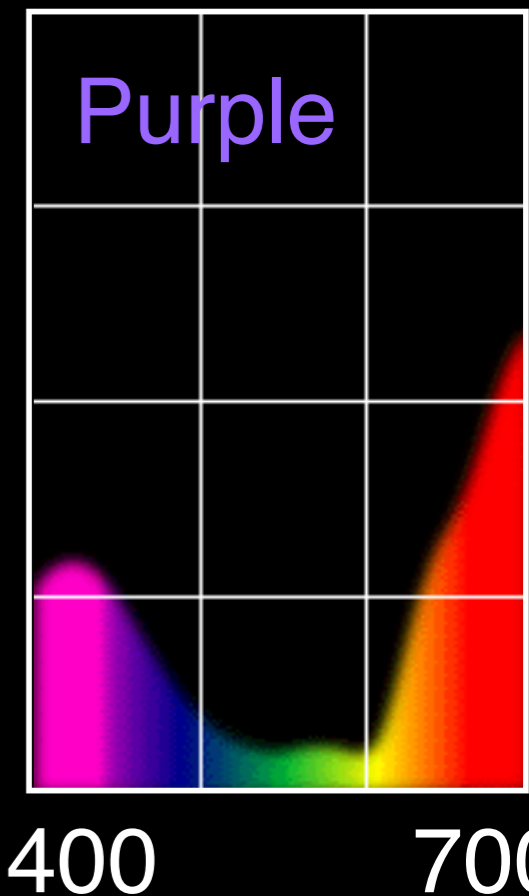
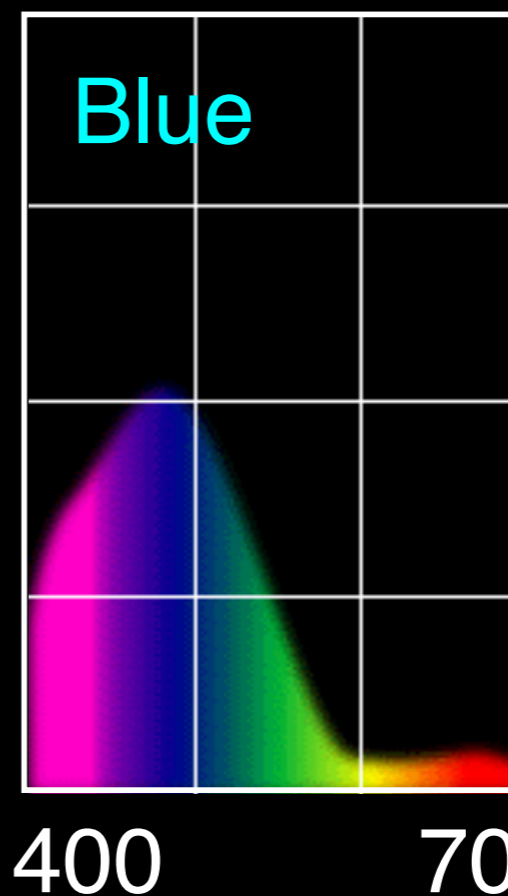
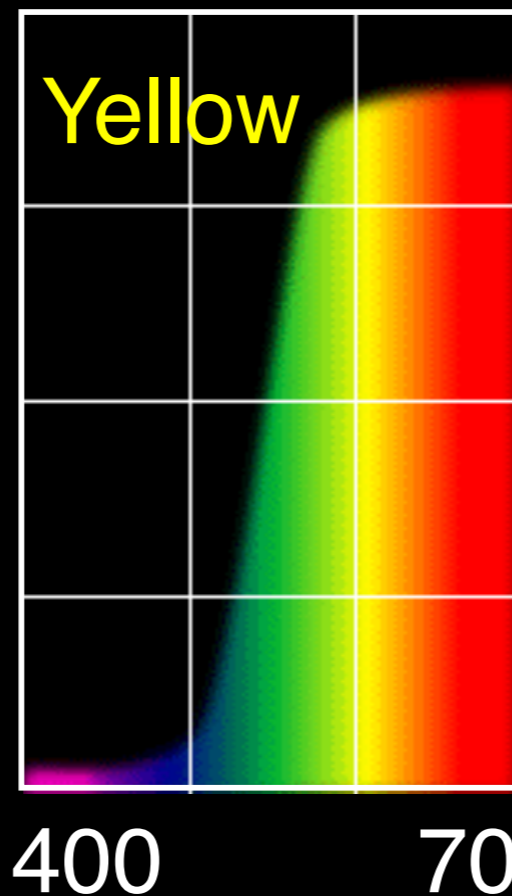
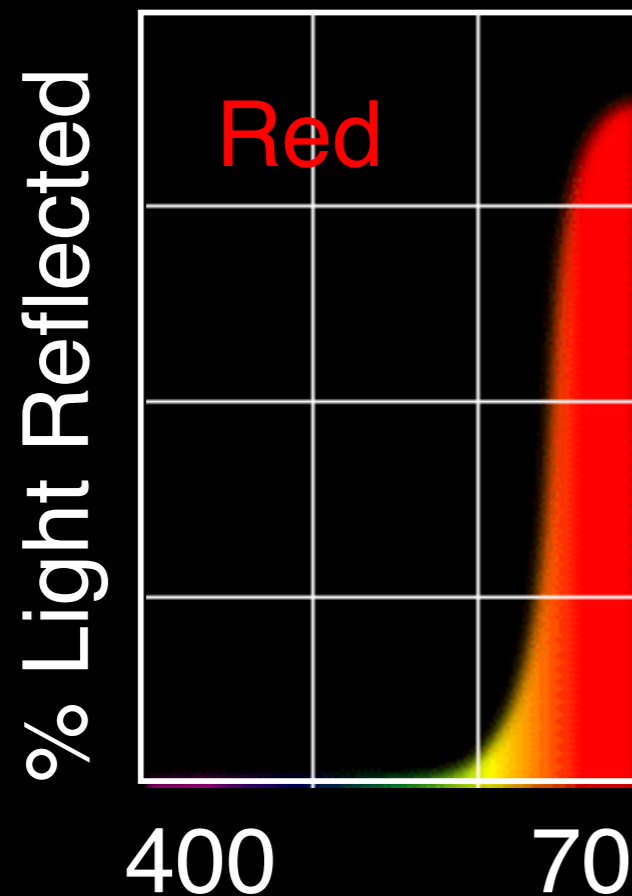


D. Normal Daylight



Reflectance Spectra of Surfaces

Some examples of the reflectance spectra of surfaces

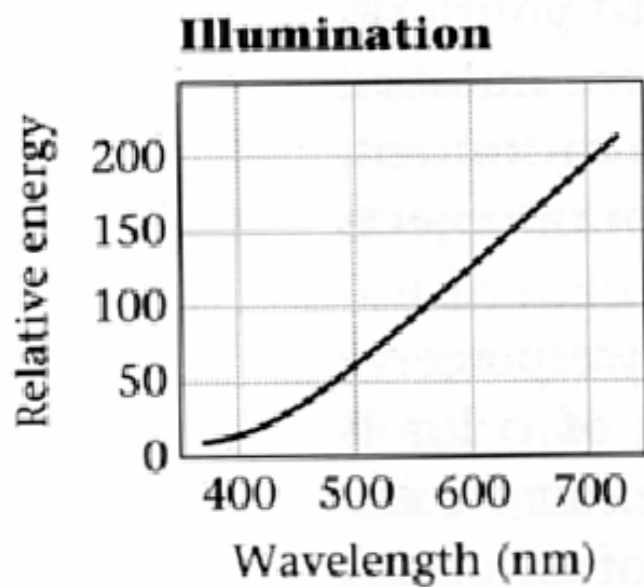


Wavelength (nm)

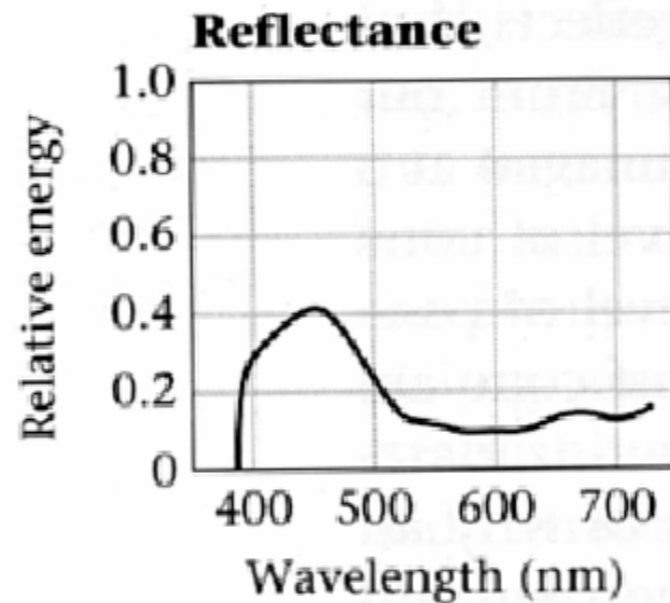
Interaction of light and surfaces



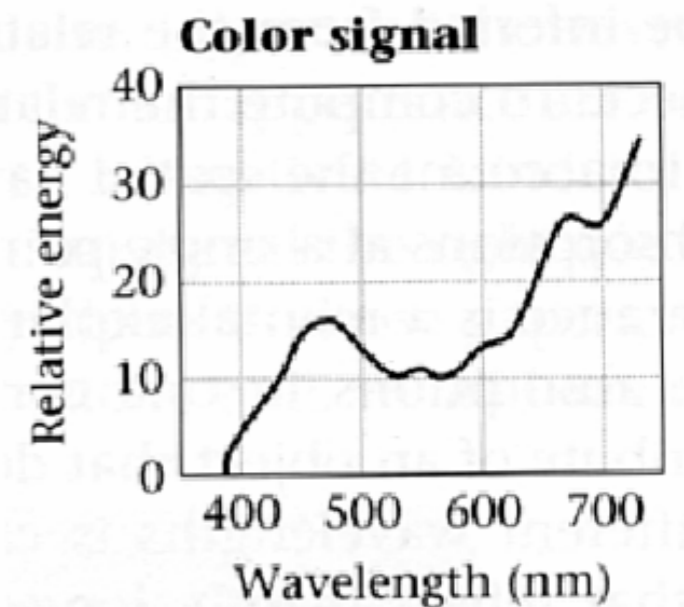
- Reflected color is the result of interaction between the light source spectrum and the reflection surface reflectance



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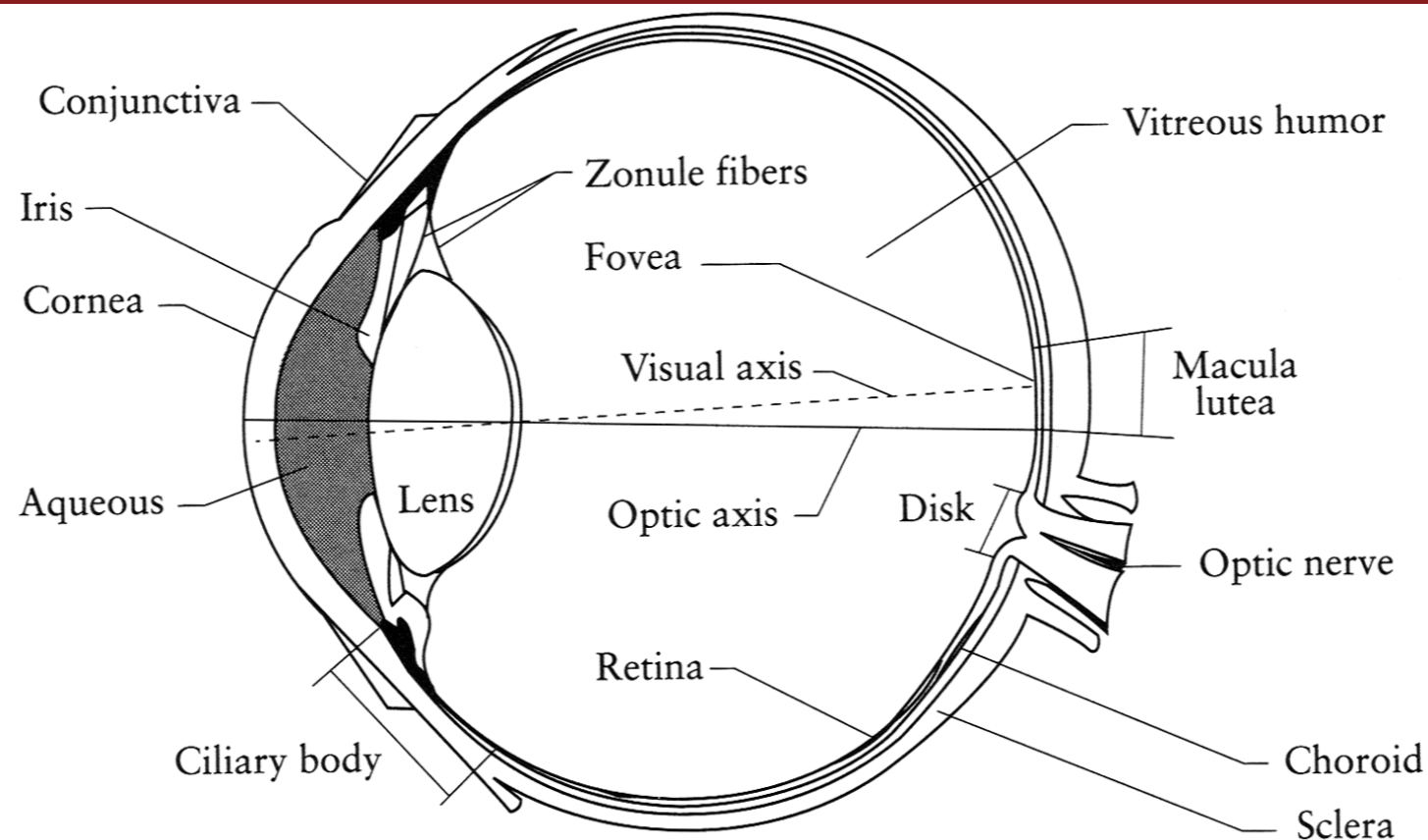
Interaction of light and surfaces

- What is the observed color of any surface under monochromatic light?



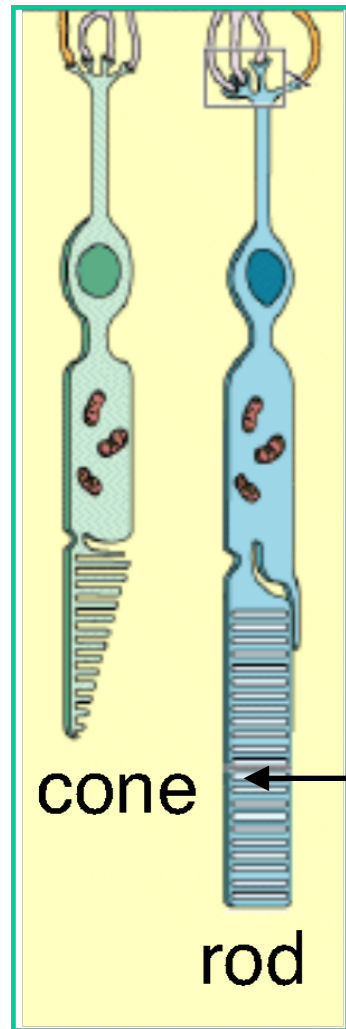
Room for one color, Olafur Eliasson

The eye



- The human eye is a sophisticated camera!
 - **Lens** - changes the shape by using ciliary muscles (to focus on objects at different distances)
 - **Pupil** - the hole (aperture) whose size is controlled by iris
 - **Iris** - colored annulus with radial muscles
 - **Retina** - photoreceptor cells

