



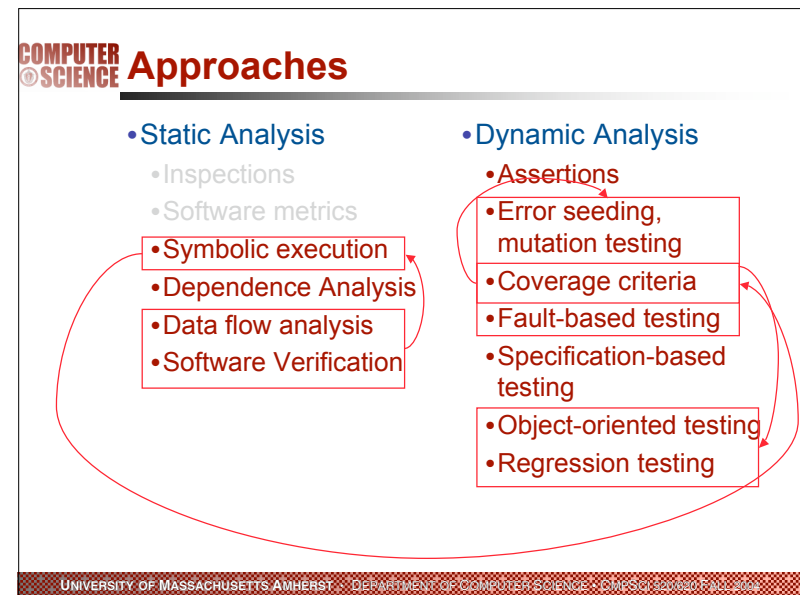
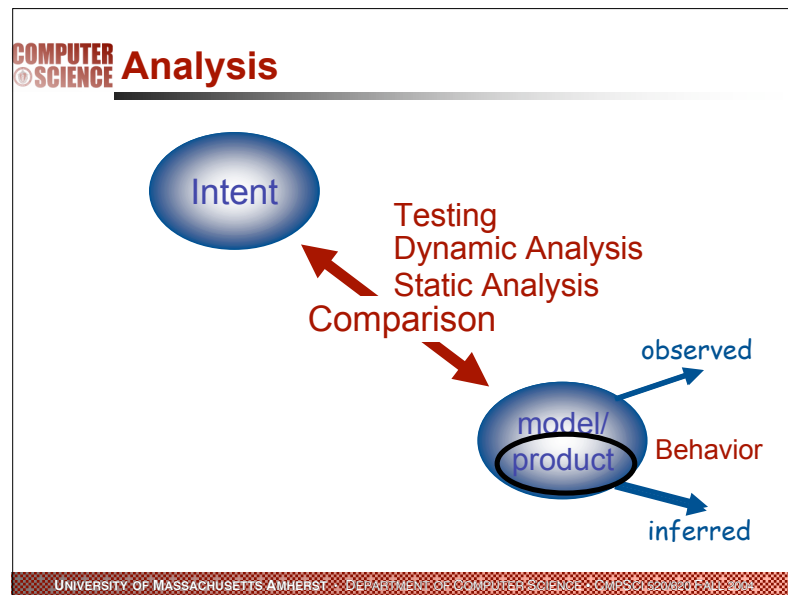
Announcements

- Revised Project 2 (minor) and new Project 3 posted
 - Note: each group (on-campus) needs to arrange a design review during the period 11/29-12/7
 - **No class on 12/6** (can be used for design review)
 - Due Date for Project 2 extended to 12/8
- As alternatives to Rational Rose, I have obtained licenses for Eclipse & Visual Paradigm; licenses are (will be available) on the website.
- I will have comments/grades on Project 1 on 11/29



22-Analysis Overview

- Readings:
 - GJM03 Chapter 6
 - Ost76 Osterweil, Leon J. and L.D. Fosdick, "DAVE--A Validation Error Detection and Documentation System for FORTRAN Programs," Software Practice and Experience, September 1976, Vol. 6., pp. 473-486
 - Ole92 Olender, K. M. and L. J. Osterweil, "Interprocedural Static Analysis of Sequencing Constraints," ACM Transactions on Software Engineering and Methodology, January 1992, 1(1), pp. 21-52.
 - Dwy95 Dwyer, M. B. and Clarke, L. A. "A Flexible Architecture for Building Data Flow Analyzers," in CMPSCI Technical Report, August 17, 1995
 - Adr82 Adrion, W.R., M.A. Branstad, and J.C. Cherniavsky, "Validation, Verification and Testing of Computer Software," ACM Computing Surveys, June 1982, pp.159-192
 - Hoa69 Hoare, C.A.R., "An Axiomatic Basis for Computer Programming," Communications of the ACM, October 1969.
 - Flo67 Floyd, R.W. "Assigning Meaning to Programs", in the Proceedings of Symposium on Applied Mathematics, 1967, pp. 19-32, (Appeared as volume 19 of Mathematical Aspects of Computer Science).
 - Han76 Hantler, S.L. and J.C King., "An Introduction to Proving the Correctness of Programs," ACM Computing Surveys, September 1976, pp. 278-300.
 - Cla85 Clarke L. A. and D. J. Richardson, "Applications of Symbolic Evaluation," Journal of Systems and Software, January 1985, 5 (1), pp.15-35.
 - Zhu97 Zhu, Hong, Patrick A. V. Hall, and John H. R. May, "Software Unit Test Coverage and Adequacy," ACM Computing Surveys, vol. 29, no.4, pp. 366-427, December, 1997.
 - Wey80 Weyuker, Elaine J. and Thomas Ostrand, "Theories of Program Testing and the Application of Revealing Subdomains," IEEE Transactions on Software Engineering, May 1980, SE-6(5), pp. 236-246
 - DeM79 DeMillo R.A. and R.J. Lipton and A.J. Perlis, "Social Processes and Proofs of Theorems and Programs, Communications of the ACM, May 1979, 22(5), pp. 271-280





Basic Verification Strategy

- analyze a system for desired properties, i.e., compare behavior to intent
 - intent
 - can be expressed as properties of a model
 - can be expressed as formulas in mathematical logic
 - behavior
 - can be observed as software executes
 - can be inferred from a model
 - can be expressed as formulas in mathematical logic
 - different representations support different sorts of inferences
 - comparison can be informal
 - done by human eye, e.g., inspection
 - can be done by computers
 - comparing text strings
 - can be done by model-checkers
 - such as formal machines (e.g., fsa's)
 - can be done by rigorous mathematical reasoning