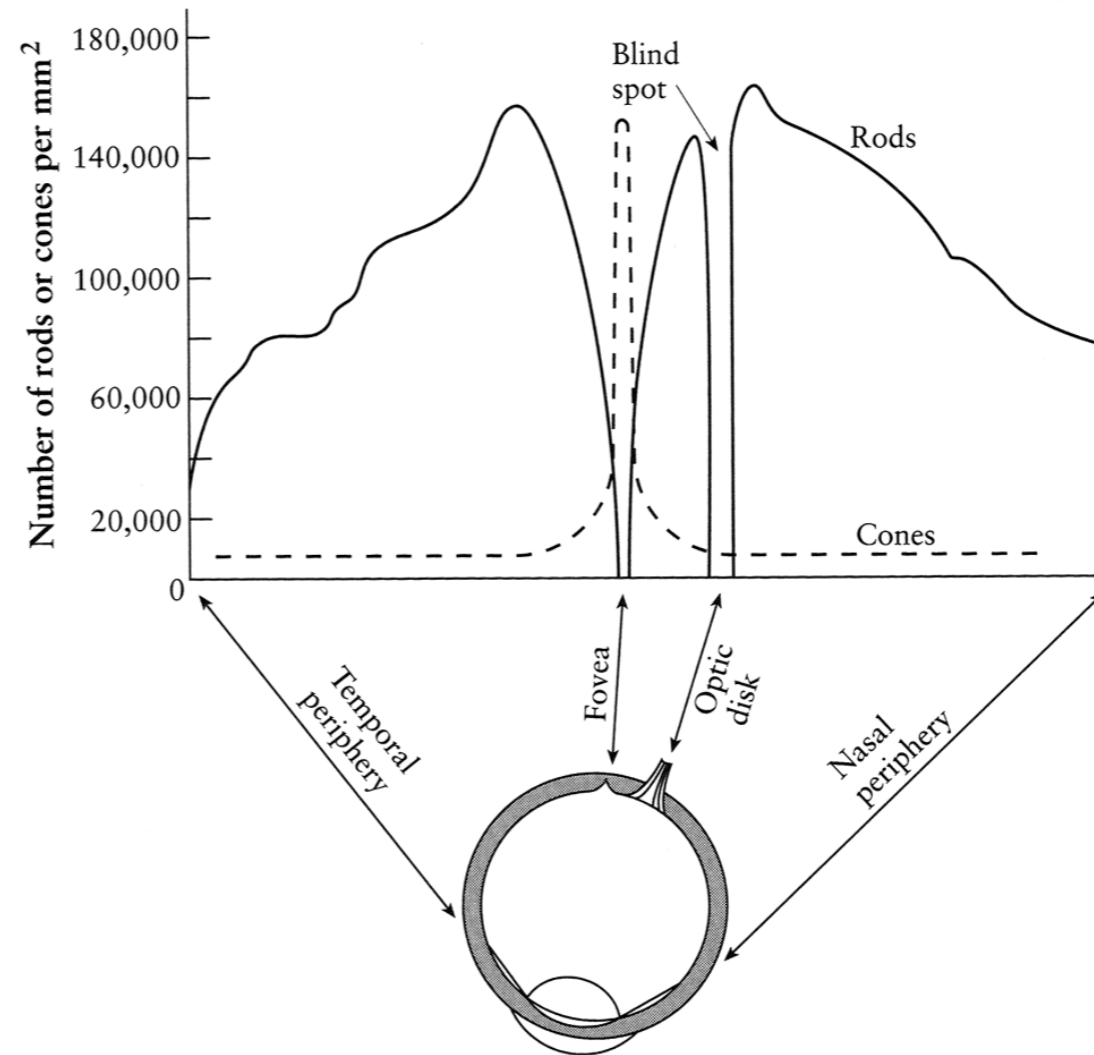
Rods and cones, fovea



pigment molecules

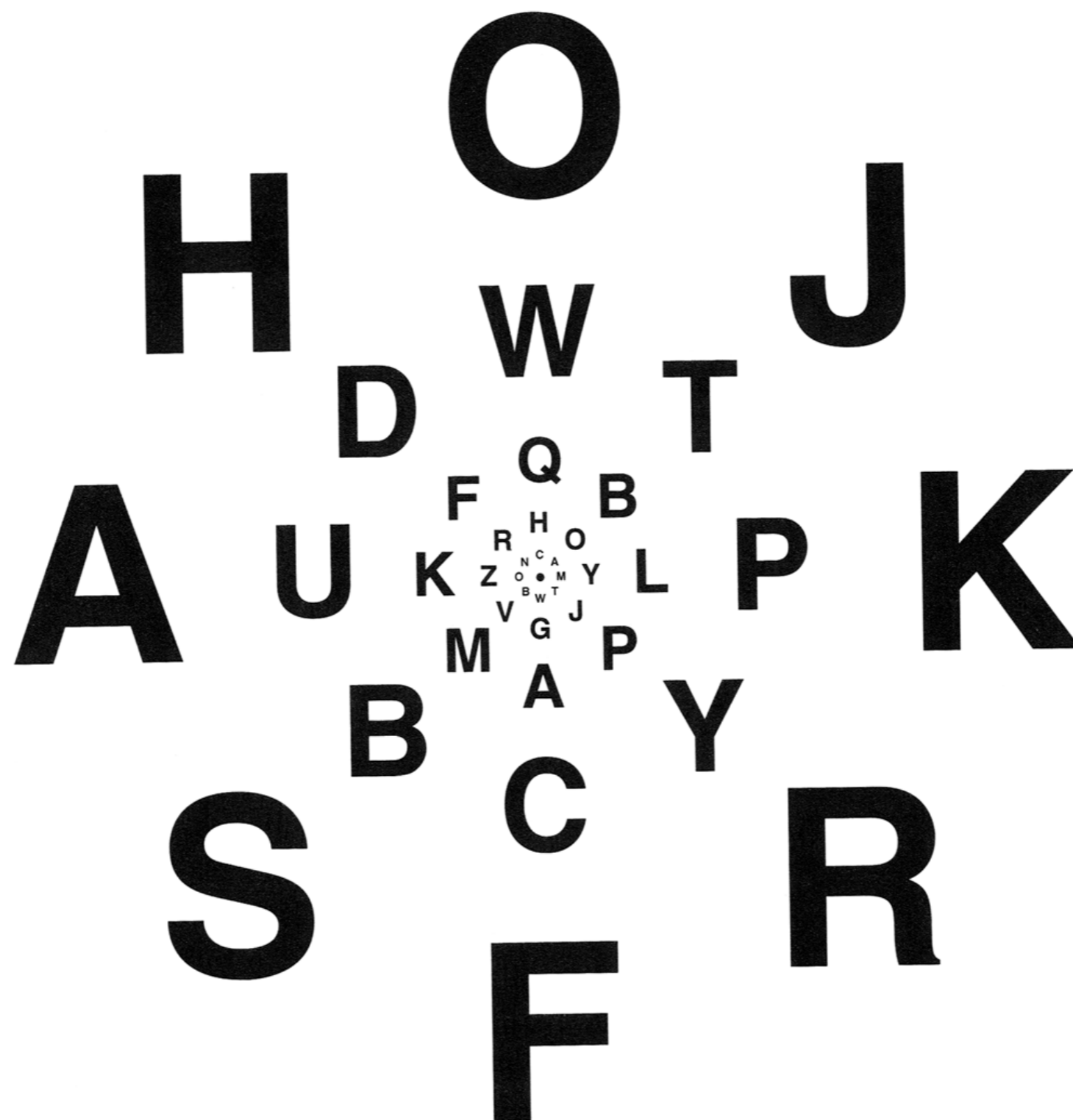
cone

rod



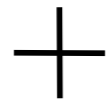
- Rods are responsible for intensity, cones for color perception
- Rods and cones are non-uniformly distributed on the retina
 - **Fovea** - Small region (1 or 2°) at the center of the visual field containing the highest density of cones - and no rods
- There are about 5 million cones and 100 million rods in each eye

Demonstration of visual acuity



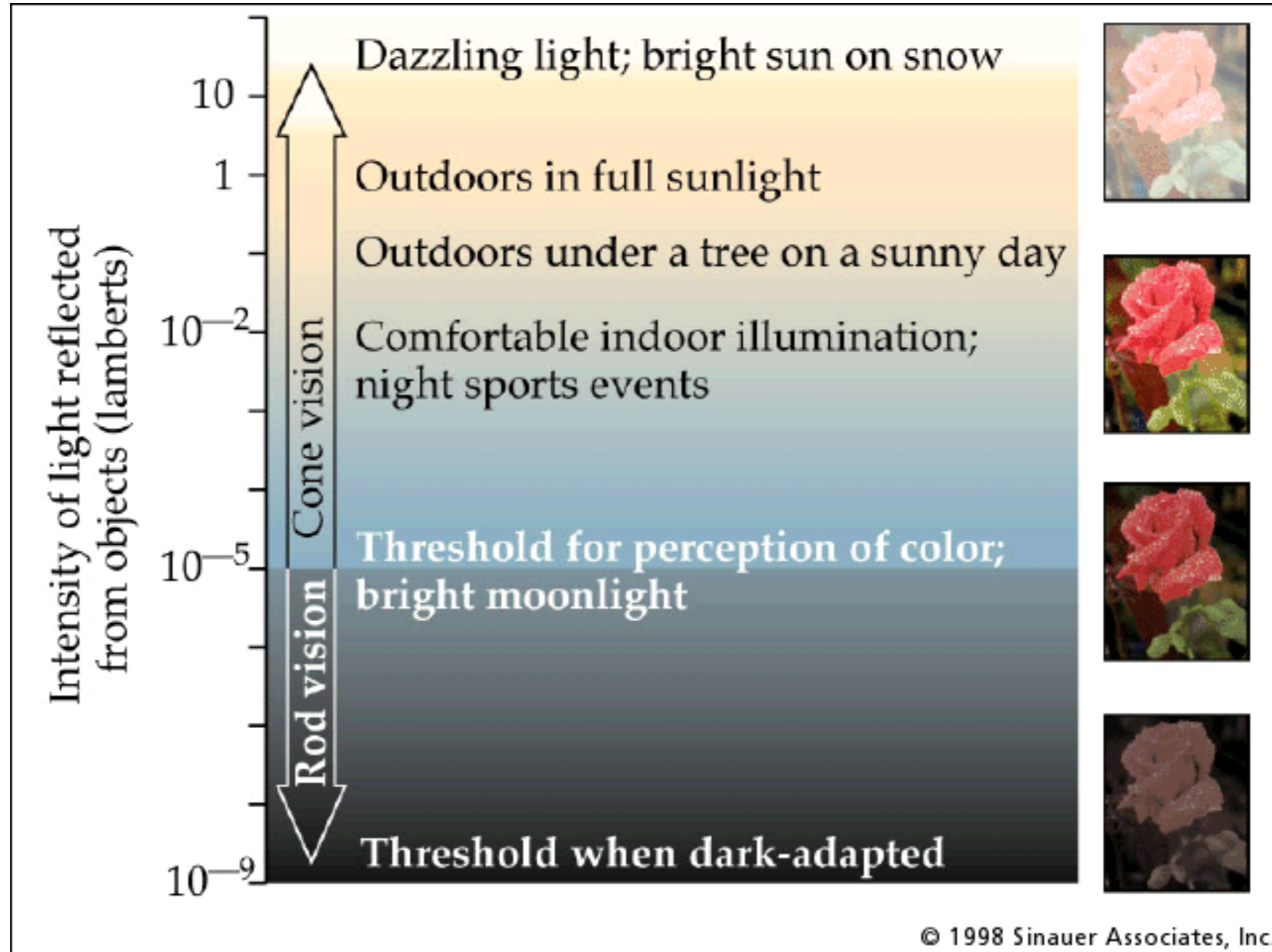
With one eye shut, at the right distance, all of these letters should appear equally legible (Glassner, 1.7).

Blind spot



With left eye shut, look at the cross on the left. At the right distance, the circle on the right should disappear (Glassner, 1.8).

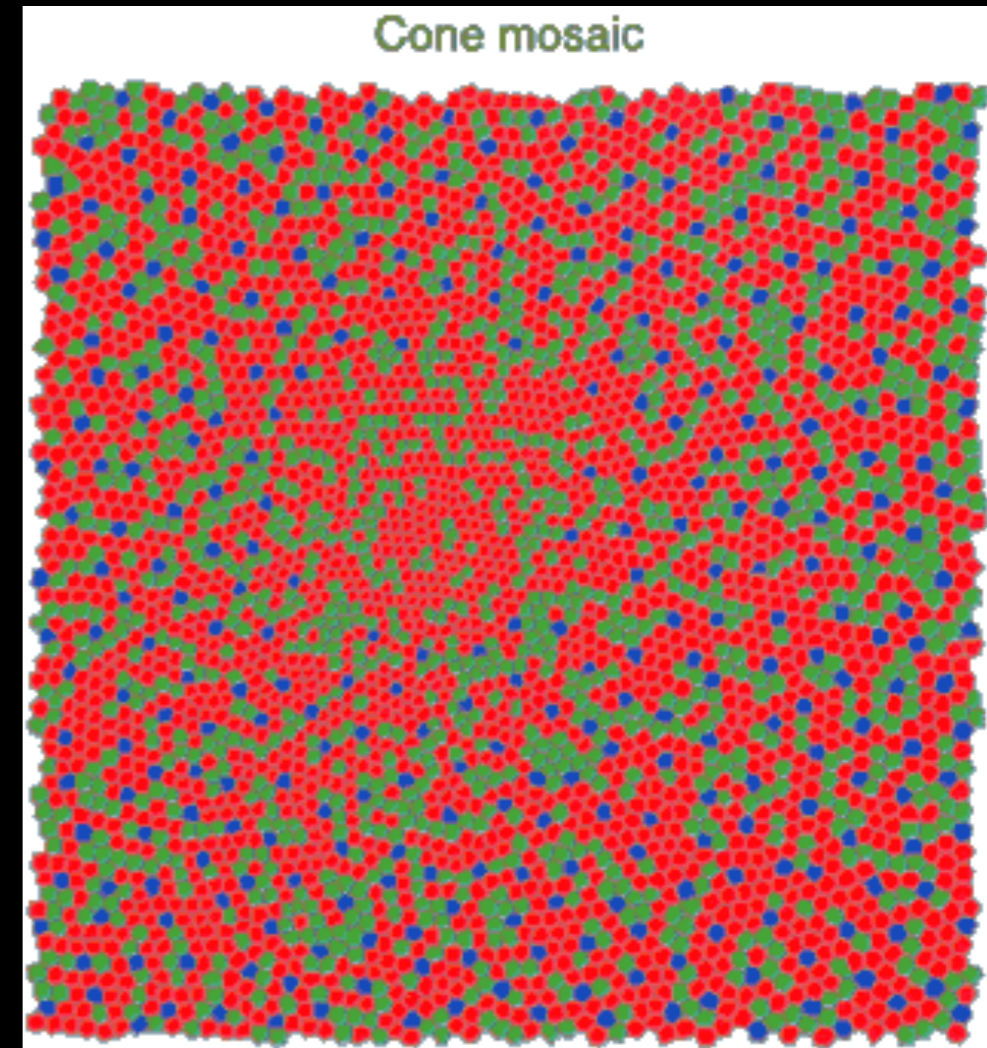
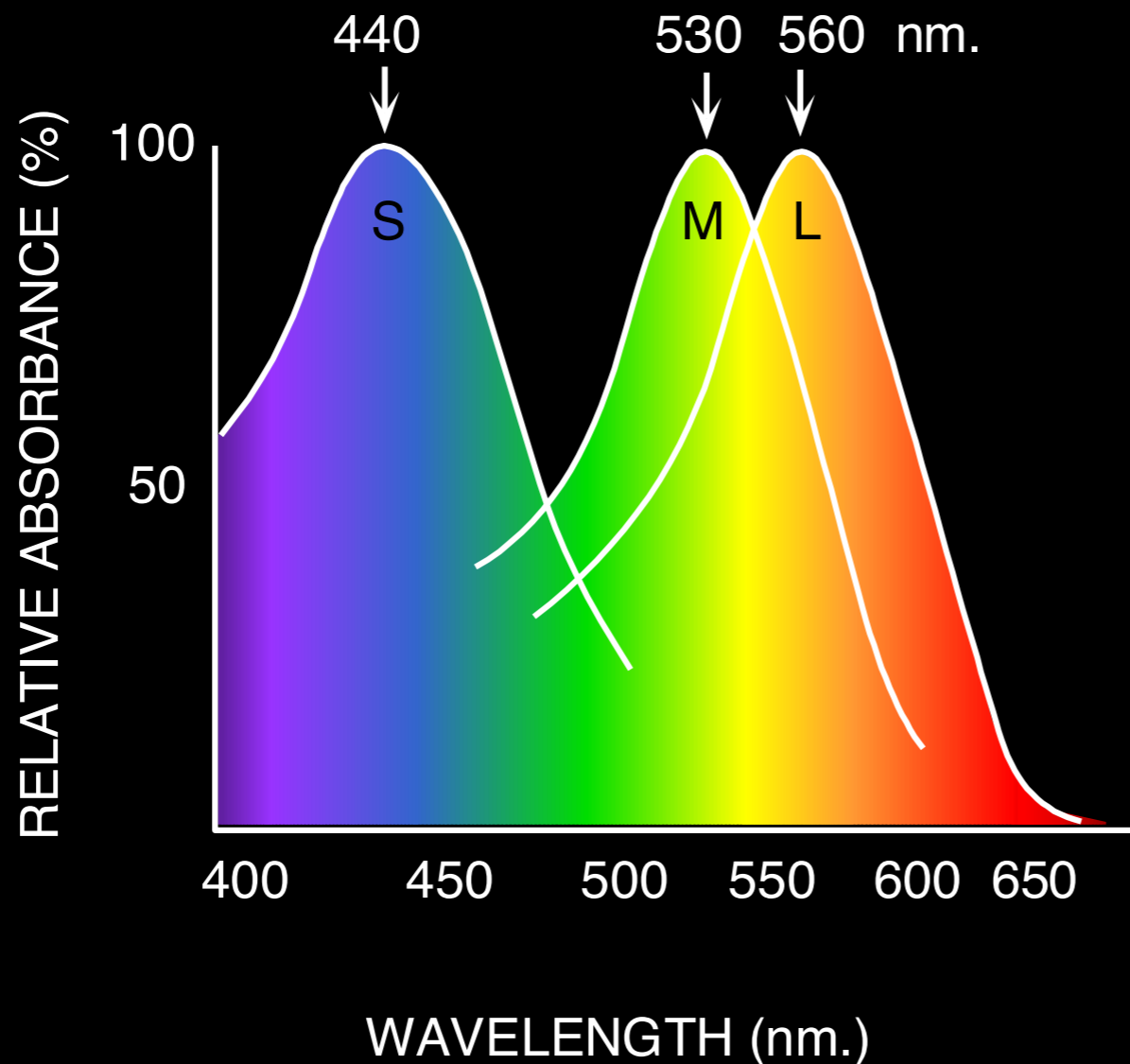
Rod/cone sensitivity



Why can't we read in the dark?

Physiology of Color Vision

Three kinds of cones:



- Ratio of L to M to S cones: approx. 10:5:1
- Almost no S cones in the center of the fovea

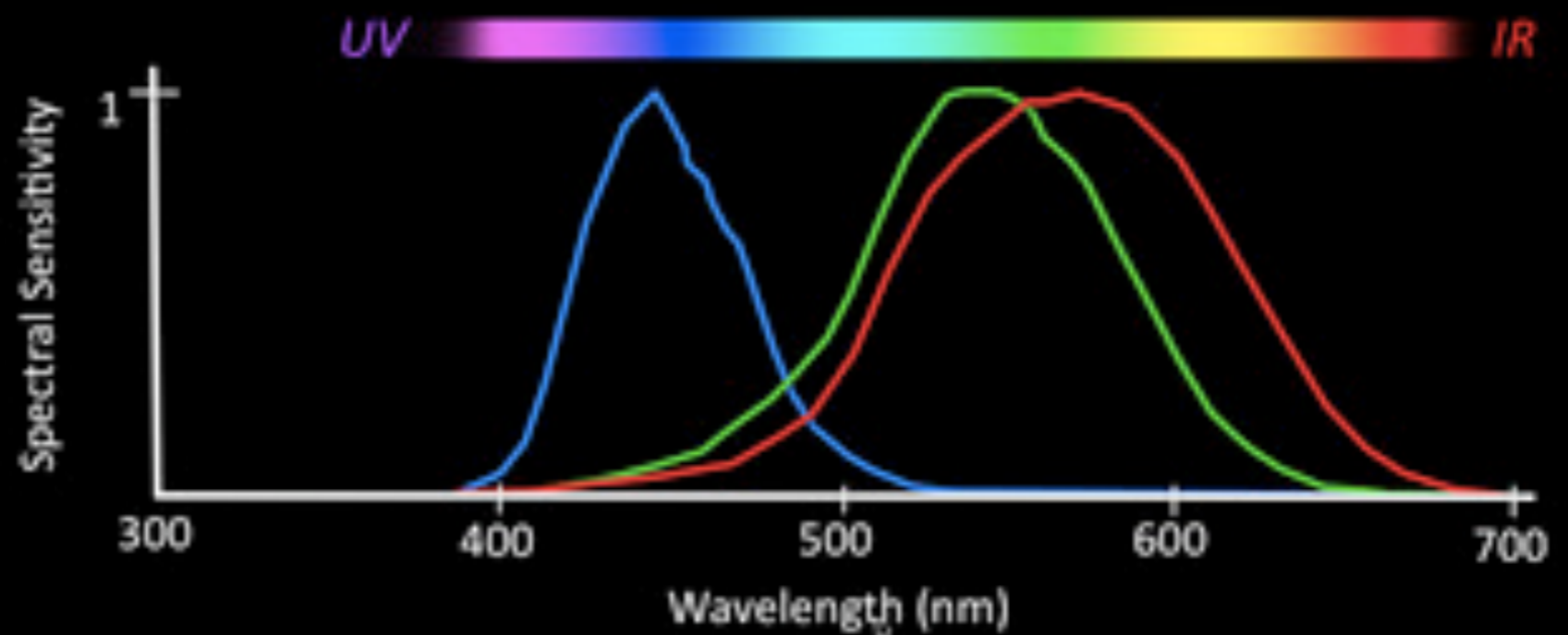
Physiology of color vision: fun facts

- “M” and “L” pigments are encoded on the X-chromosome
 - That’s why men are more likely to be color blind
 - “L” gene has high variation, so some women may be *tetrachromatic*
- Some animals have one (night animals), two (e.g. dogs), four (fish, birds), five (pigeons, some reptiles/amphibians), or even 12 (mantis shrimp) types of cones
- <http://www.mezzmer.com/blog/how-animals-see-the-world/>