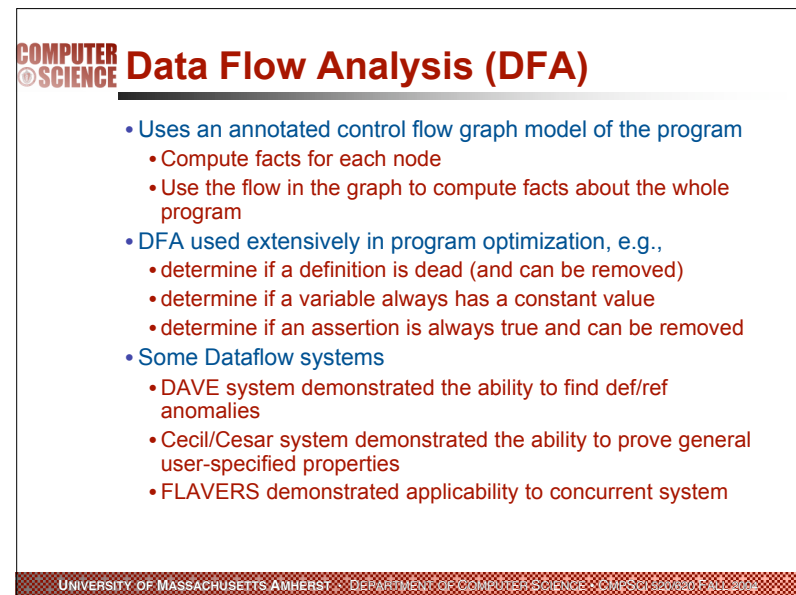
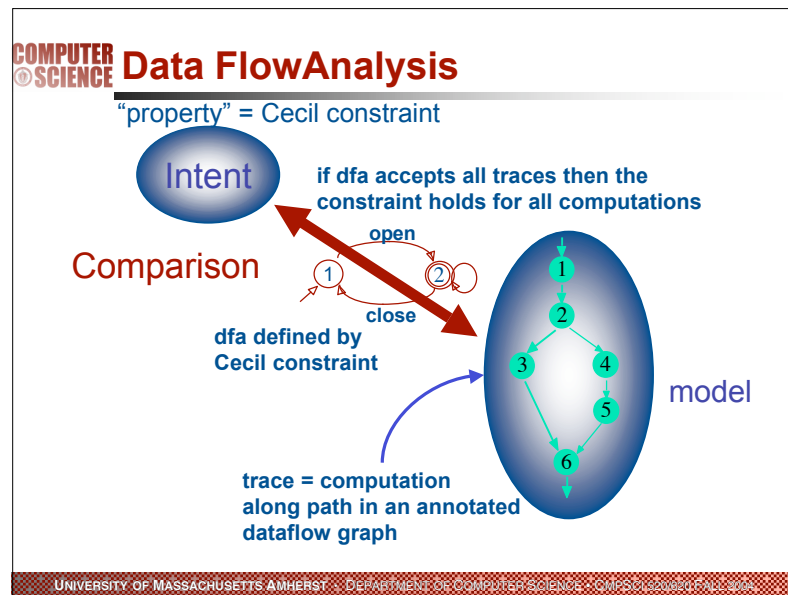
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Example: Dataflow Analysis

- intent:
 - stated as a property
 - captured as an event sequence
- behavior:
 - model represents some execution characteristics
 - inferred from a model: (e.g., annotated flow graph)
 - inferences based upon:
 - semantics of flow graph
 - semantics captured by annotations
- comparison:
 - done by a fsa (e.g., a property automaton)

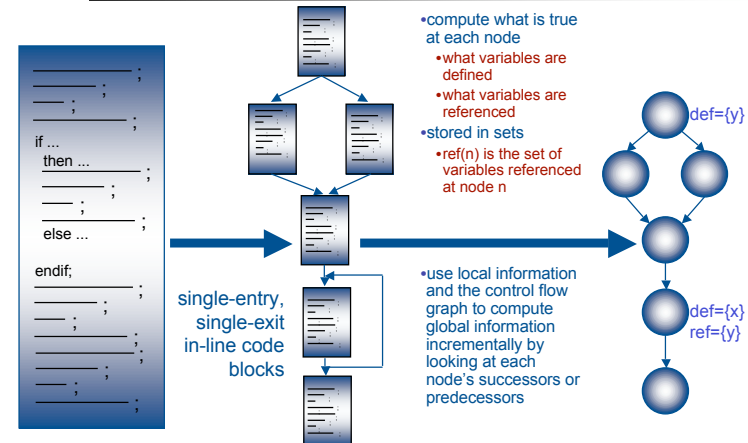
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Data flow analysis

- computes information that is true at each node in the CFG, e.g.,
 - what variables are defined
 - what variables are referenced
- usually stored in sets
 - $ref(n)$ is the set of variables referenced at node n
- uses this local information and the control flow graph to compute global information about the whole program
 - done incrementally by looking at each node's successors or predecessors

DFA



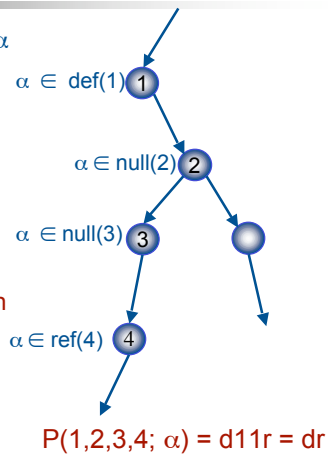
Def-ref path expressions

- for a path P and a variable α can write a path expression describing the sequence of set memberships encountered for α , where

- $\alpha \in \text{def}(n)$ or
- $\alpha \in \text{ref}(n)$ or
- $\alpha \in \text{null}(n)$
- for each node n on the path

- write (and simplify) a path expression

- $P(n_1, n_1, \dots, n_1; \alpha)$



Anomalous pairs of ref/defs

d - defined, r - referenced, u - undefined

dd	bug?	du	bug?
dr	normal	ud	normal
uu	harmless?	rr	normal
rd	normal	ru	normal
ur	bug		

← unreferenced definition

← undefined reference



Consider unreferenced definition

- Want to know if a def is not going to be referenced
 - dd or du
- At the point of a definition of a, want to know if there is some path where a is defined or undefined before being used
 - May be indicative of a problem if the path is executable
 - Usually just a programming convenience and not a problem
- At the point of a definition of a, want to know if on all paths a is defined or undefined before being used
 - May be indicative of a problem
 - Or could just be wasteful