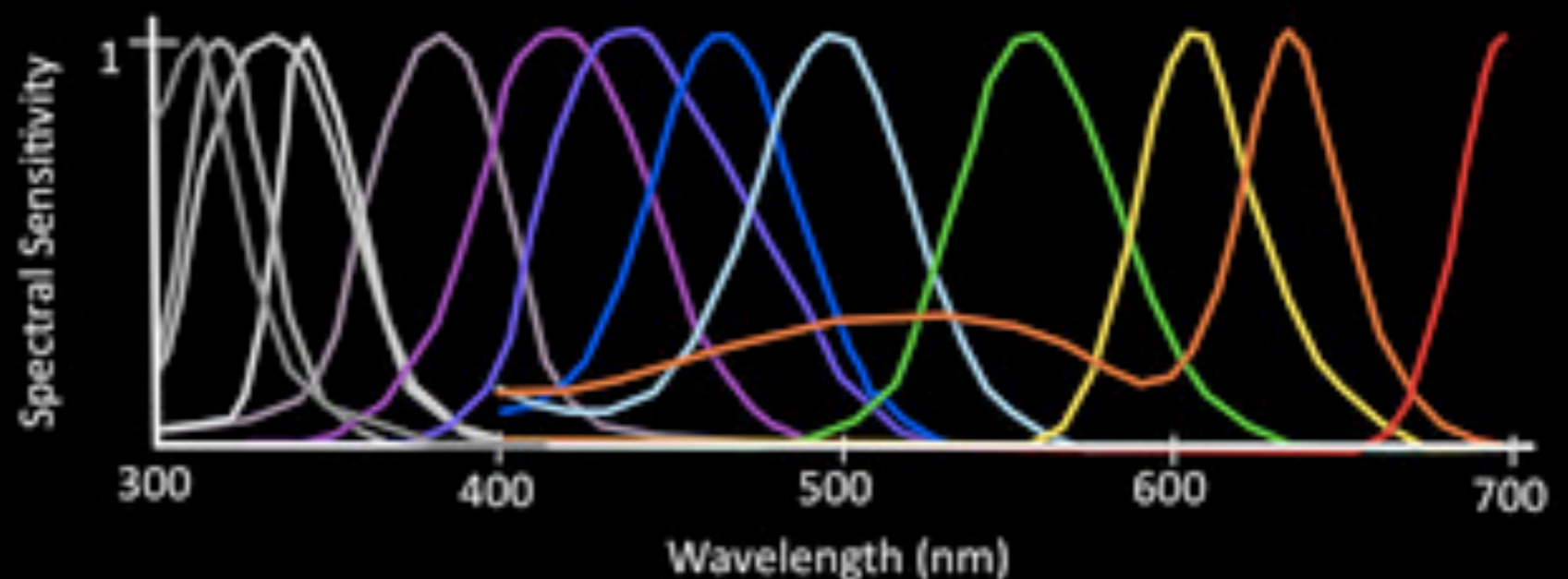
http://en.wikipedia.org/wiki/Color_vision

Mantis Shrimp: Extraordinary Eyes

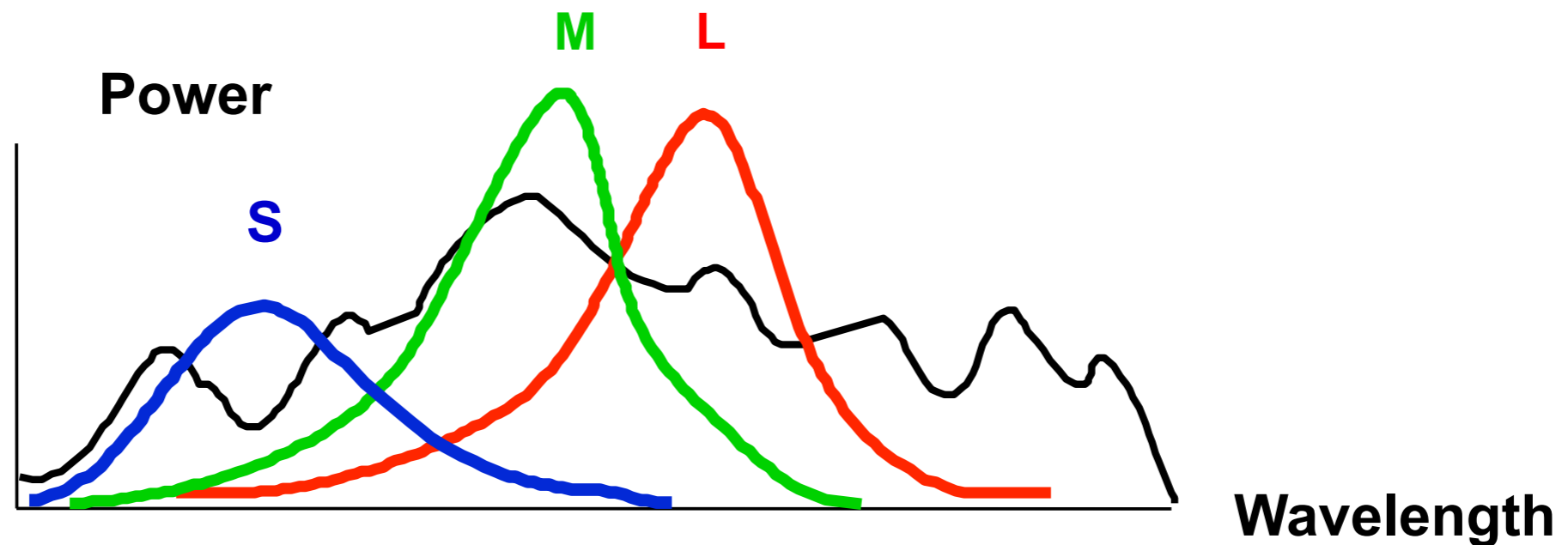
Homo sapiens



Neogonodactylus oestedii



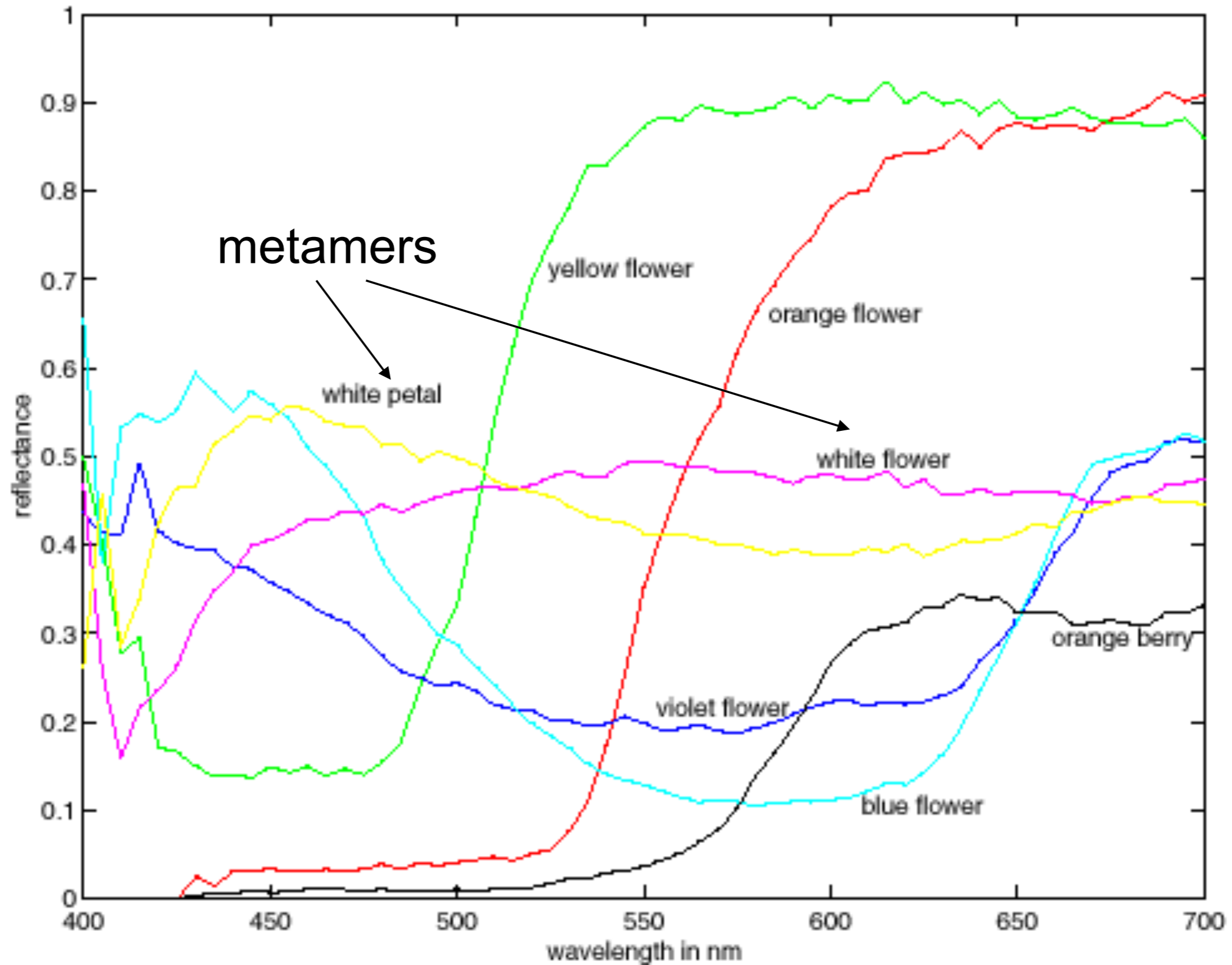
Color perception



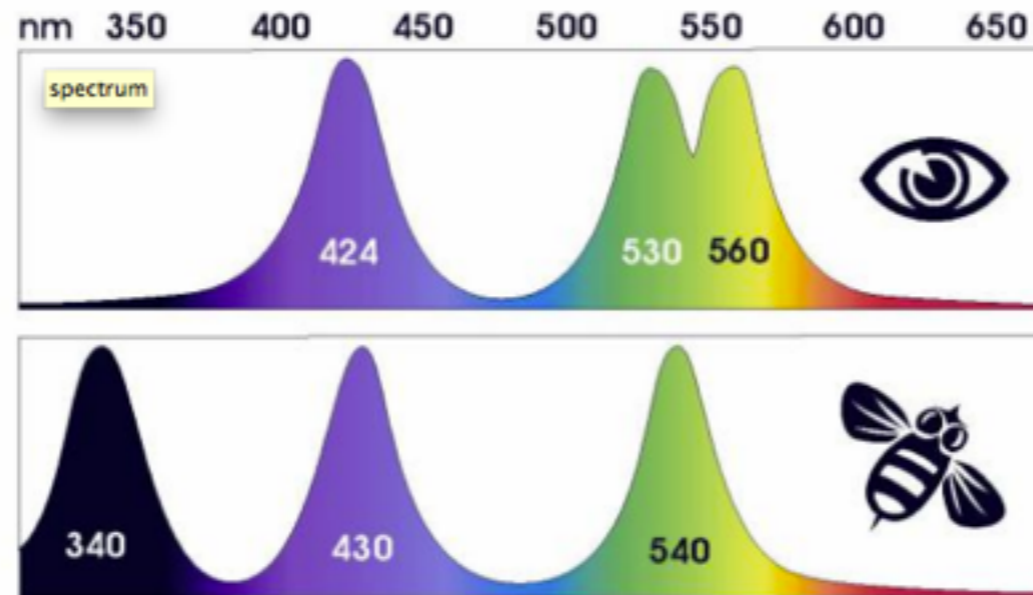
Rods and cones act as filters on the spectrum

- To get the output of a filter, multiply its response curve by the spectrum, integrate over all wavelengths
 - Each cone yields one number
- How can we represent an entire spectrum with 3 numbers?
- We can't! A lot of the information is lost
 - As a result, two different spectra may appear indistinguishable
 - Such spectra are known as **metamers**

Spectra of some real-world surfaces



How insects see



<http://fieldguidetohummingbirds.wordpress.com/2008/11/11/do-we-see-what-bees-see/>



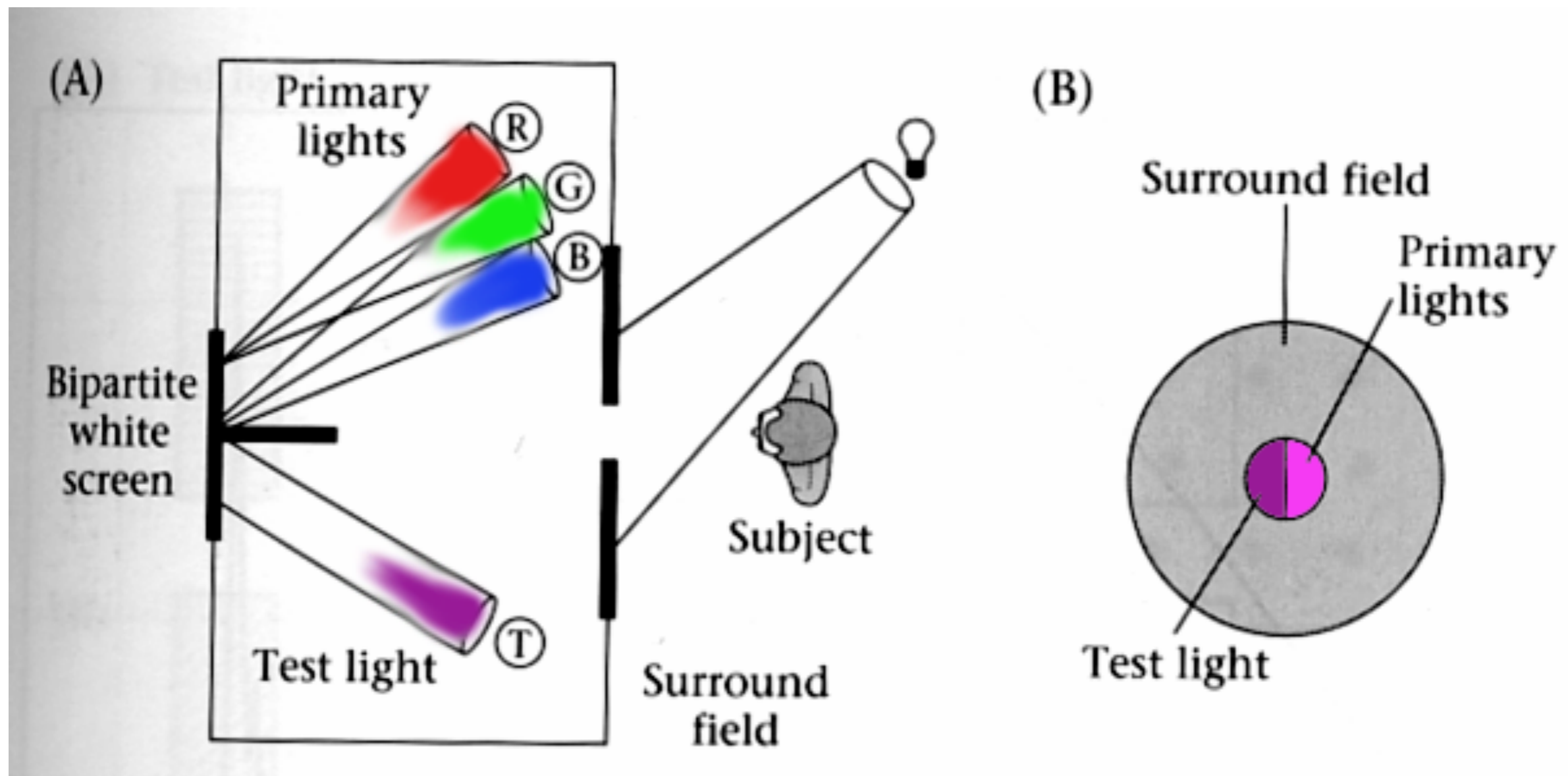
visible light image



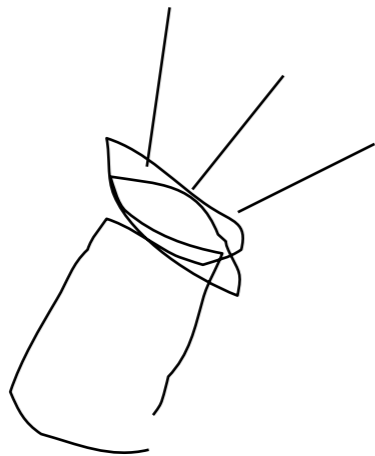
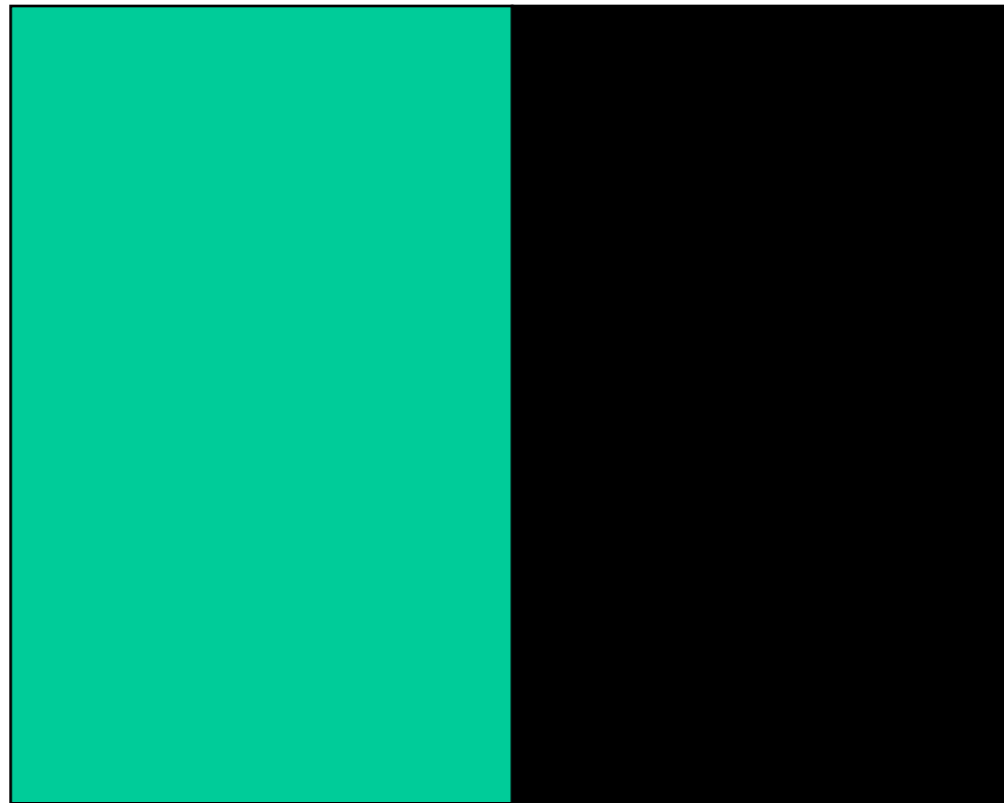
simulated bee vision