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global dataflow analysis

- classes
 - forward flow problems (e.g., available expressions)
 - what definitions can affect computations at a given point in a program
 - backward flow problems (e.g., live variables)
 - what uses that follow a given point in the program can be affected by computations up to that point
- paths
 - any path
 - all path

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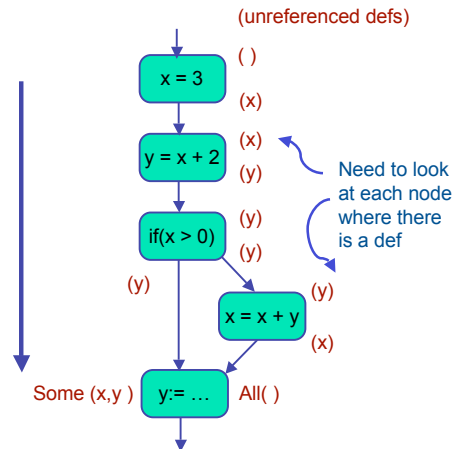
Unreferenced definitions

```

int x,y;
...
x := 3;
y := x + 2;
if x > 0 then
  x := x + y;
end if;
y := ...

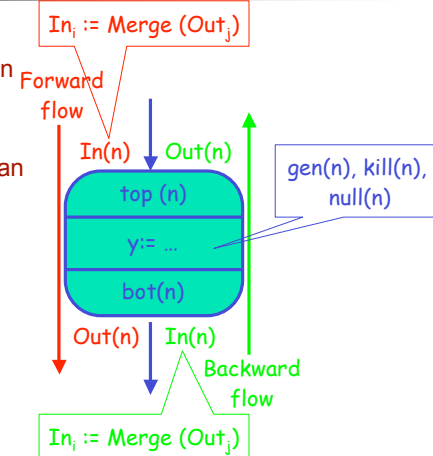
```

Forward flow,
all paths problem



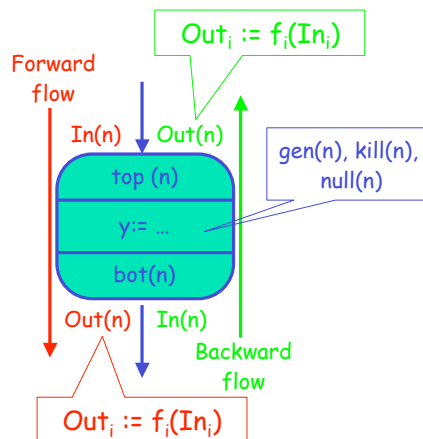
General Approach

- Initial values
 - for each node define gen and kill information
- Input Equations
 - for each node we have an equation of the form:
 $In_i := \text{Merge}(Out_j)$
 - "Merge" operation over the "predecessors" of n_i



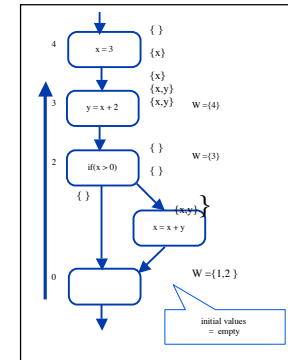
General Approach

- Transfer Equations
 - for each node we have an equation of the form: $Out_i := f_i(In_i)$
 - Transfer functions usually depend on Gen/Kill information that is computed for each node
 - Usually: $Out := (In - kill) \cup gen$
- We can view the set of variables, transfer functions, and flow graph as a system of equations



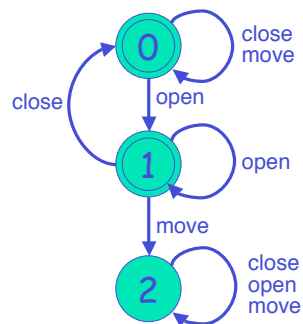
worklist algorithm

1. Start at initial node (entry for forward; exit for reverse), label IN_0 with pertinent "facts" (initial values)
2. Compute $OUT_0 = F(IN_0)$ (label OUT_0 with the computed facts)
3. Propagate OUT_0 to IN_i (label edge $N_0 \Rightarrow N_i$ with OUT_0) where N_i are successor nodes (forward) or predecessor nodes (reverse) of N_0
4. Compute $OUT_i = F(IN_i)$, place all N_i on a "worklist" W , and for all N_i label OUT_i with the computed facts.
5. While W is not empty,
 1. pick N_i from W and propagate OUT_i to IN_k (label edges $N_i \Rightarrow N_k$ with OUT_i) where N_k are successor nodes (forward) or predecessor nodes (reverse) for N_i ; delete N_i from W
 2. Compute $OUT_k = F(IN_k)$ for all N_k where $IN_k = \text{MERGE}$ all input edge labels (MERGE = $\cup$ for "some paths" and $\cap$ for "all paths"), label OUT_k with the computed facts; and if for N_k , OUT_k changes put N_k on W
6. If W' is not empty, then $W=W'$ and go to 5



Using Quantified Regular Expressions

- Alphabet, quantification, regular expression
- For the events {open, close, move}
show that for all paths:
 $((\text{close} \vee \text{move})^*, (\text{open}^+ \vee \text{open}^+, \text{close})^*)$



Cecil: Olender and Osterweil

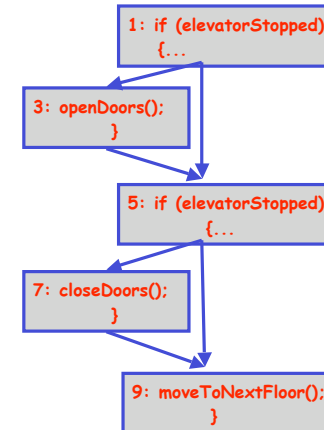
- Instead of implicitly defined facts, let the user define application-specific facts
 - Represented as a Deterministic Finite State Automaton (DFSA) or as a Quantified Regular Expression (QRE)
- Events
 - Recognizable events
 - Method calls
 - Can reason about sequences of method calls
 - E.g., Push must be called before Pop
 - Thread interactions
 - Join or Fork
 - Arbitrary operations
 - $a+b$
 - Need to be able to treat events as indivisible actions
 - E.g., can treat pop and push as atomic as long as they do not contain any events of concern
- Propagate the states in the DFSA that can reach each node in the program