Standardizing color experience

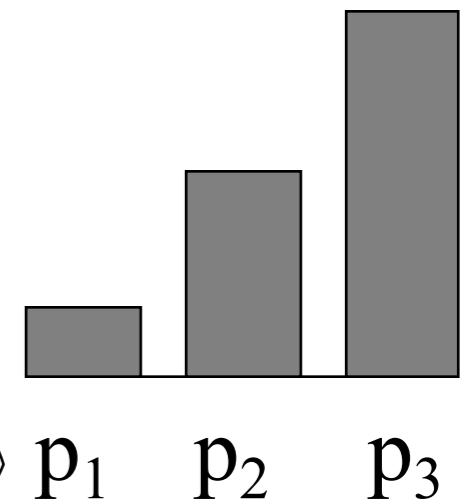
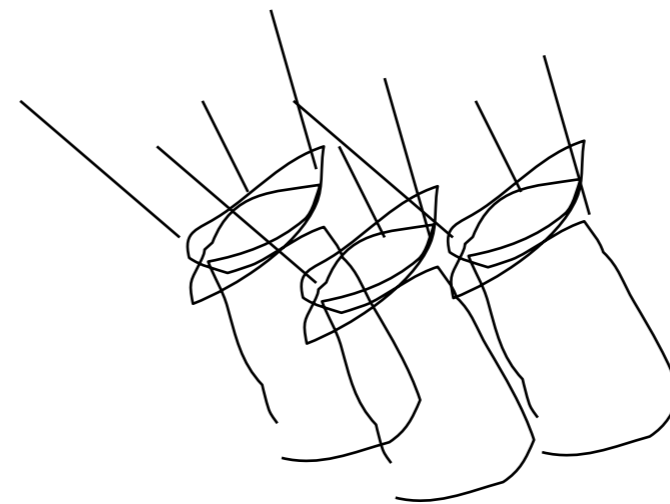
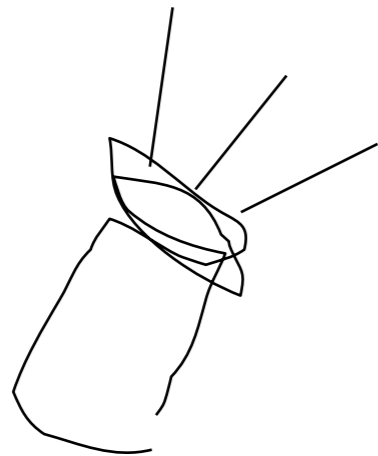
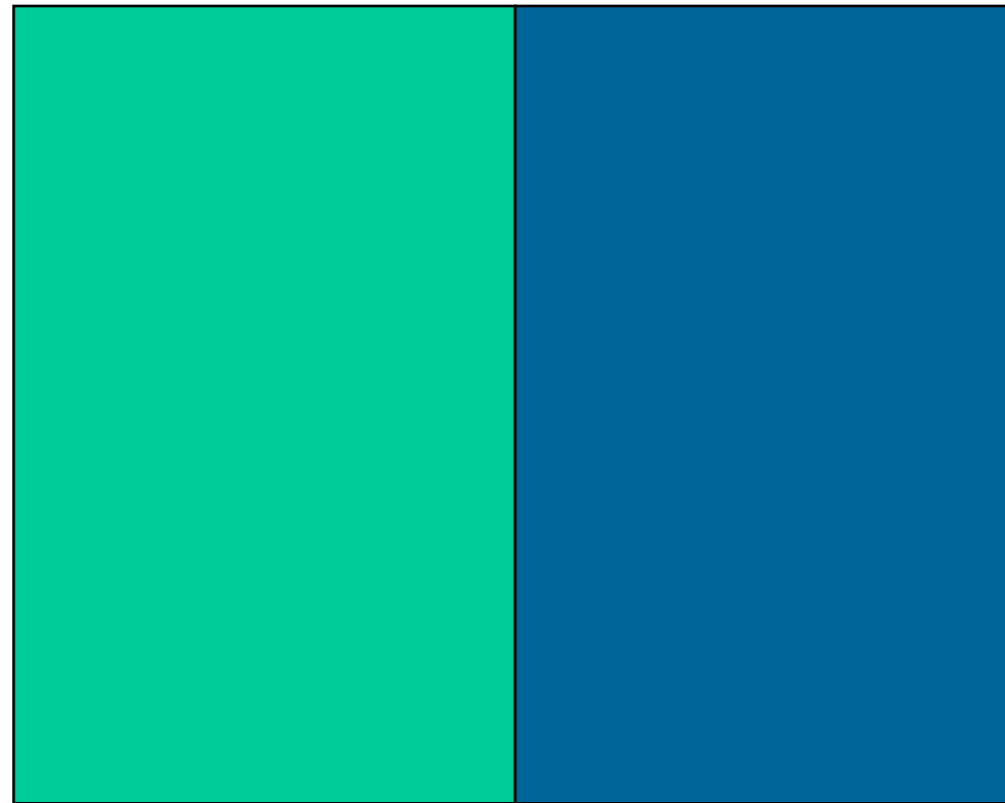
- We would like to understand which spectra produce the same color sensation in people under similar viewing conditions
- Color matching experiments



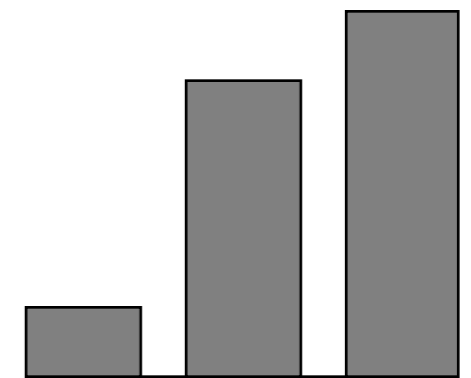
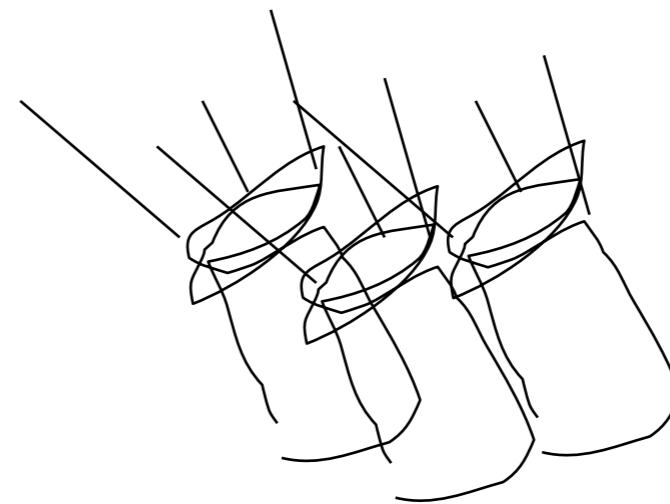
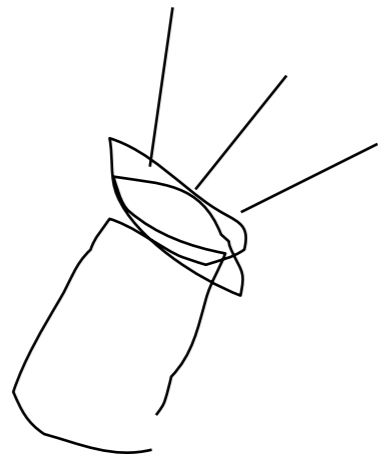
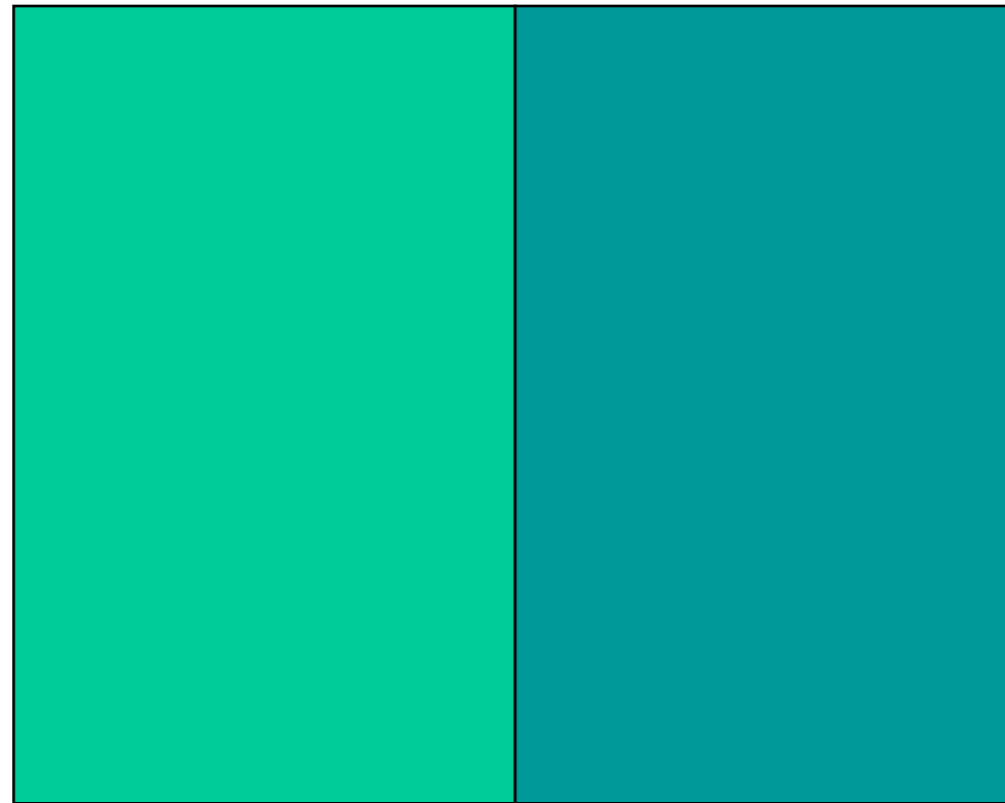
Color matching experiment 1



Color matching experiment 1

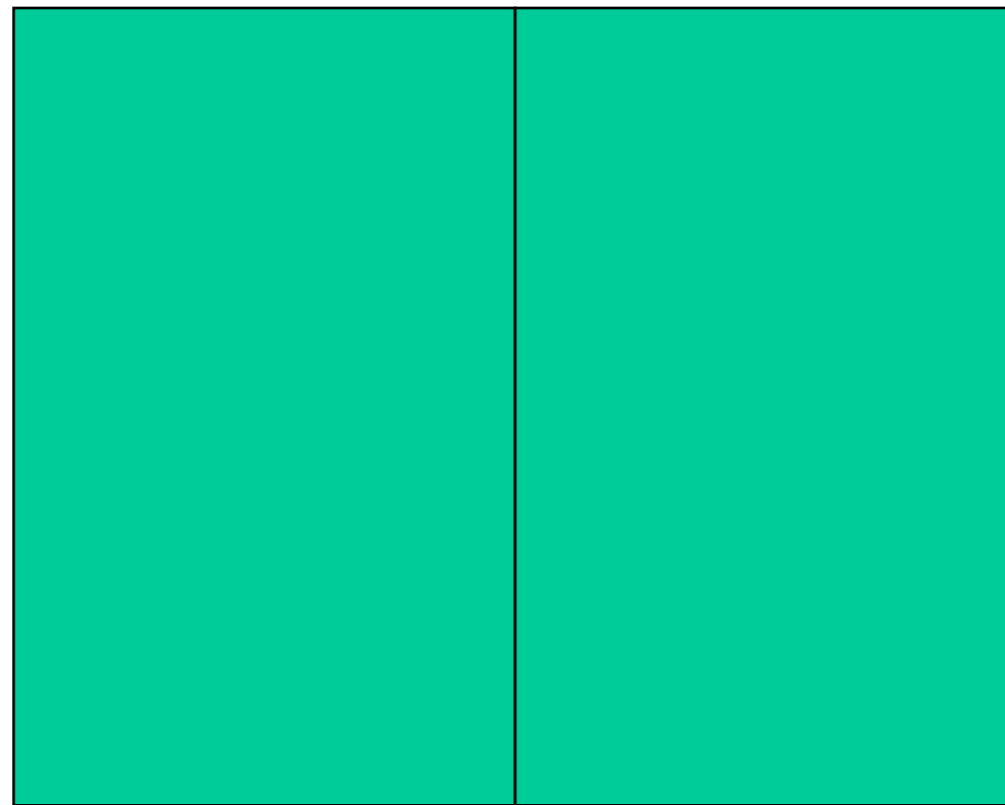


Color matching experiment 1

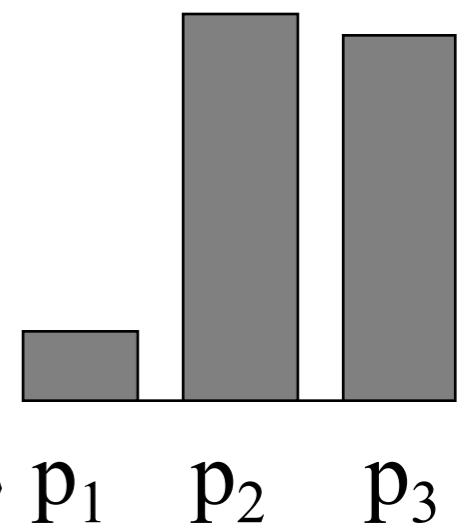
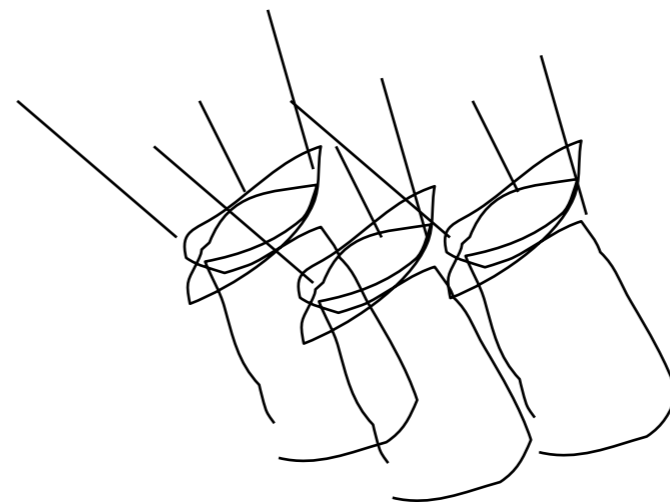
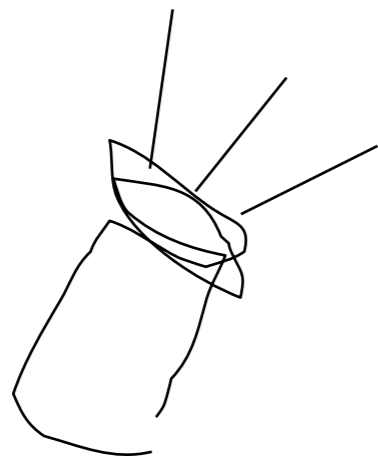


p_1 p_2 p_3

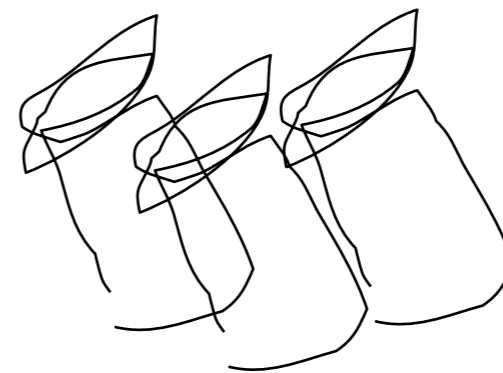
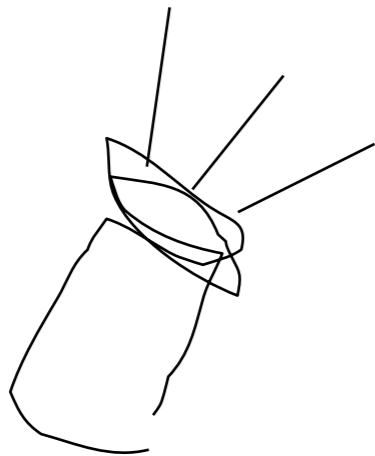
Color matching experiment 1



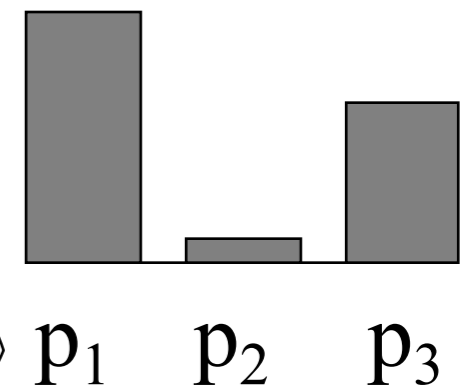
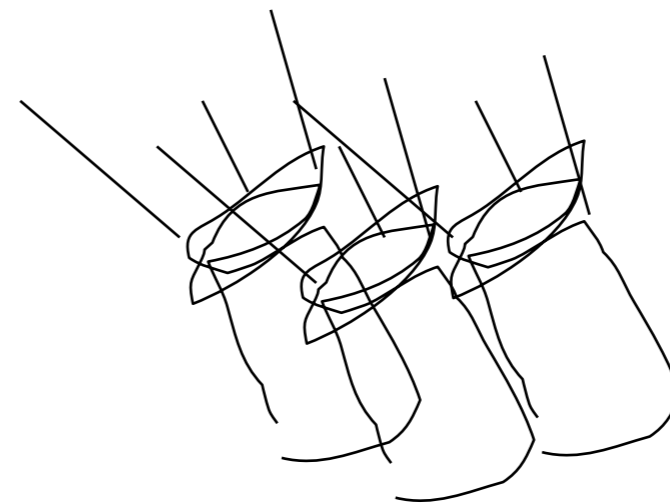
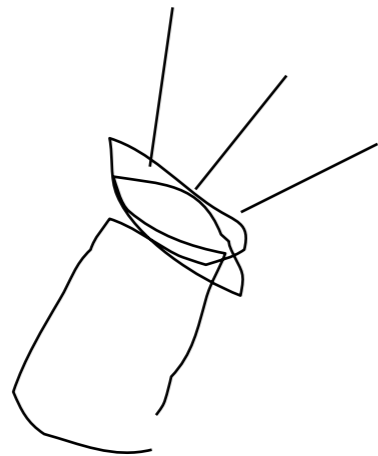
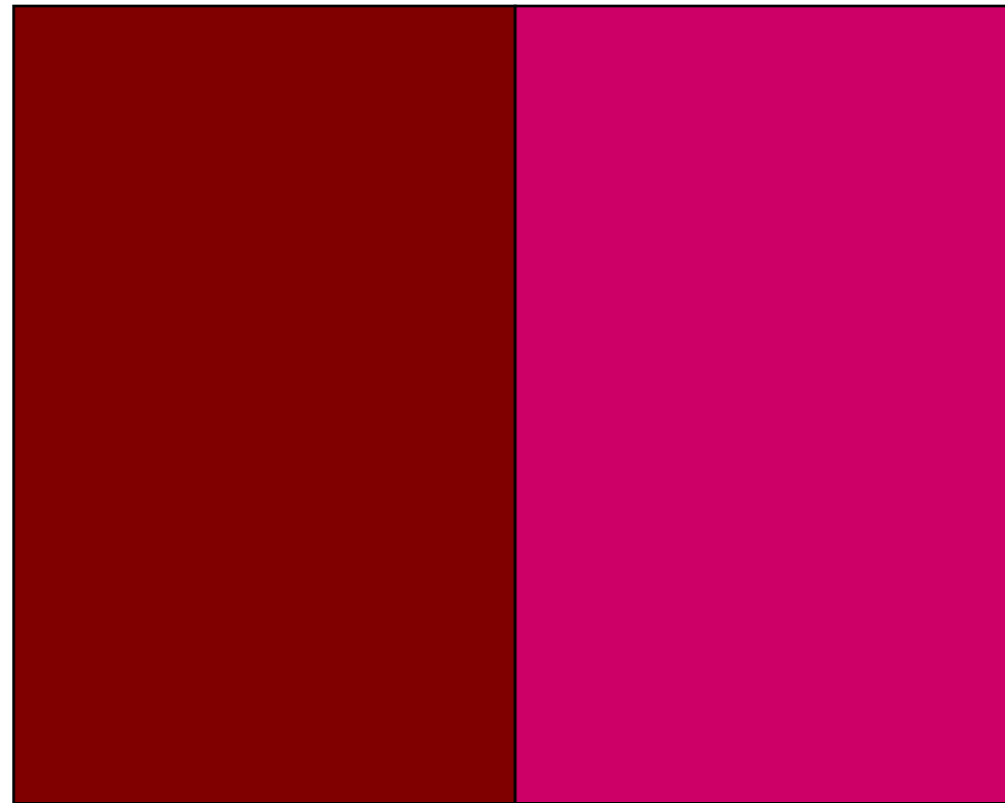
The primary color amounts needed for a match