State Propagation

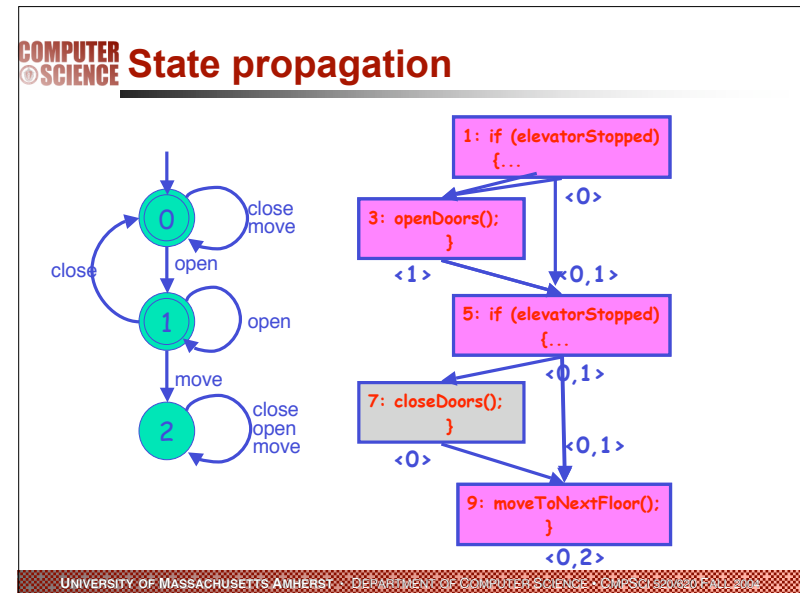
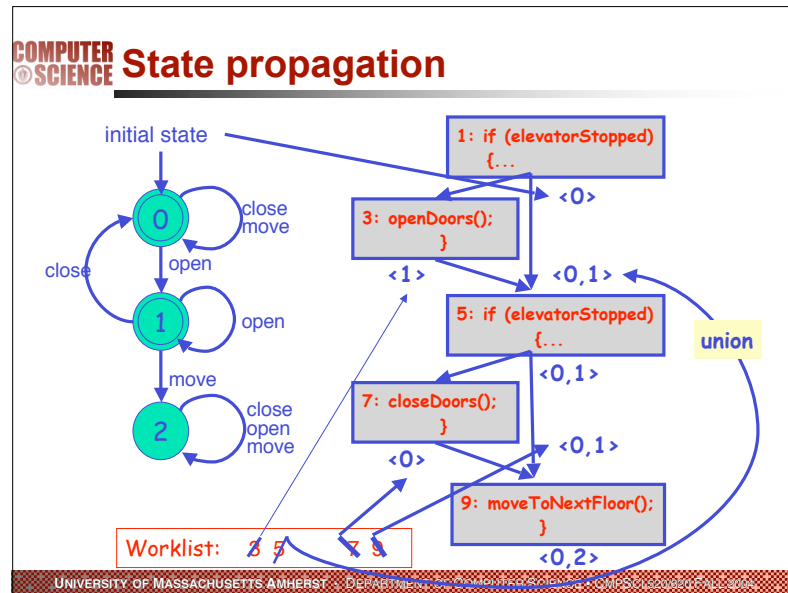
- States of the property are propagated through the CFG
- The property is proved if only accepting (non-accepting) states are contained in the final node of the CFG
- Cecil DFSA ->
 - lattice $(\mathcal{P}(S), \subseteq, \cup)$
 - function space
 - $\delta : \mathcal{P}(S) \rightarrow \mathcal{P}(S)$
 - facts at nodes are elements of $\mathcal{P}(S)$
- propagate until convergence and check if terminal node in an accepting state of DFSA

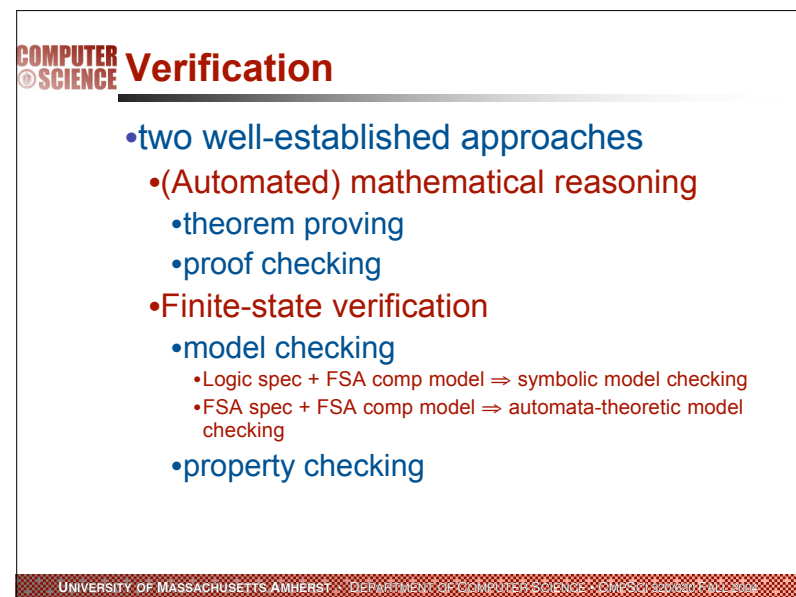
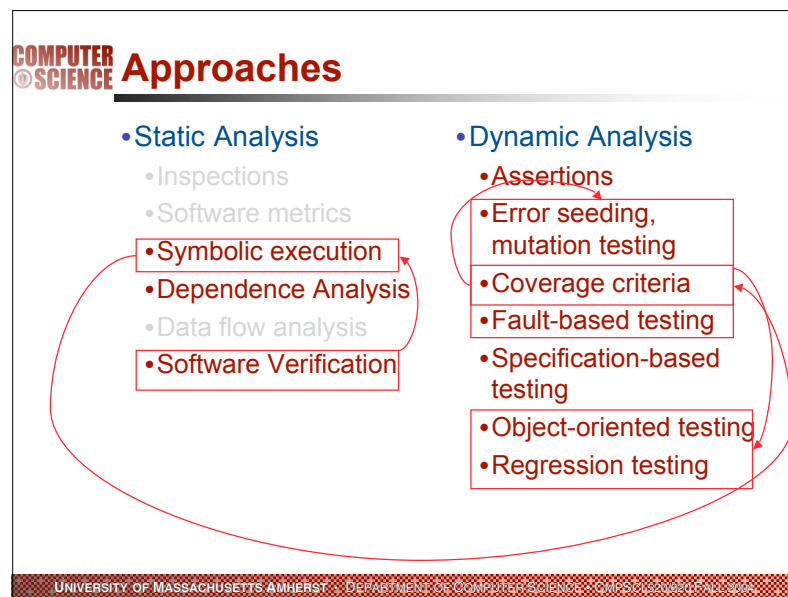
Elevator Controller

```
void main()
{
1: if (elevatorStopped)
{
3: ...
openDoors();
}
5: if (elevatorStopped)
{
7: ...
closeDoors();
}
9: moveToNextFloor();
}
```