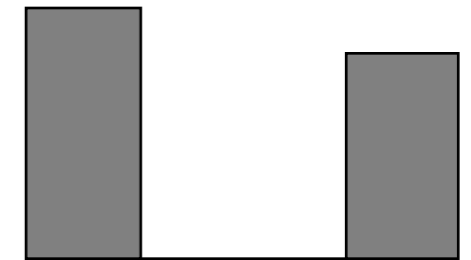
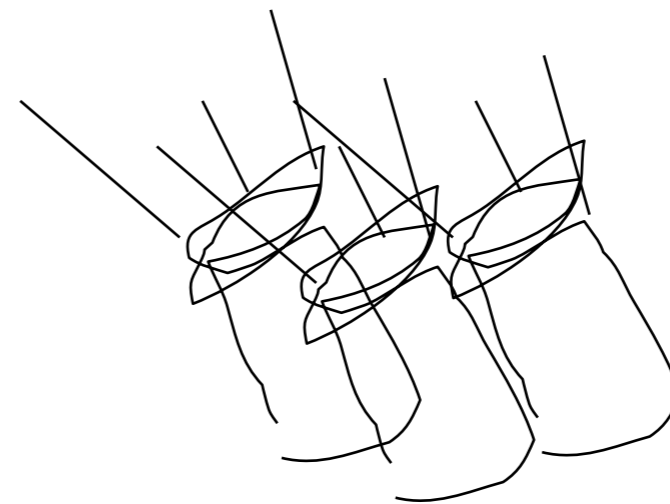
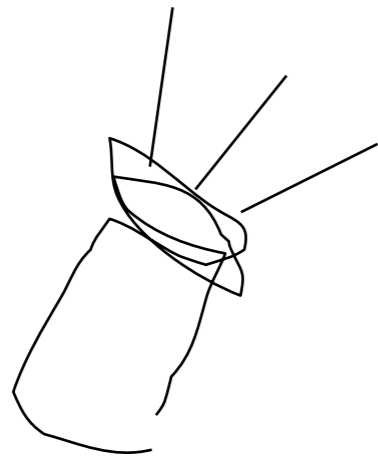
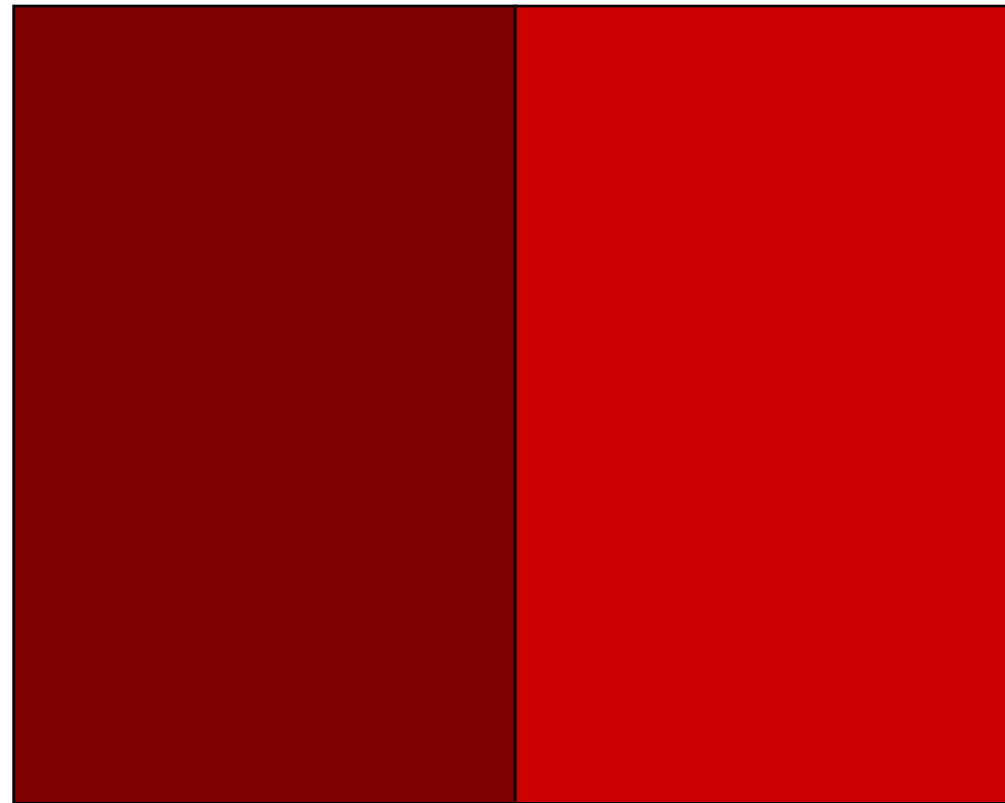
Color matching experiment 2



Color matching experiment 2



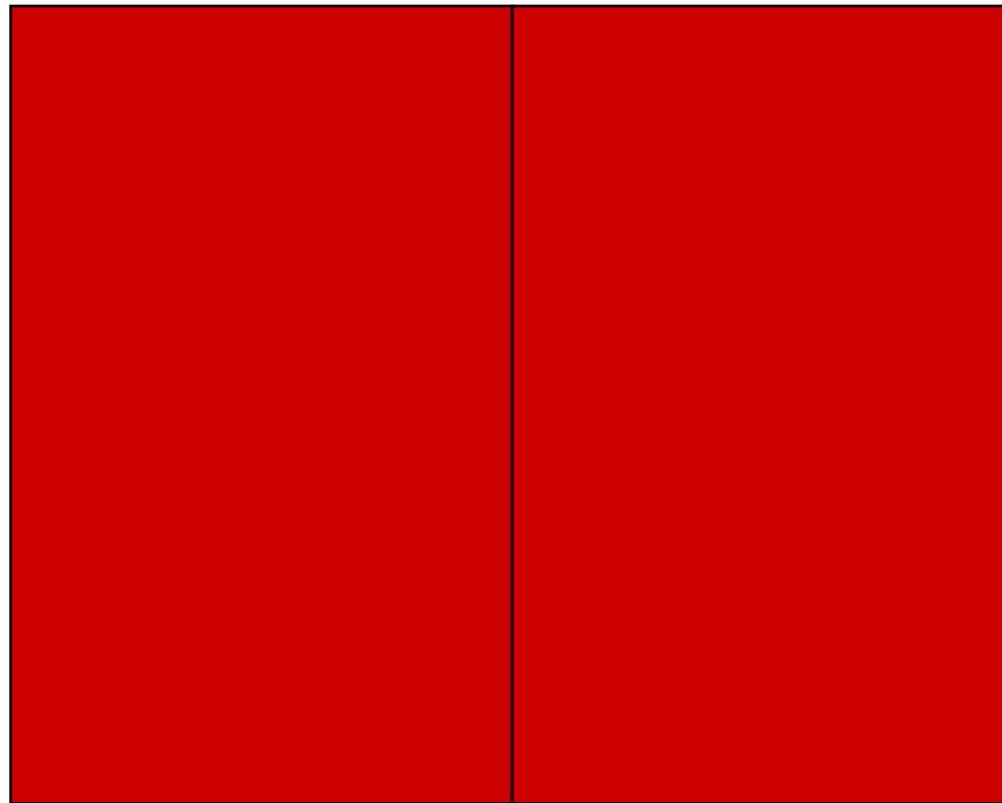
Color matching experiment 2



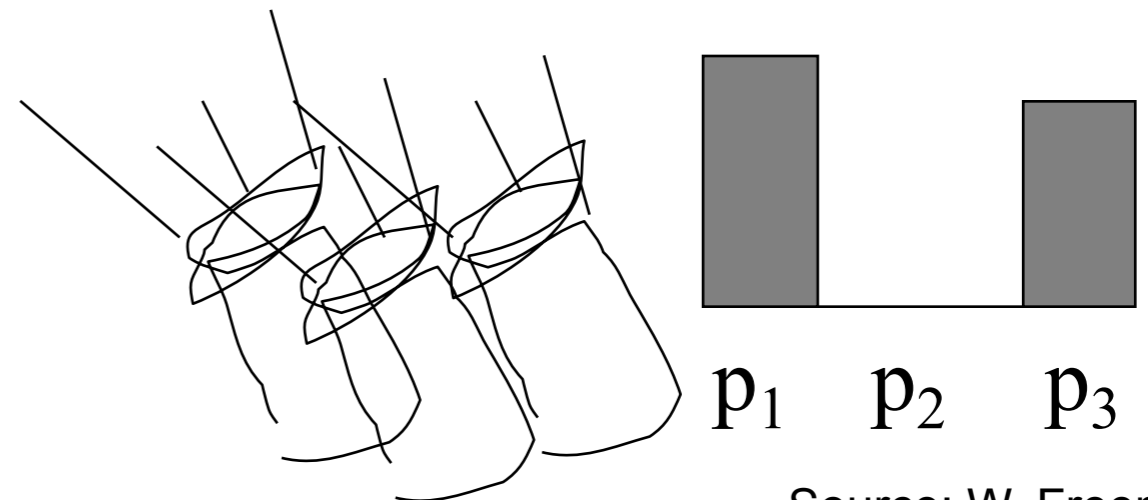
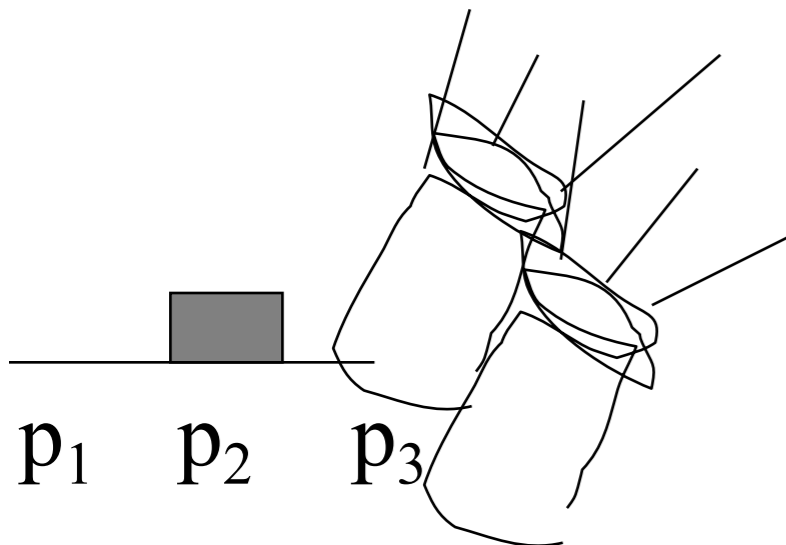
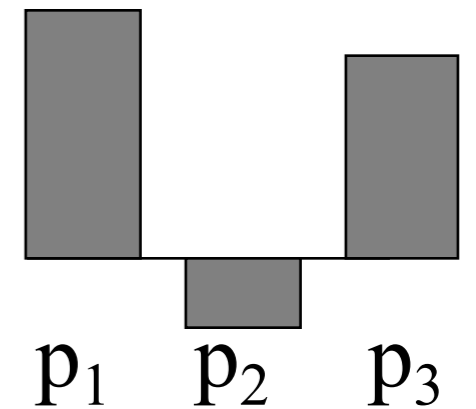
p_1 p_2 p_3

Color matching experiment 2

We say a “negative” amount of p_2 was needed to make the match, because we added it to the test color’s side.



The primary color amounts needed for a match:



Trichromacy

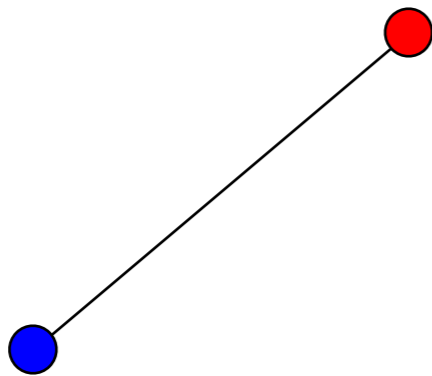
- In color matching experiments, most people can match any given light with three primaries
 - Primaries must be *independent*
- For the same light and same primaries, most people select the same weights
 - Exception: color blindness
- Trichromatic color theory
 - Three numbers seem to be sufficient for encoding color
 - Dates back to 18th century (Thomas Young)

Grassman's Laws (1853)

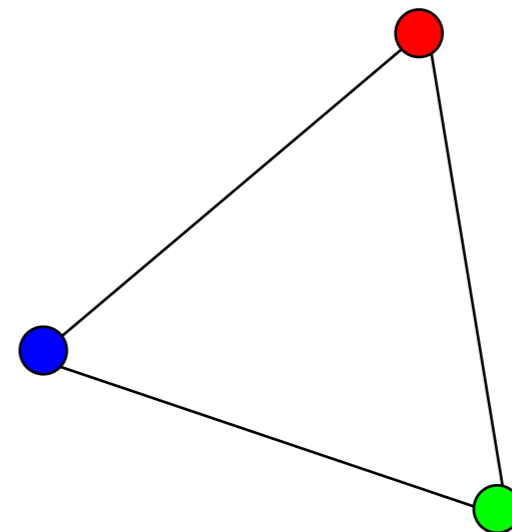
- Color matching appears to be linear
- If two test lights can be matched with the same set of weights, then they match each other:
 - Suppose $A = u_1 P_1 + u_2 P_2 + u_3 P_3$ and $B = u_1 P_1 + u_2 P_2 + u_3 P_3$. Then $A = B$.
- If we mix two test lights, then mixing the matches will match the result:
 - Suppose $A = u_1 P_1 + u_2 P_2 + u_3 P_3$ and $B = v_1 P_1 + v_2 P_2 + v_3 P_3$. Then $A + B = (u_1 + v_1) P_1 + (u_2 + v_2) P_2 + (u_3 + v_3) P_3$.
- If we scale the test light, then the matches get scaled by the same amount:
 - Suppose $A = u_1 P_1 + u_2 P_2 + u_3 P_3$.
Then $kA = (ku_1) P_1 + (ku_2) P_2 + (ku_3) P_3$.

Linear color spaces

- Defined by a choice of three *primaries*
- The coordinates of a color are given by the weights of the primaries used to match it



mixing two lights produces colors that lie along a straight line in color space

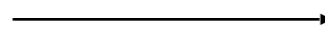
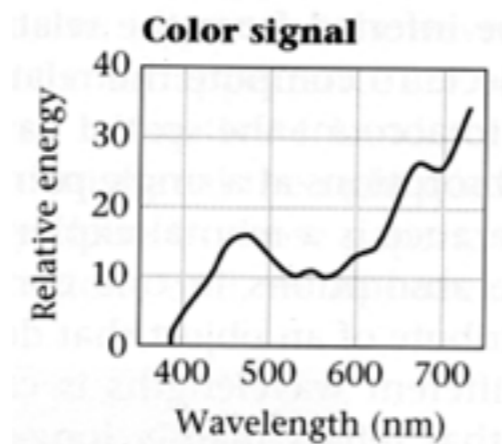
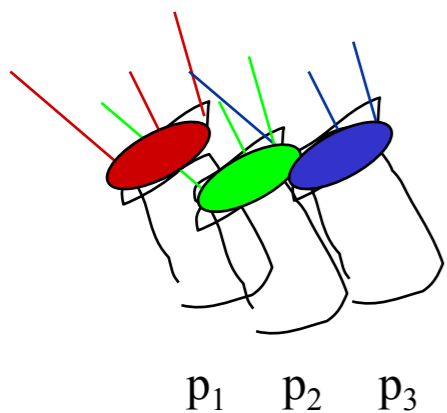


mixing three lights produces colors that lie within the triangle they define in color space

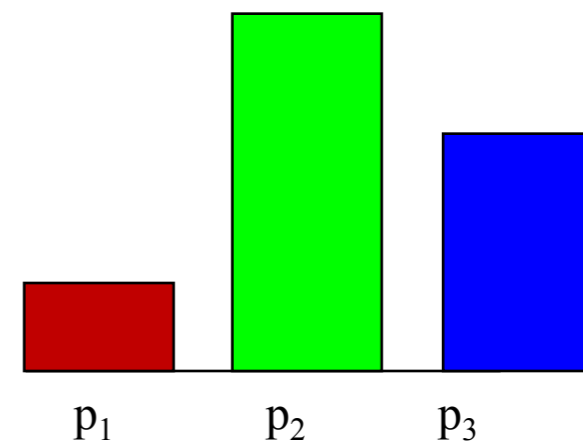
Linear color spaces

- How to compute the weights of the primaries to match any spectral signal?