- States of the property are propagated through the CFG
- For an **all** property: the property is proved if only accepting states are contained in the final node of the CFG
- For a **none** property: the property is proved if only non-accepting states are contained in the final node of the CFG





Verification

- How are they different?
 - (Automated) mathematical reasoning
 - difficult, error prone
 - decidability vs. expressiveness
 - Propositional calculus is decidable
 - Predicate calculus is semi-decidable
 - Finite-state verification
 - Reason about a finite model of the system
 - Fast, yields counterexamples, manages partial specifications, applies to concurrency
 - State explosion!

Proof

predicate logic
assertions



lemmas and theorems in
predicate logic

typically inferred
by symbolic
execution of the
specifications



Behavior



Floyd Method of Inductive Assertions

- Show that given the input assertions, after executing the program, program satisfies output assertions
 - show that each program fragment behaves as intended
 - use induction to prove that all fragments, including loops, behave as intended
- show that the program must terminate
- informal description
 - Place assertions at the start, final, and intermediate points in the code.
 - Any path is composed of sequences of program fragments that start with an assertion, are followed by some assertion free code, and end with an assertion
 - $A_s, C_1, A_2, C_2, A_3, \dots, A_{n-1}, C_{n-1}, A_f$
 - Show that for **every** executable path, if A_s is assumed true and the code is executed, then A_f is true



Why does this work?

- suppose P is an arbitrary path through the program
- can denote it by

$$P = A_0 C_1 A_1 C_2 A_2 \dots C_n A_n$$

- where

A_0 - Initial assertion

A_n - Final assertion

A_i - Intermediate assertions

C_i - Loop free, uninterrupted, straight-line code



If it has been shown that

$$\forall i, 1 \leq i < n: A_i C_i \Rightarrow A_{i+1}$$

Then, by transitivity

$$A_0 \Rightarrow \dots \Rightarrow A_n$$

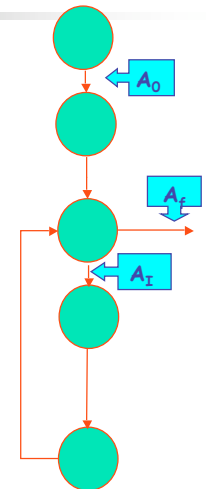
Obvious problems

- How do we do this for a path?
- How do we do this for all paths?
 - Infinite number of paths
 - Must find a way to deal with loops

Find loop invariant (A_l)

- subpaths to consider:
 - C_1 Initial assertion A_0 to final assertion A_f
 - C_2 Initial assertion A_0 to A_l
 - C_3 A_l to A_l
 - C_4 A_l to final assertion A_f
- Basically an inductive proof

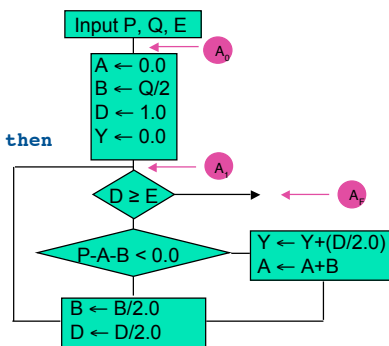
The “Aha!” moment -
finding invariants is
hard!



Wensley's Algorithm

```

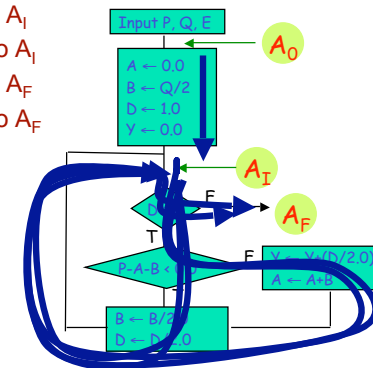
Procedure Wensley (P:input, Q:input, E:input, Y:output);
Declare P, Q, E, Y, A, B, D real;
A := 0.0;
B := Q/2.0;
D := 1.0;
Y := 0.0;
Do_While (D>=E)
  If ~(P - A - B ≥ 0.0) then
    { Y := Y+(D/2.0);
      A := A+B; }
  B := B/2.0;
  D := D/2.0;
End_do;
End Wensley;
    
```



Floyd Proof: Wensley's Algorithm

Summary of Five Lemmas Needed

- A_0 to A_1
- A_1 , true branch, to A_1
- A_1 , false branch, to A_1
- A_1 , true branch, to A_F
- A_1 , false branch, to A_F



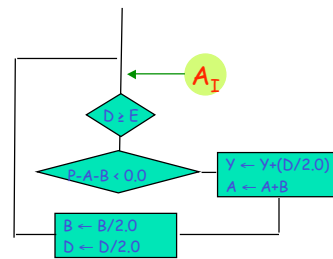
Lemma III: A_I , false branch, to A_I

A_I : $\{(A=Q*Y) \wedge (B=Q*(D/2))\}$
 $\wedge (k \geq 0, k \text{ integer} \wedge D=2^k)$
 $\wedge ((P/Q)-D) < Y \leq (P/Q)\}$

code

$D \geq E$ [constraint]
 $P - A - B \geq 0$ [constraint]
 $Y \leftarrow Y + (D/2.0)$
 $A \leftarrow A + B$
 $B \leftarrow B/2$
 $D \leftarrow D/2$

A'_I : $\{(A'=Q*Y') \wedge (B'=Q*(D'/2))\}$
 $\wedge (k \geq 0, k \text{ integer} \wedge D'=2^k)$
 $\wedge ((P/Q)-D') < Y' \leq (P/Q)\}$



proof of lemma III

$A_I \Rightarrow A'_I$: $\{(A'=Q*Y') \wedge (B'=Q*(D'/2))\}$
 $\wedge (k \geq 0, k \text{ integer} \wedge D'=2^k)$
 $\wedge ((P/Q)-D') < Y' \leq (P/Q)\}$

we have

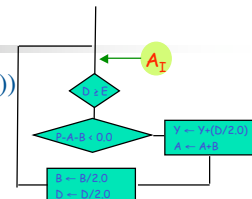
$A' = A + B$; $B' = B/2.0$; $D' = D/2.0$; $Y' = Y + D/2.0$;