Given: a choice of three primaries and a target color signal



Find: weights of the primaries needed to match the color signal






Linear color spaces

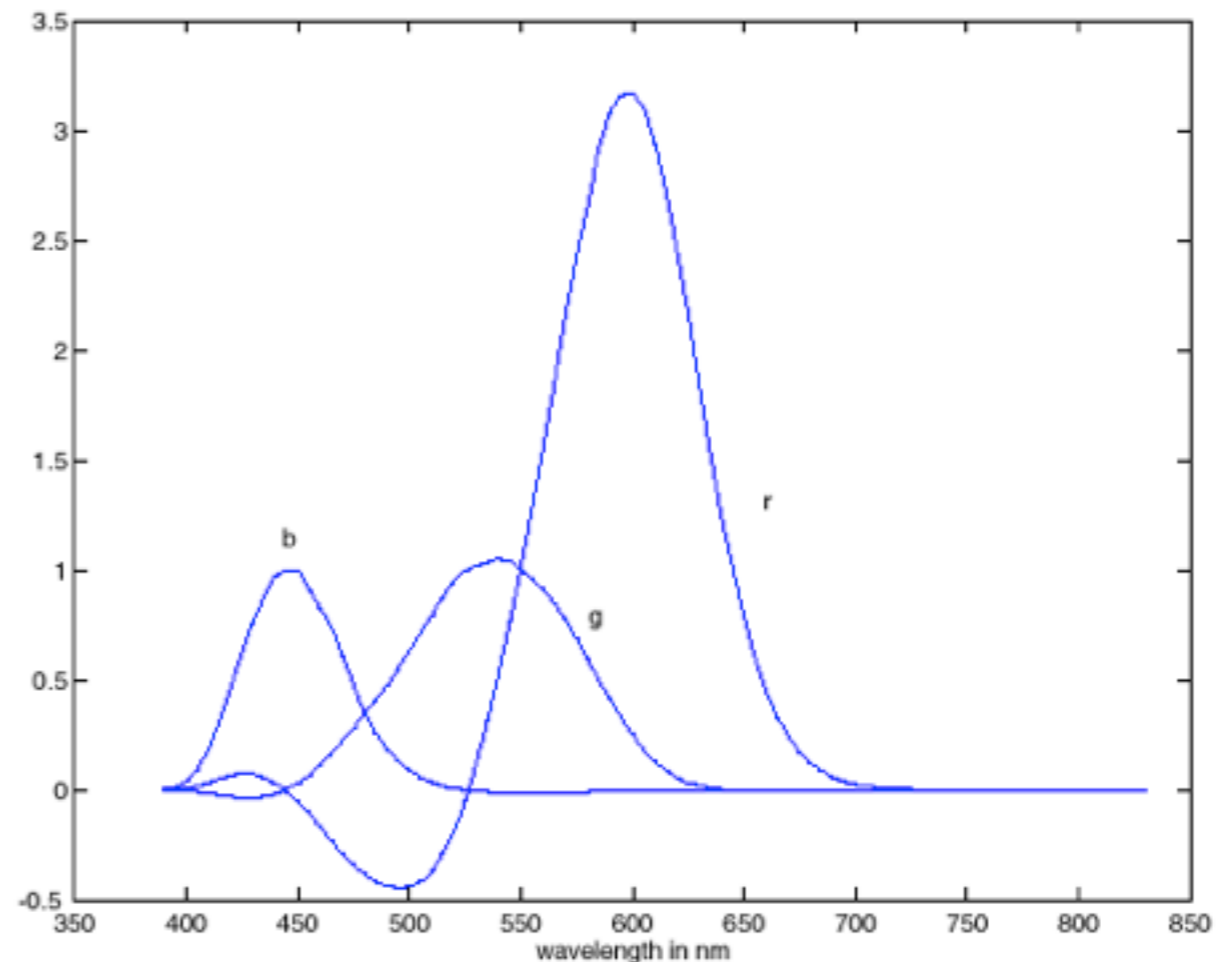
- In addition to primaries, need to specify **matching functions**: the amount of each primary needed to match a monochromatic light source at each wavelength

RGB primaries



-  $p_1 = 645.2 \text{ nm}$
-  $p_2 = 525.3 \text{ nm}$
-  $p_3 = 444.4 \text{ nm}$

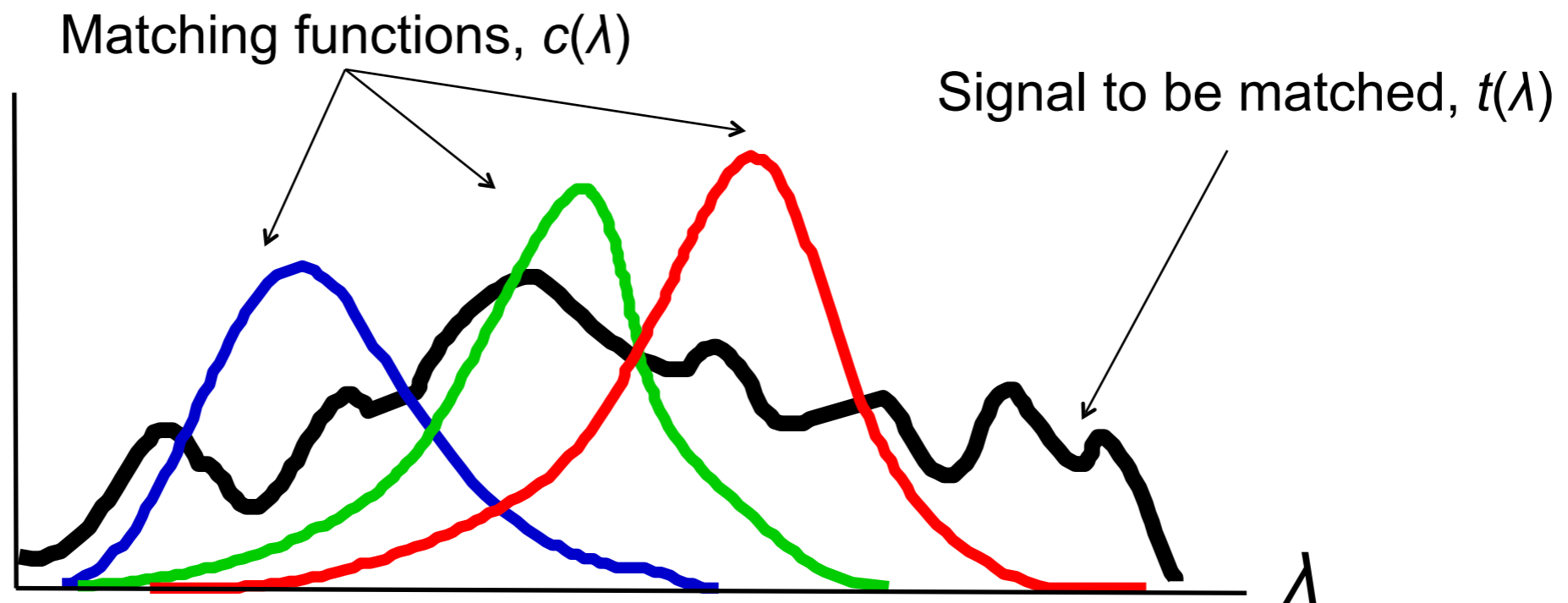
RGB matching functions



Linear color spaces

- How to compute the weights of the primaries to match any spectral signal?
- Let $c(\lambda)$ be one of the matching functions, and let $t(\lambda)$ be the spectrum of the signal. Then the weight of the corresponding primary needed to match t is

$$w = \int_{\lambda} c(\lambda)t(\lambda)d\lambda$$



RGB space

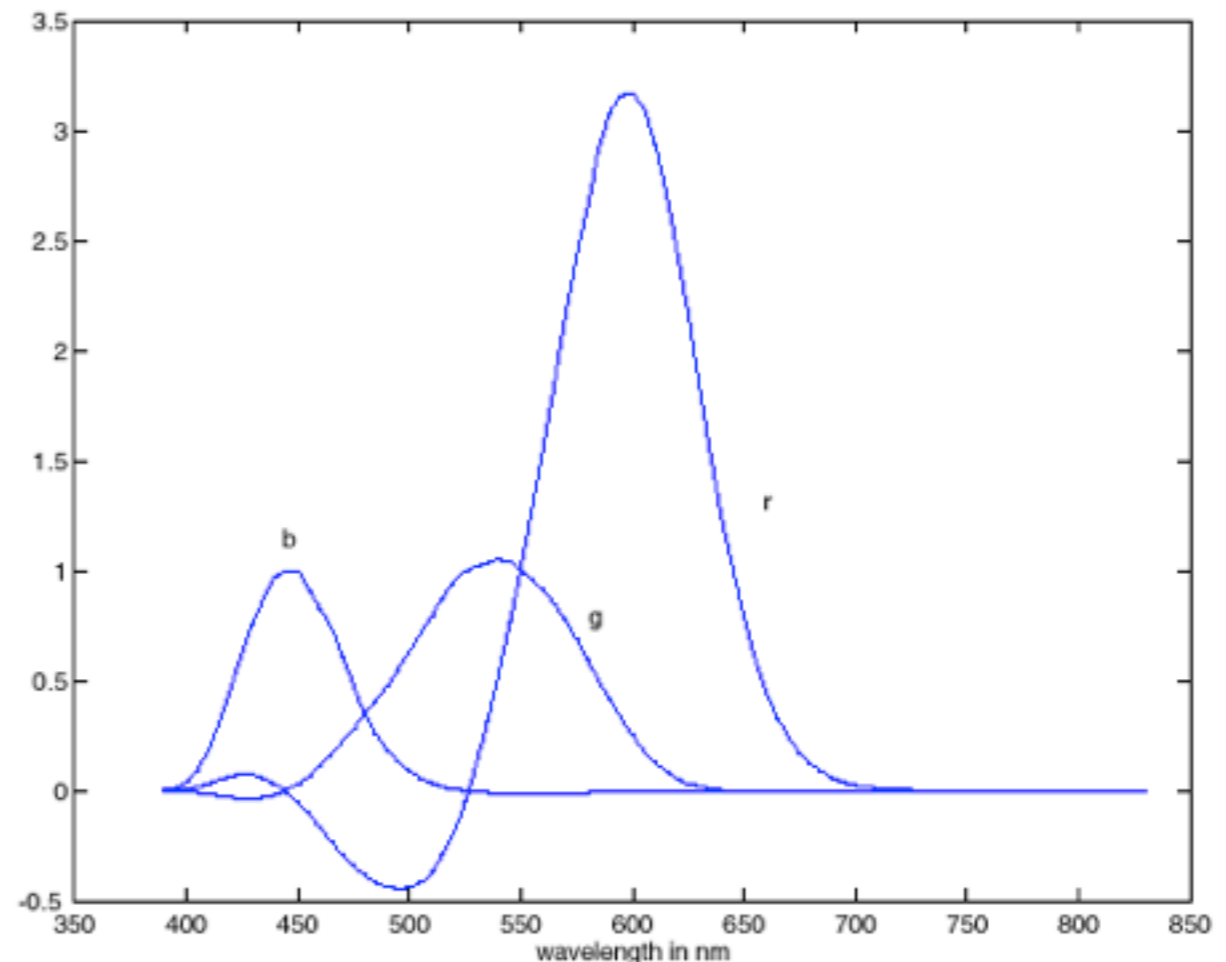
- Primaries are monochromatic lights (for monitors, they correspond to the three types of phosphors)
- *Subtractive matching* required for some wavelengths

RGB primaries



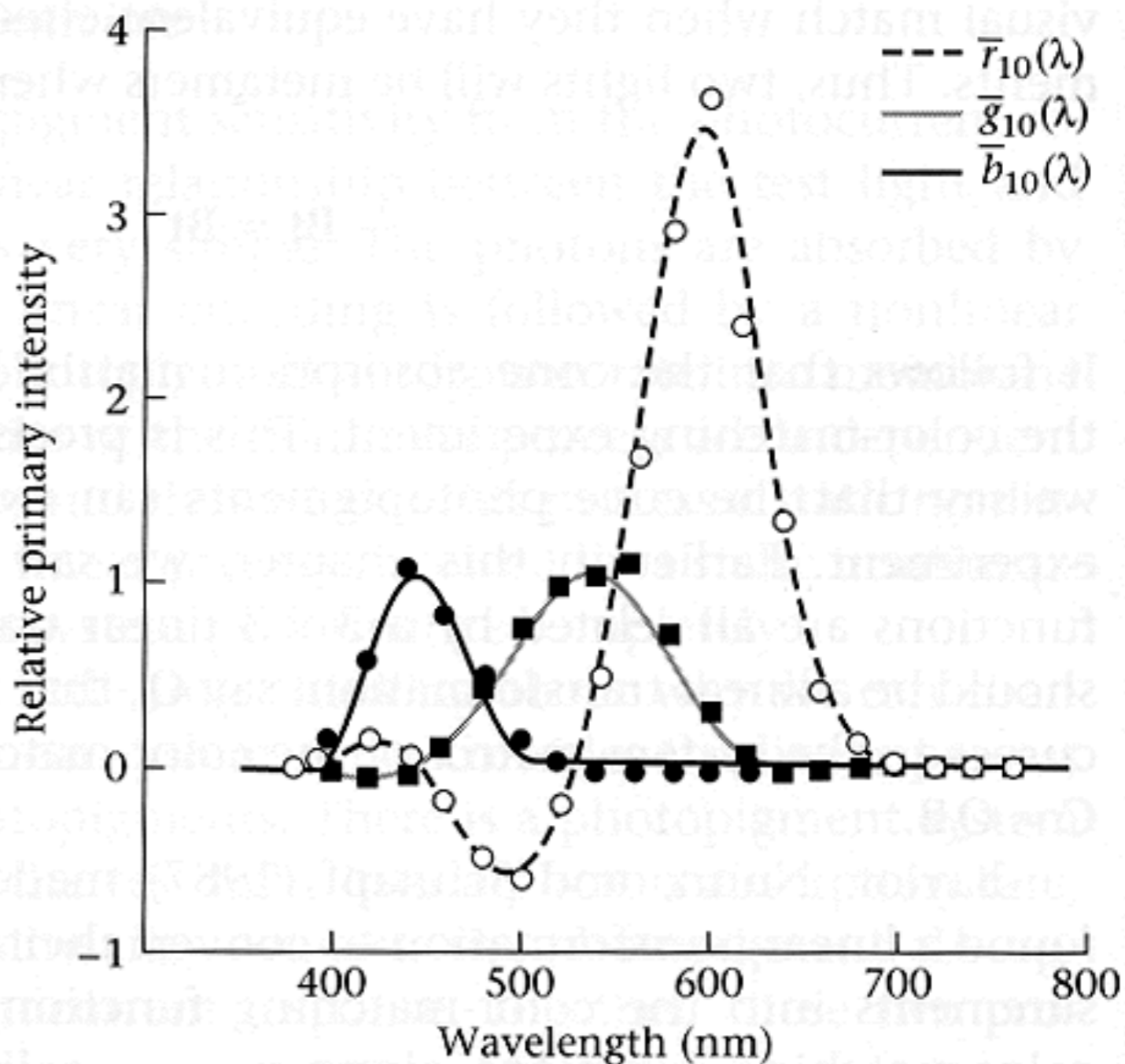
- $p_1 = 645.2 \text{ nm}$
- $p_2 = 525.3 \text{ nm}$
- $p_3 = 444.4 \text{ nm}$

RGB matching functions



Comparison of RGB matching functions with best linear transformation of cone responses

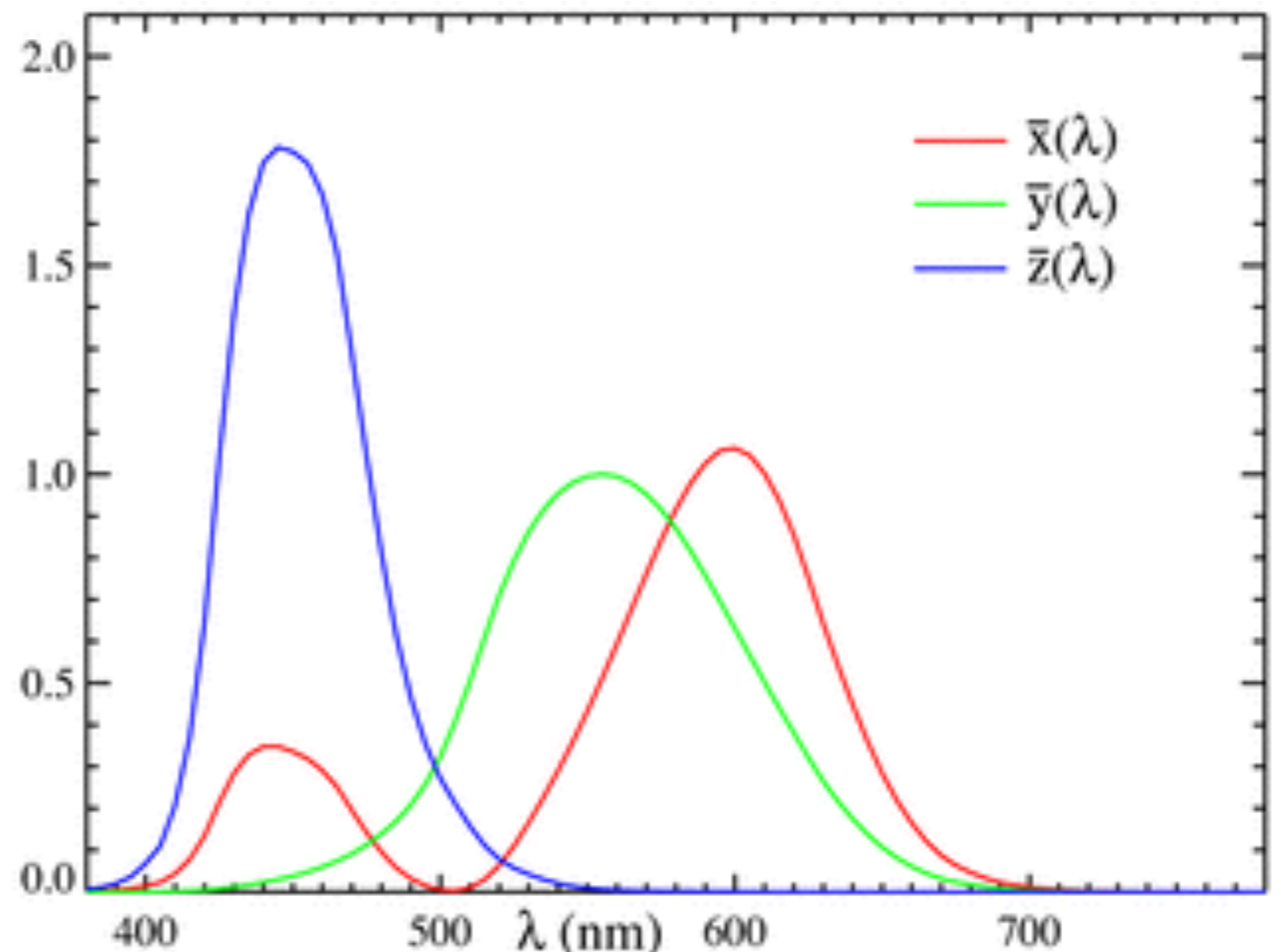
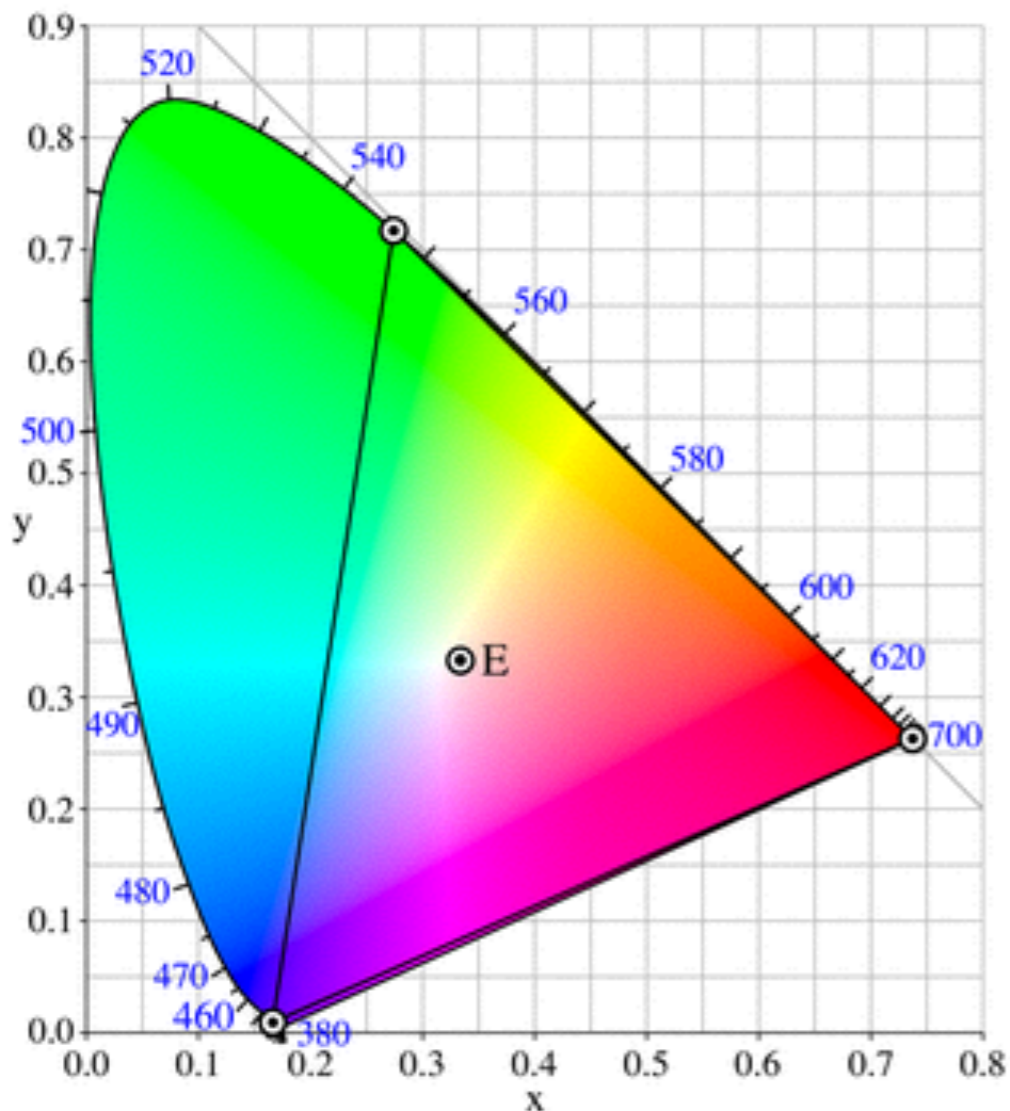
4.20 COMPARISON OF CONE PHOTOCURRENT RESPONSES AND THE COLOR-MATCHING FUNCTIONS. The cone photocurrent spectral responsivities are within a linear transformation of the color-matching functions, after a correction has been made for the optics and inert pigments in the eye. The smooth curves show the Stiles and Burch (1959) color-matching functions. The symbols show the matches predicted from the photocurrents of the three types of macaque cones. The predictions included a correction for absorption by the lens and other inert pigments in the eye. Source: Baylor, 1987.



Linear color spaces: CIE XYZ

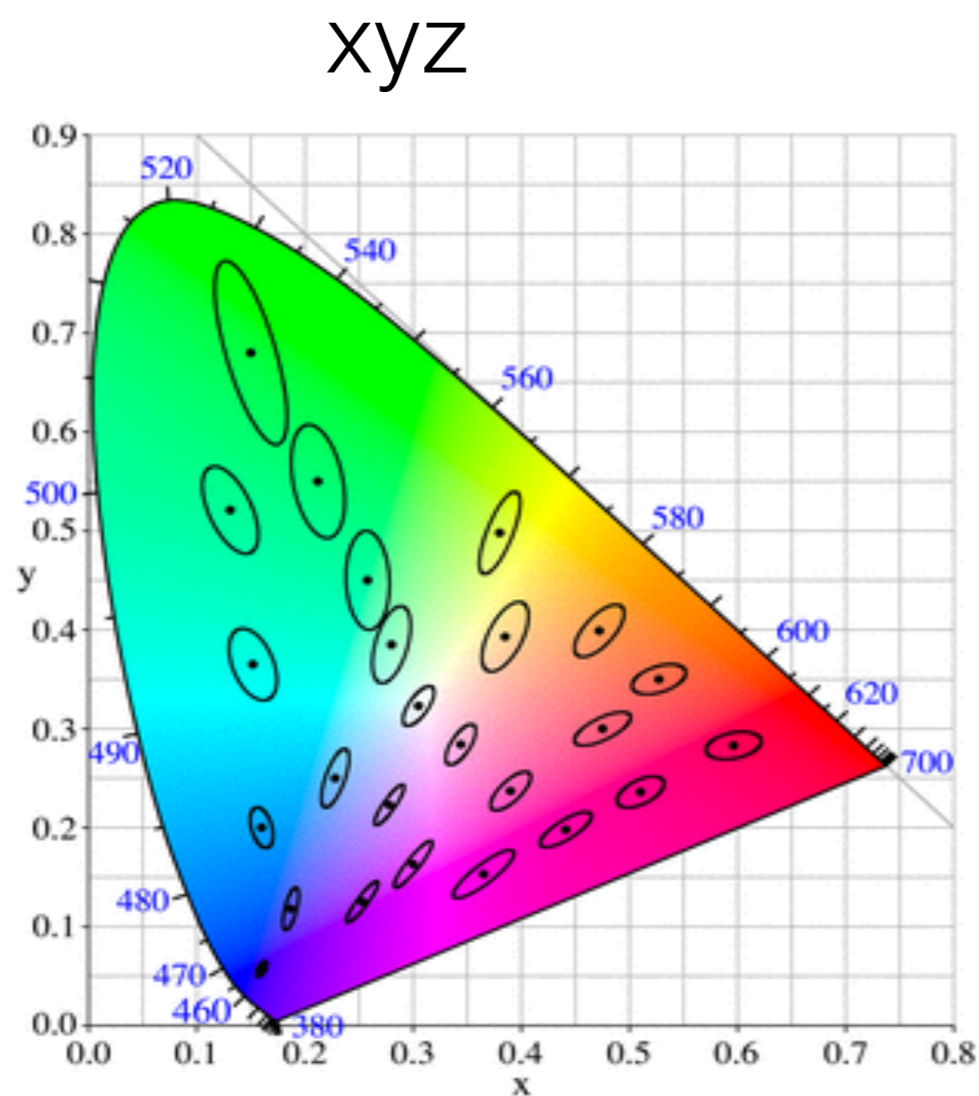
- Primaries are “*imaginary*”, but matching functions are positive everywhere
- Y parameter corresponds to brightness or *luminance* of a color
- Z corresponds to blue stimulation

Matching functions

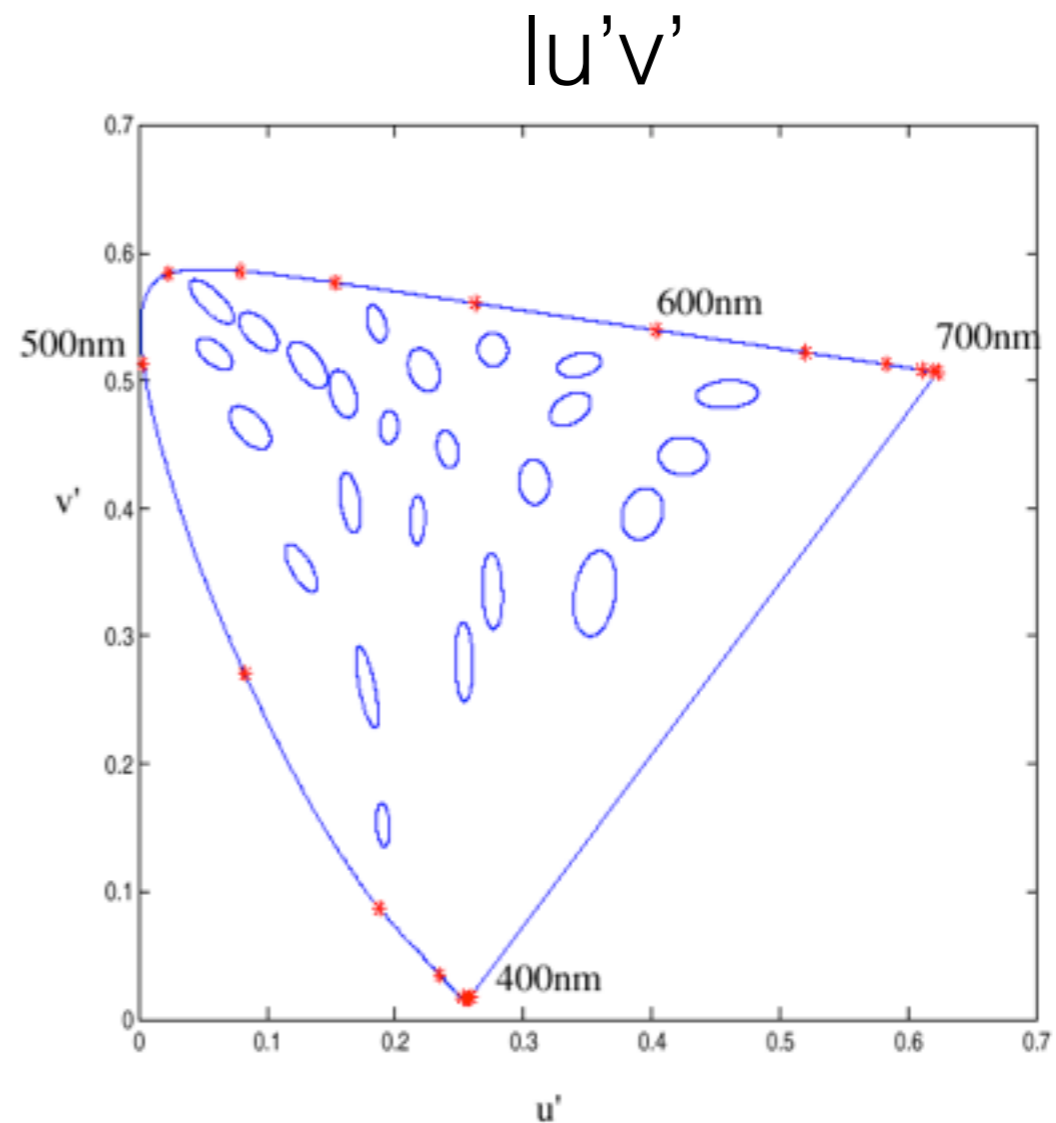


Uniform color spaces

- Unfortunately, differences in x,y coordinates do not reflect perceptual color differences
- CIE $u'v'$ is a transform of x,y to make the ellipses more uniform

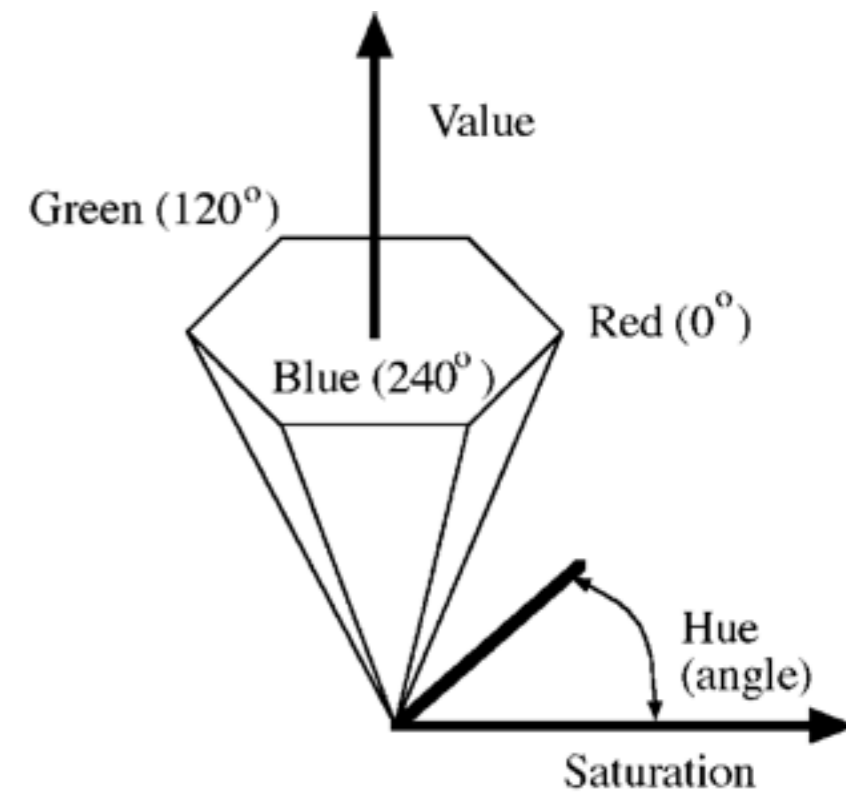
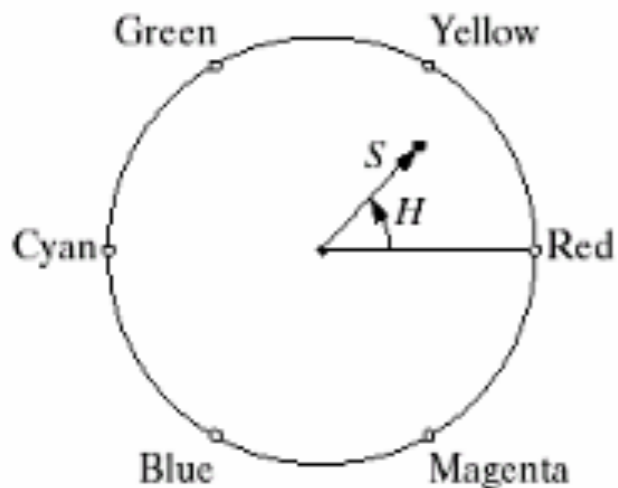
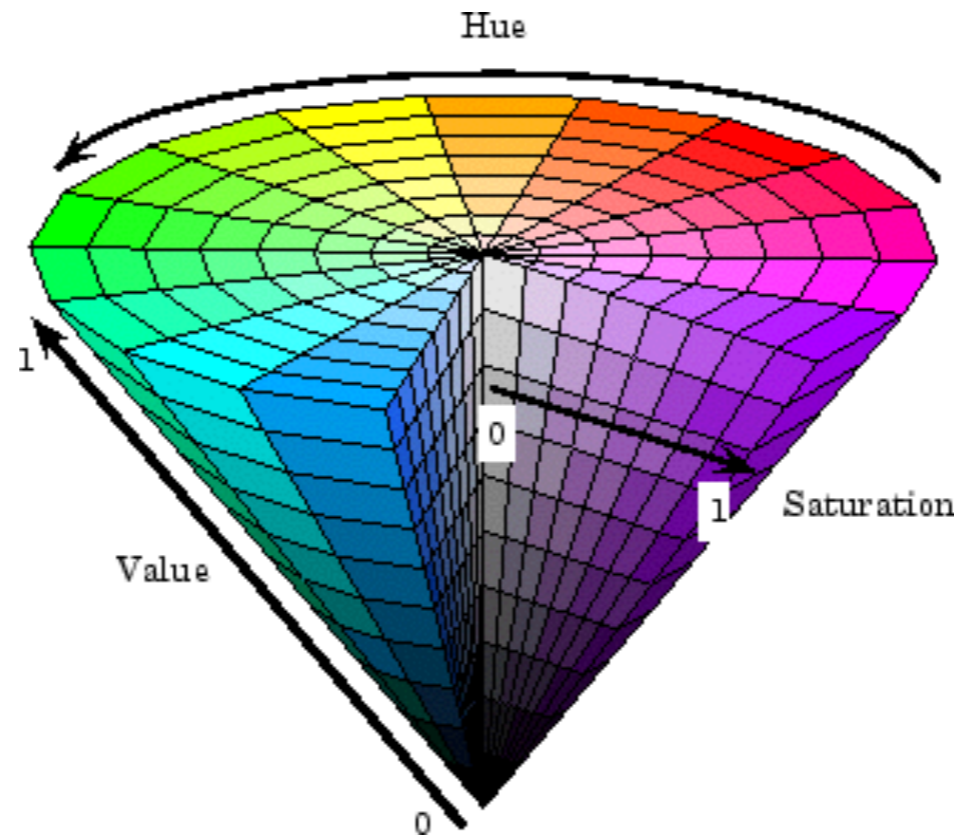
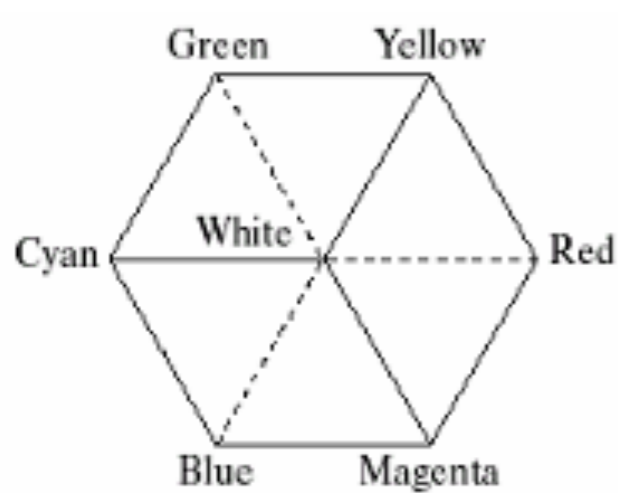