1) $A' = A+B = Q*Y + Q*(D/2) = Q*(Y+(D/2))$;
 $Y' = Y+(D/2)$; $\therefore A' = Q*Y'$

2) $B' = B/2 = (Q*D/2)/2$; $D' = D/2$
 $\therefore B' = (Q * 2D'/2)/2 = Q* D'/2$

from A_I

and so on ... basically using symbolic evaluation





Hoare axiomatic proof

- assertions are preconditions and post conditions on some statement or sequence of statements
 $P\{S\}Q$
- if P is true before S is executed and S is executed then Q is true
- as in Floyd's inductive assertion method, we construct a sequence of assertions, each of which can be inferred from previously proved assertions and the rules and axioms about the statements and operations of the program
- to prove $P\{S\}Q$, we need some axioms and rules about the programming language



Hoare axioms and proof rules

- axiom of assignment
 - $P \{x := f\} Q$,
 - where Q is obtained from P by substituting f for all occurrences of x in P (symbolic execution)
- rule of composition
 - $P \{S_1, S_2\} Q \Rightarrow \exists P_1, P \{S_1\} P_1 \wedge P_1 \{S_2\} Q$
- rule for the alternative statement
 - $P \{ \text{if } B \text{ then } S_1 \text{ else } S_2 \} Q \Rightarrow P \{B \wedge S_1\} Q \wedge P \{\neg B \wedge S_2\} Q$
- rules of consequence
 - $[P \{S\} Q \wedge Q \Rightarrow R] \Rightarrow P \{S\} R$
 - $[P \{S\} Q \wedge R \Rightarrow P] \Rightarrow R \{S\} Q$
- rule of iteration
 - $P \{ \text{while } B \text{ do } S \} Q \Rightarrow P \{ \neg B \} Q \wedge \exists I. P \{B \wedge S\} I \wedge I \{B \wedge S\} I \wedge I \{ \neg B \} Q$

loop invariant

backwards substitution

COMPUTER SCIENCE Proof

- Hoare-style and Floyd-style verification are essentially the same
 - one is based on graphical representation and the other on a textual representation.
 - In Floyd-style proof, we visualize the proof goal by annotating a CFG
 - In the other, we define the proof goal as a Hoare triple
- Mechanism for applying proof
 - may work either direction on such a proof, but because it's typically easier to work backwards, often use a technique called backwards substitution
 - we work our way from the post-condition, using the proof rules to "push formulas through" the program
 - at each point where a "pushed-through" predicate "runs into" a supplied predicate, we have a verification condition (VC) that must be proved.
 - After all VCs are proved, we need to be prove termination
 - Without a termination proof, we achieve **partial correctness**
 - With a termination proof, we achieve **total correctness**

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COMPUTER SCIENCE Proof

predicate logic assertions



lemmas and theorems in predicate logic

typically inferred by symbolic execution of the specifications



Behavior

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COMPUTER SCIENCE Symbolic Evaluation/Execution

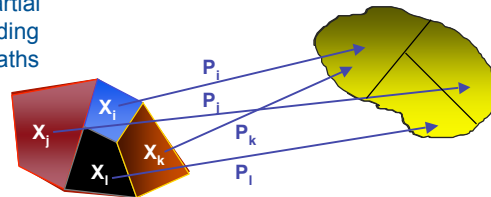
- Creates a functional representation of a path of an executable component

- P is composed of partial functions corresponding to the executable paths
 $P = \{P_1, \dots, P_r\}$

$$P_i : X_i \rightarrow Y$$

- For a path P_i

- $D[P_i]$ is the domain for path P_i
- $C[P_i]$ is the computation for path P_i



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COMPUTER SCIENCE Execution tree (Hantler-King)

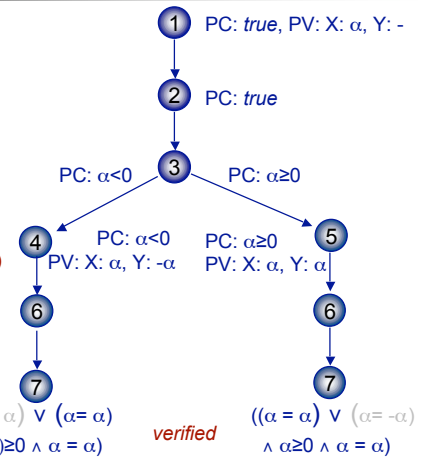
ABSOLUTE

assume (true)

```

1  procedure(X);
2  declare X,Y integer
3  if X<0
4    then Y ← -X;
5    else Y ← X;
6  return (Y);
7  end;
```

prove((Y = X' | Y = -X') & Y ≥ 0 & X = X')



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COMPUTER SCIENCE **Loops -- unroll them?**

```

n
n+1  do_while predicate1
n+2    if predicate2
n+3      then code ;
n+4      else code ;
n+5    end;
n+6  output assertion ;
    
```

input assertion

output assertion

better: find a loop invariant

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COMPUTER SCIENCE **Straightforward Observations**

- **Problems**
 - formal proofs are long, tedious and are often hard; assertions are hard to get right; invariants are difficult to get right (need to be invariant, but also need to support overall proof strategy)
- **Unsuccessful proof attempt $\Rightarrow$???**
 - incorrect software? assertions? placement of assertion? inept prover? although failed proofs often indicate which of the above is likely to be true (especially to an astute prover)
- **Deeper Issues**
 - undecidability of predicate calculus $\Rightarrow$ no way to be sure when you have a false theorem
 - there is no sure way to know when you should quit trying to prove a theorem (and change something)
 - proofs are generally much longer than the software being verified $\Rightarrow$ errors in the proof are more likely than errors in the software being verified

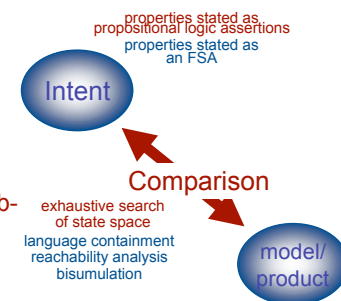
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Verification

- How are they different?
 - (Automated) mathematical reasoning
 - difficult, error prone
 - decidability vs. expressiveness
 - Propositional calculus is decidable
 - Predicate calculus is semi-decidable
 - Finite-state verification
 - Reason about a finite model of the system
 - Fast, yields counterexamples, manages partial specifications, applies to concurrency
 - State explosion!

Model Checking: Overview

- properties usually expressed in
 - in a propositional logic (e.g., temporal logic)
 - as a FSA
- system represented as a (possibly "abstracted") reachability graph
- reasoning engine
 - logic $\Rightarrow$ propagates valid sub-formulas through the graph
 - FSA $\Rightarrow$ compares FSAs via language inclusion; reachability; or bisimulation





Conservative Analysis

- If property is verified, property holds for all possible executions of the system
- If property is not verified:
 - an error found
 - OR
 - a spurious result
- System model abstracts information to be tractable
 - Conservative abstractions usually over-approximate behavior
 - If inconsistency relies upon over-approximations, then a spurious result
 - e.g. all counter example correspond to infeasible paths

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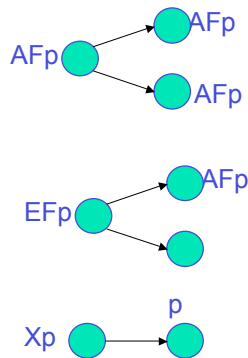
Temporal logic

- augments the standard operators of propositional logic with “tense” operators
- “possible worlds semantics” $\Rightarrow$ Kripke model
 - relativize the truth of a statement to temporal stages or states
 - a statement is not simply true, but true at a particular state
 - states are temporally ordered, with the type of temporal order determined by the choice of axioms.
- model of time
 - partially ordered time
 - linearly ordered time
 - linear temporal logic is typically extended by two additional operators, “until” and “since”
 - discrete time
 - branching (nondeterministic) time
 - foundation for one of the principal approaches to verifying concurrent systems = Computational Tree Logics.

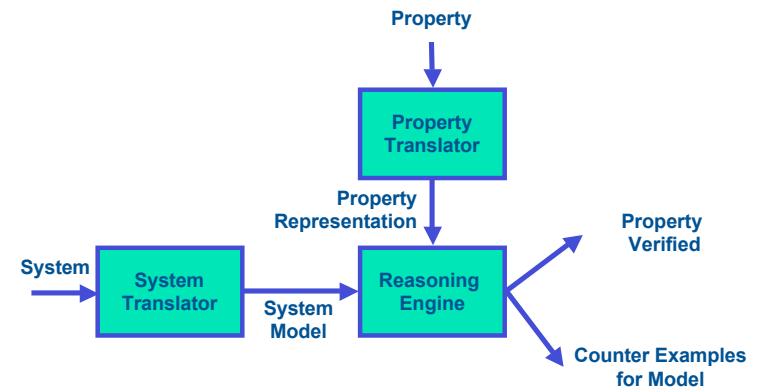
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Computation Tree Logics

- specification language
 - a propositional temporal logic.
- verification procedure
 - exhaustive search of the state space of the concurrent system to determine truth of specification.
- formulas constructed from path quantifiers and temporal operators:
 - path quantifier:
 - A "for every path"
 - E "there exists a path"
 - temporal operator:
 - Xp "p holds next time"
 - Fp "p holds sometime in the future"
 - Gp "p holds globally in the future"
 - pUq "p holds until q holds"



Architecture of FSV Systems



mutual exclusion protocol

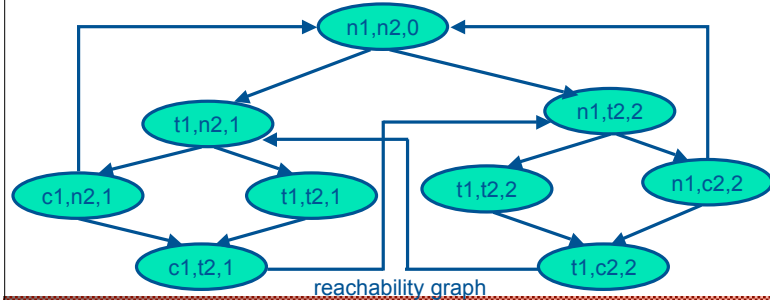
♣ Example: processes can be null, trying to obtain the lock, or in a critical region ($n1, t1, c1$) or ($n2, t2, c2$)

♣ TURN is a variable that indicates which process can obtain the lock (0,1,2)

♣ Need a reachability graph that shows that states (i.e., the values) of the variables

process1 = $n1, t1, c1$
process2 = $n2, t2, c2$
turn = 0,1,2

*McMillan



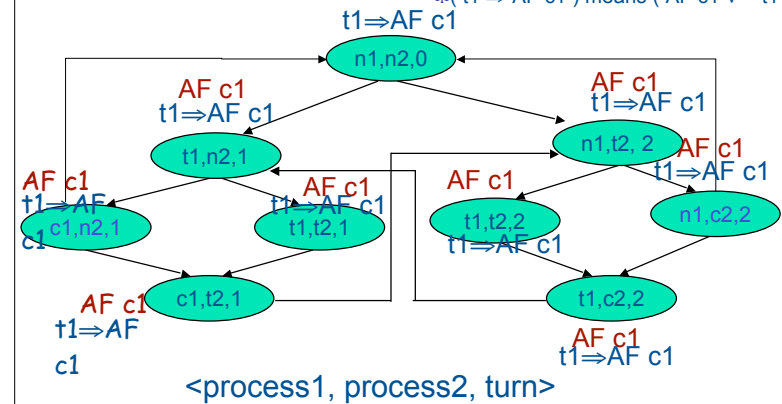
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Example: propagation

$AG(t1 \Rightarrow AF c1)$

♣ $a \Rightarrow b$ means (b or $\neg a$)

♣ $(t1 \Rightarrow AF c1)$ means $(AF c1 \vee \neg t1)$



<process1, process2, turn>

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COMPUTER SCIENCE Automata-Theoretic Model Checking

properties stated as an FSA



language containment
reachability analysis
bisimulation



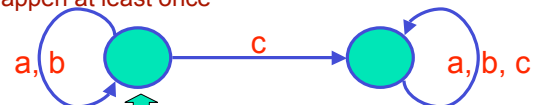
FSA

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COMPUTER SCIENCE Example

• Specification:

- of the possible observable events (a, b, c), c must happen at least once

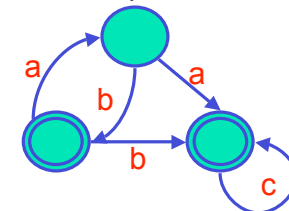


•

Accepted by?