McAdam ellipses: Just noticeable differences in color

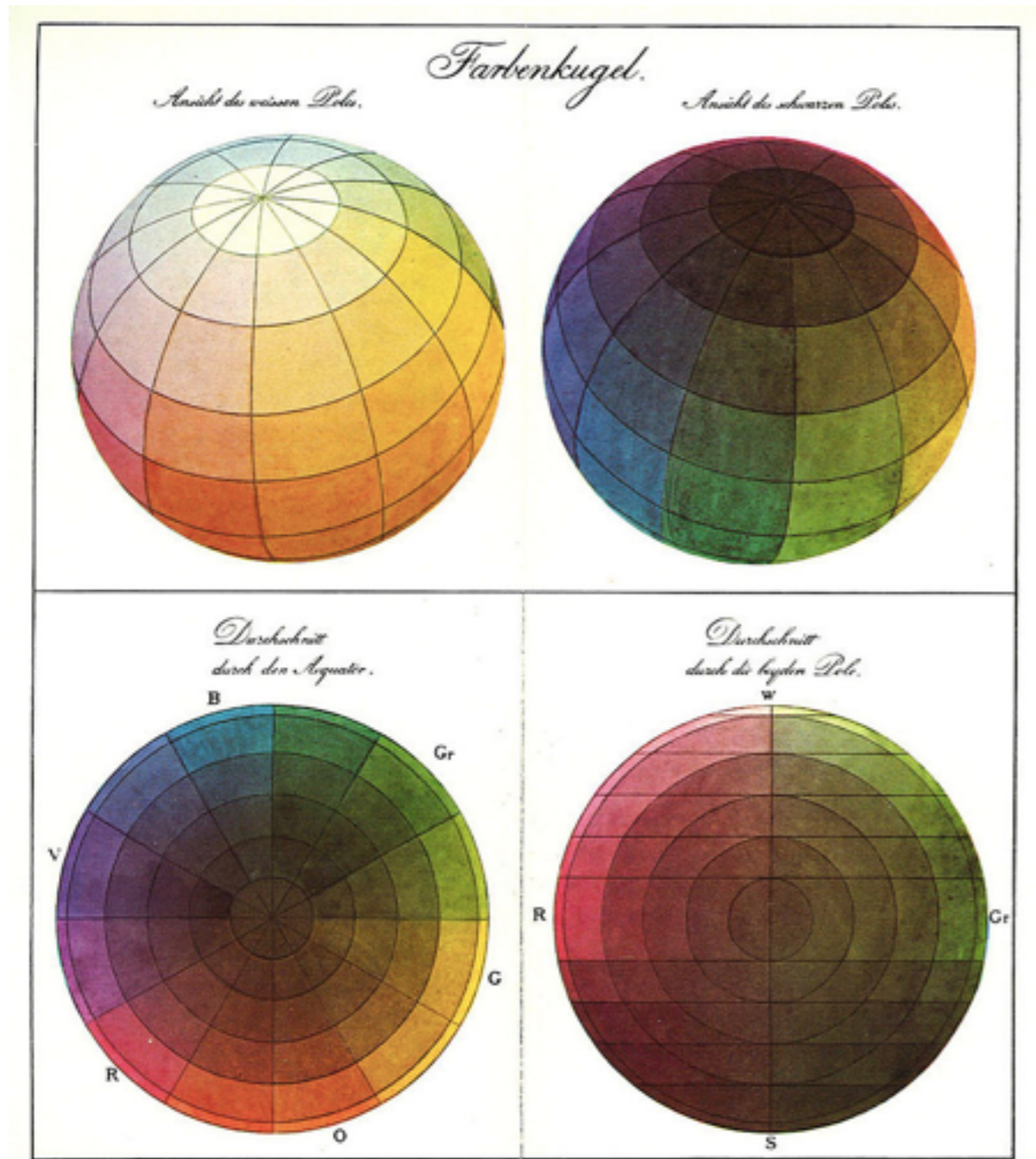


Nonlinear color spaces: HSV

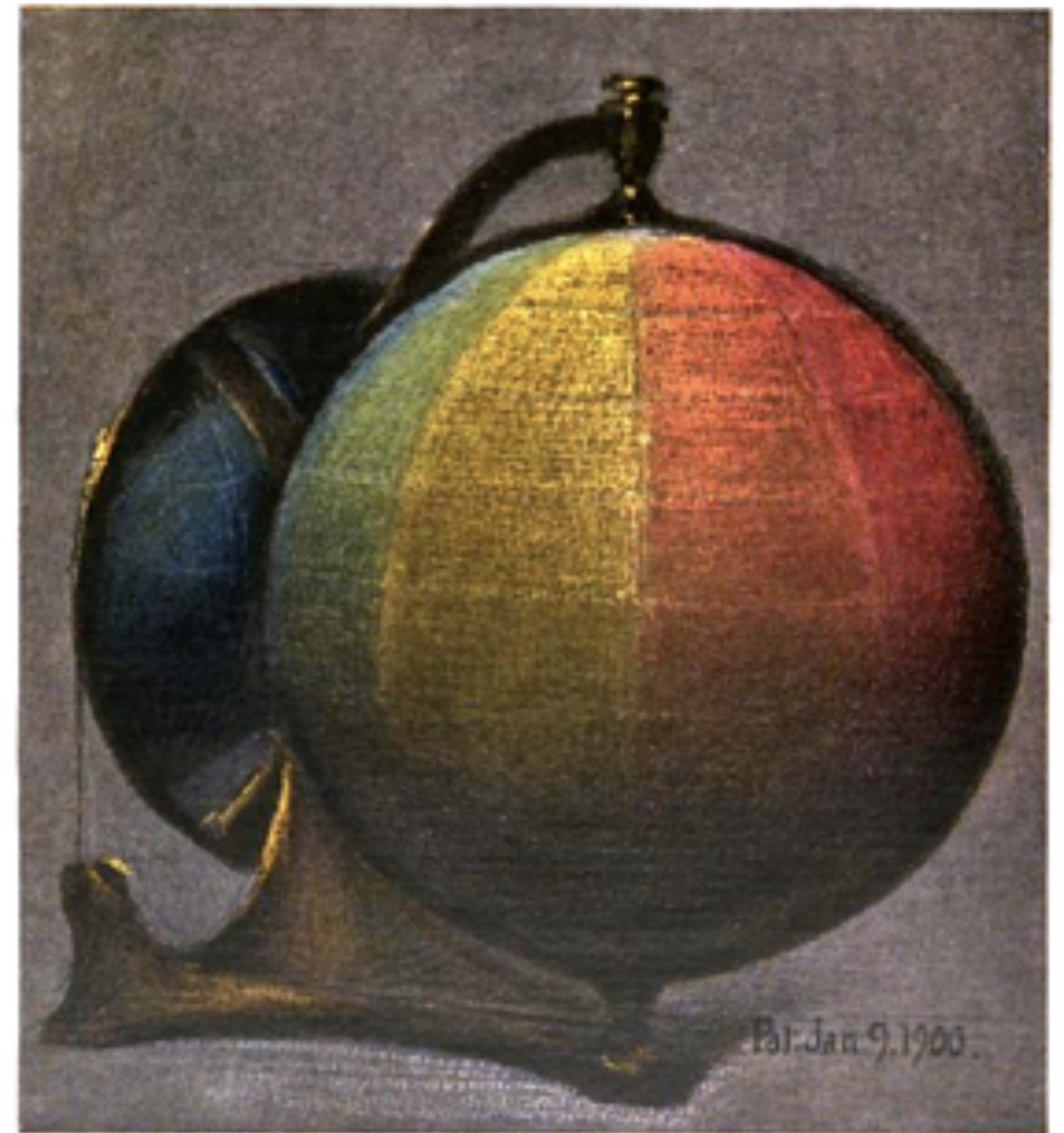
- Perceptually meaningful dimensions: Hue, Saturation, Value (Intensity)
- RGB cube on its vertex



Some early attempts in color spaces



Philipp Otto Runge's Farbenkugel (color sphere), 1810



A BALANCED COLOR SPHERE

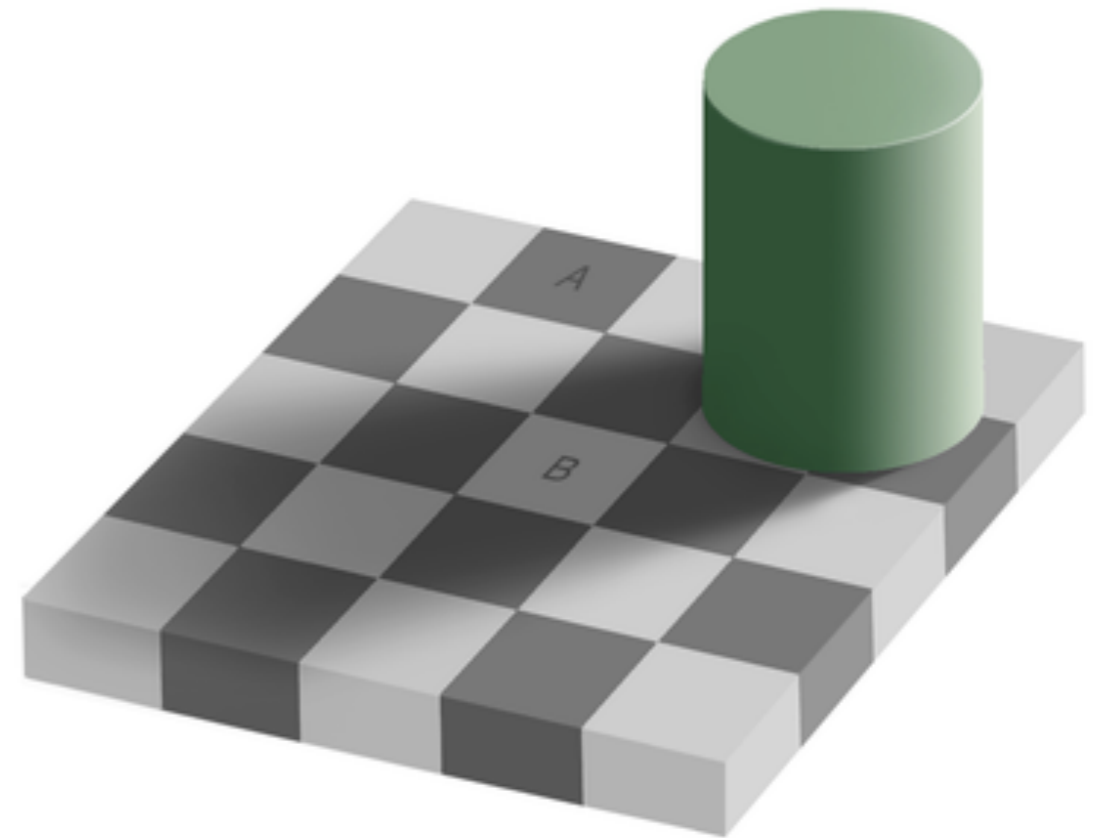
Munsell's balanced color sphere, 1900, from A Color Notation, 1905

Color constancy

- The ability of the human visual system to perceive color relatively constant despite changes in illumination conditions

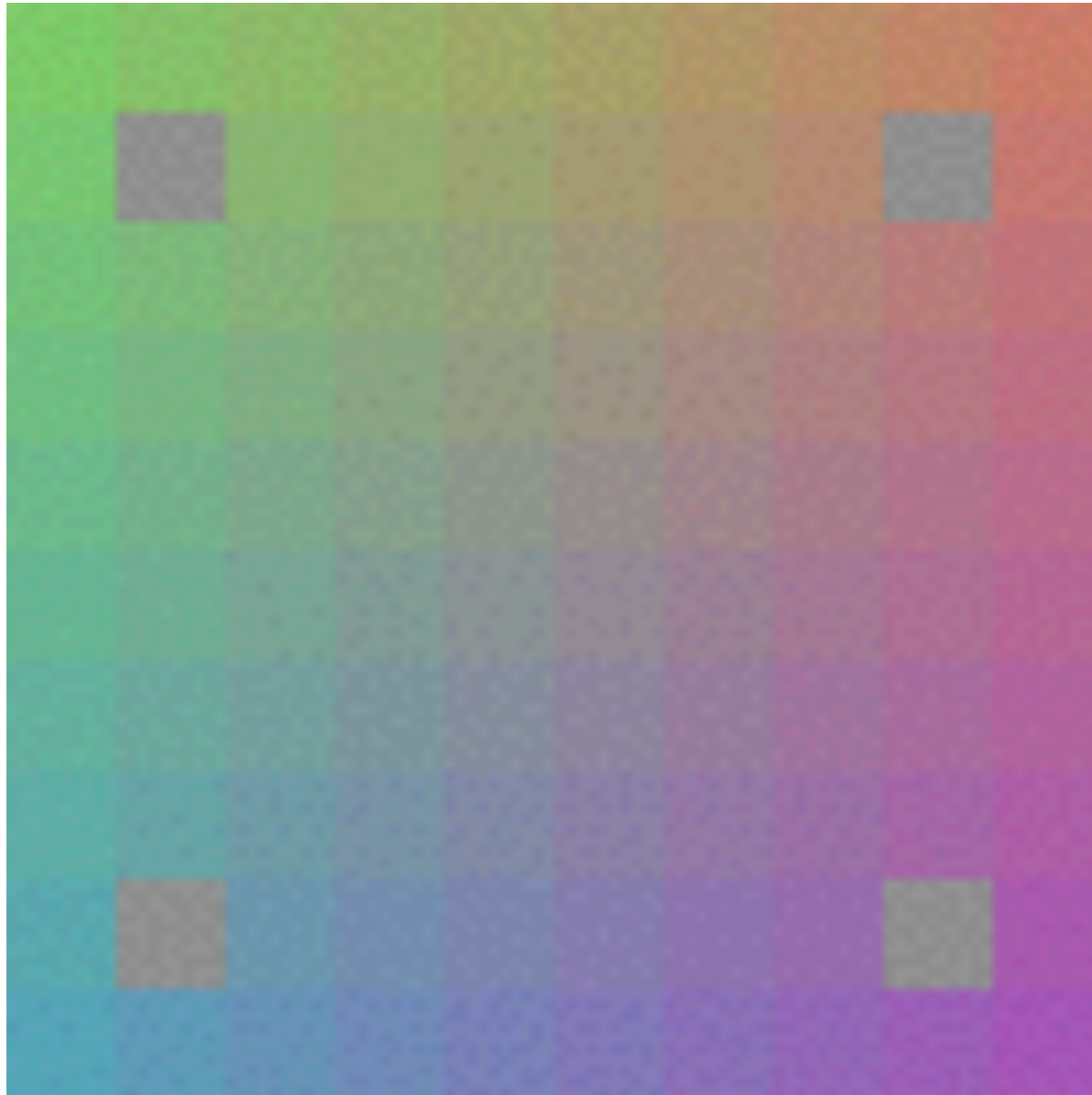


We perceive the same color both in shadow and sunlight



Color constancy causes A and B to look different although the pixel values are the same

Simultaneous contrast/Mach bands



Chromatic adaptation

- The visual system changes its sensitivity depending on the luminances prevailing in the visual field
 - The exact mechanism is poorly understood
- Adapting to different brightness levels
 - Changing the size of the iris opening (i.e., the aperture) changes the amount of light that can enter the eye
 - Think of walking into a building from full sunshine
- Adapting to different color temperature
 - The receptive cells on the retina change their sensitivity
 - For example: if there is an increased amount of red light, the cells receptive to red decrease their sensitivity until the scene looks white again
 - We actually adapt better in brighter scenes: This is why candlelit scenes still look yellow

White balance

- When looking at a picture on screen or print, our eyes are adapted to the illuminant of the room, not to that of the scene in the picture
- When the white balance is not correct, the picture will have an unnatural color “cast”

incorrect white balance










correct white balance



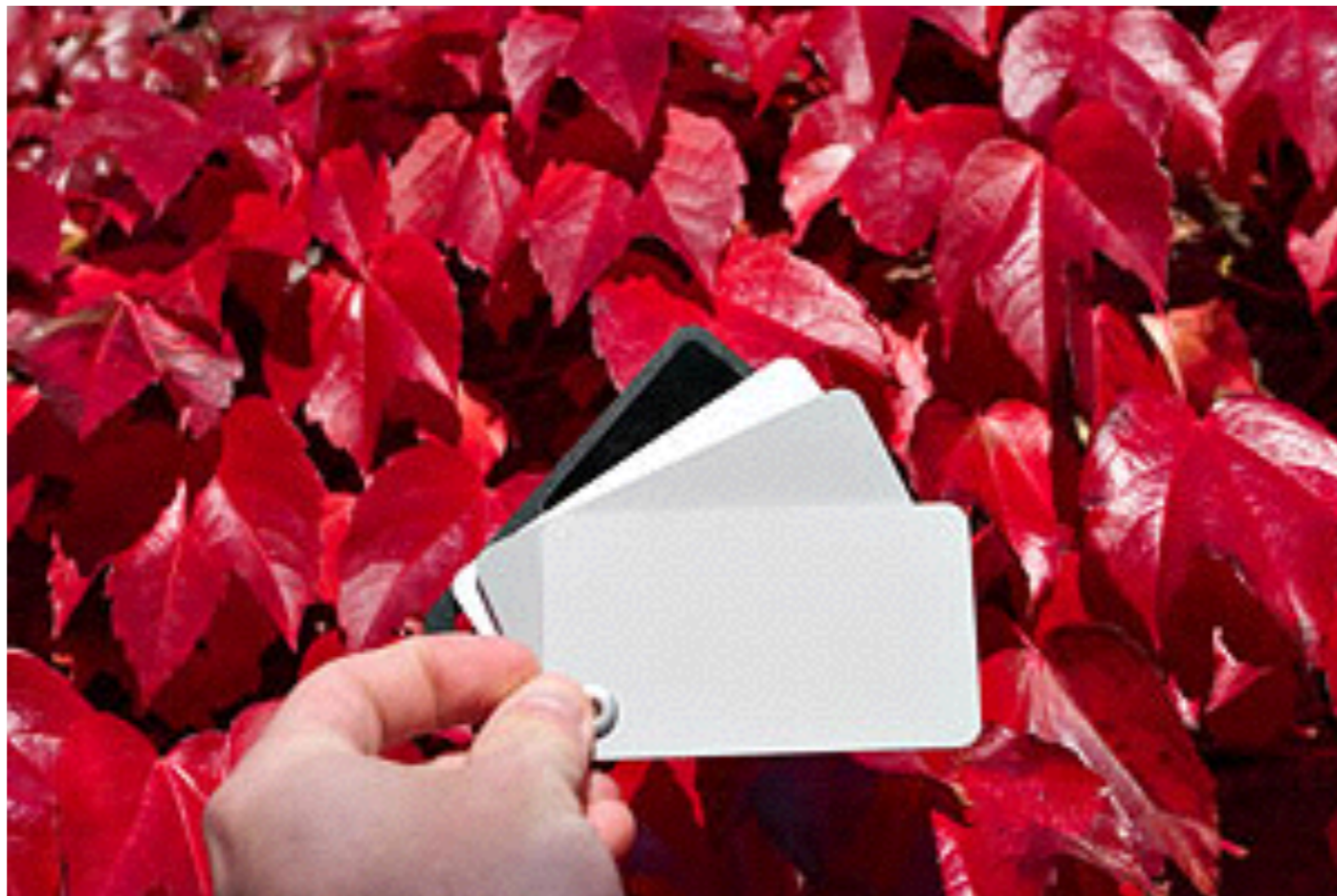
White balance

- **Film cameras:**
 - Different types of film or different filters for different illumination conditions
- **Digital cameras:**
 - Automatic white balance
 - White balance settings corresponding to several common illuminants
 - Custom white balance using a reference object

	AWB	Auto White Balance
		Custom
	K	Kelvin
Increasing Color Temperature ↓		Tungsten
		Fluorescent
		Daylight
		Flash
		Cloudy
		Shade

White balance

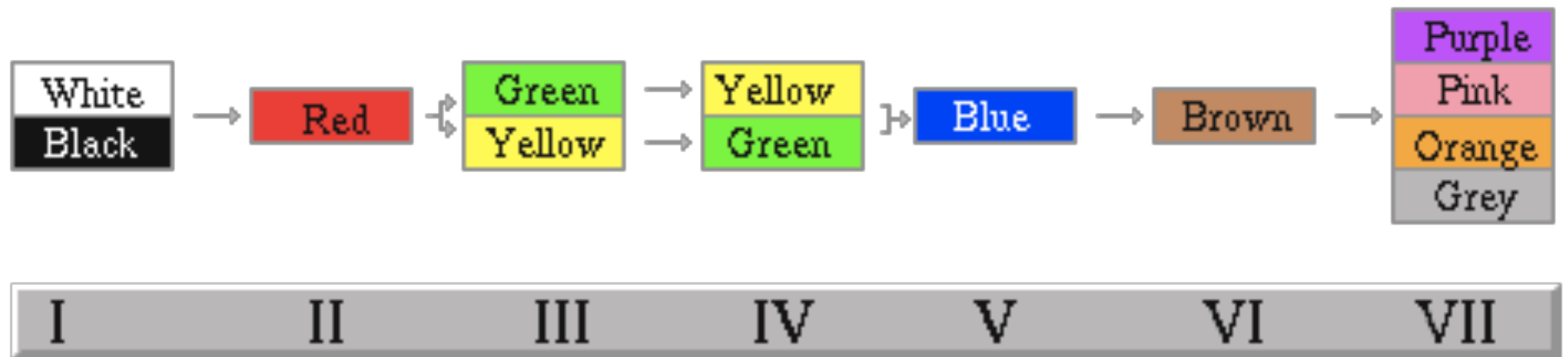
- Von Kries adaptation
 - Multiply each channel by a gain factor
- **Best way:** gray card
 - Take a picture of a neutral object (white or gray)
 - Deduce the weight of each channel
 - If the object is recoded as r_w , g_w , b_w use weights $1/r_w$, $1/g_w$, $1/b_w$



White balance

- Without gray cards: we need to “guess” which pixels correspond to white objects
- Gray world assumption
 - The image average r_{ave} , g_{ave} , b_{ave} is gray
 - Use weights $1/r_{ave}$, $1/g_{ave}$, $1/b_{ave}$
- Brightest pixel assumption
 - Highlights usually have the color of the light source
 - Use weights inversely proportional to the values of the brightest pixels
- Gamut mapping
 - Gamut: convex hull of all pixel colors in an image
 - Find the transformation that matches the gamut of the image to the gamut of a “typical” image under white light
- Use image statistics, learning techniques

Color and language



Evolution of color terms across ~20 diverse languages

B. Berlin and P. Kay, Basic Color Terms: Their Universality and Evolution (1969)

Further readings and thoughts ...

- Color matching applet
 - <http://graphics.stanford.edu/courses/cs178/applets/colormatching.html>
- B. Berlin and P. Kay, Basic Color Terms: Their Universality and Evolution (1969)
 - It is a book. The library has some copies.
- D.A. Forsyth, A novel algorithm for color constancy
 - Gamut based approach
 - <http://luthuli.cs.uiuc.edu/~daf/papers/colorconst.pdf>