$(ba)^*(ac^* + bbc^*)$

Implementation



Some observations

- Model Checking
 - worst case bound linear in size of the model
 - but the model is exponential
 - not clear if model checking or symbolic model checking is superior
 - depends on the problem
 - experimentally often very effective!
 - used selectively to verify hardware designs
 - trying to develop appropriate abstractions to make it applicable to software systems

Approaches

- Static Analysis
 - Inspections
 - Software metrics
 - Symbolic execution
 - Dependence Analysis
 - Data flow analysis
 - Software Verification
- Dynamic Analysis
 - Assertions
 - Error seeding, mutation testing
 - Coverage criteria
 - Fault-based testing
 - Specification-based testing
 - Object-oriented testing
 - Regression testing

Types of Testing--what is tested

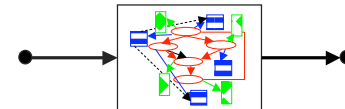
- Unit testing
 - exercise a single simple (procedure) component
- Integration testing
 - exercise a collection of inter-dependent components
 - focus on interfaces between components
- System testing
 - exercise a complete, stand-alone system
- Acceptance testing
 - customer's evaluation of a system
 - usually a form of system testing
- Regression testing
 - exercise a changed system
 - Focus on modifications or their impact

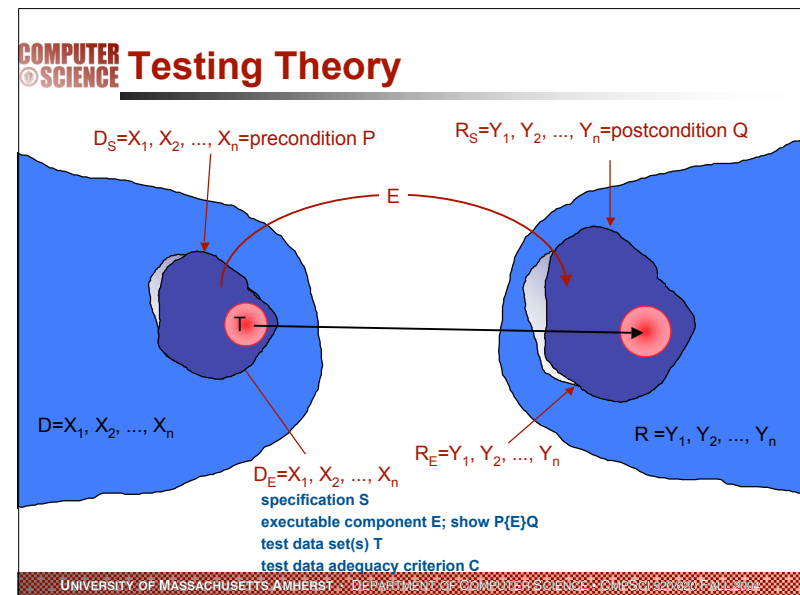
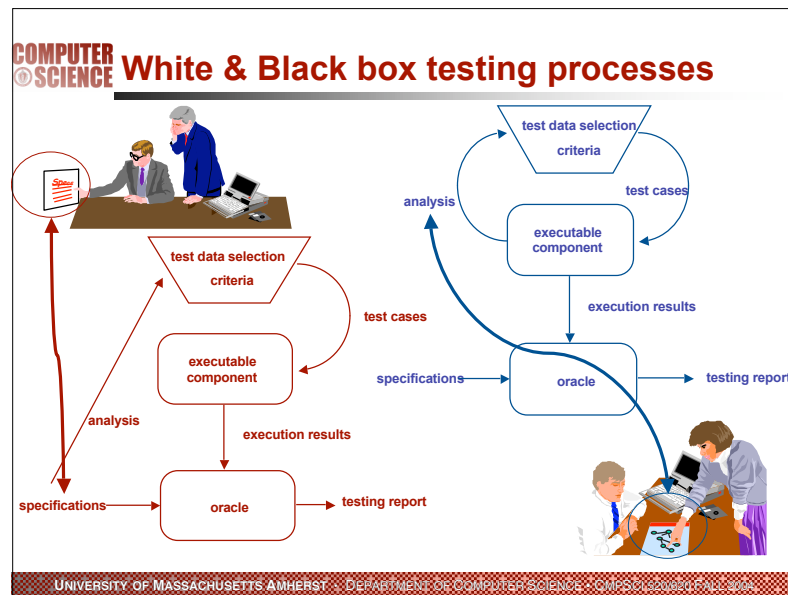
Testing approaches

- “black box”



- “white box” or “glass box”





Testing Theory

• Criterion C for Test Adequacy

$$C: S \times E \rightarrow 2^T$$

• specification-based	$C(s)$	"black box"
• interface-based	$C(x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_n)$	
• program-based	$C(e)$	
• combined	$C(s, e)$	"white box"

• Types

- structural
- fault-based
- error-based

• if specification S defines a function F, such that $P\{F\}Q$, then C is *reliable* if $T_1, T_2, \dots, T_m; C(T_i, E)$; and $D(E) \supseteq T_i$

- $\forall T_i (\forall t \in T_i, E(t) = F(t)) \vee \forall T_i (\exists t \in T_i, E(t) \neq F(t))$
- $\forall t \in T_i, E(t) = F(t) \Rightarrow \forall t \in T_i, OK(T_i) \Rightarrow E = F$

Ideal Test Criterion

- test criterion C is *ideal* if for any executable component E and every test set $T_i \subseteq D(E)$ such that $C(T_i, E)$, T_i is successful
 - of course we want $T_i \ll D(E)$
 - but in general, $T = D(P)$ is the only ideal test criterion
- In general, there is no ideal test criterion
 - "Testing shows the presence, not the absence of bugs" E. Dijkstra
- Dijkstra was arguing that verification was better than testing
- but, verification has similar problems
 - can't prove an arbitrary program is correct
 - can't solve the halting problem
 - can't determine if the specification is complete
- need to use these techniques so that they compliment one another



Black Box Testing

- Functional/Interface Test Data Selection
 - typical cases
 - boundary conditions/values
 - illegal conditions (if robust)
 - fault-revealing cases
 - based on intuition about what is likely to break the system
 - other special cases
- stress testing
 - large amounts of data
 - worse case operating conditions
- combinations of events
 - select those cases that appear to be more error-prone
- common representations for selecting sequences of events
 - decision tables
 - cause and effect graphs
 - usage scenarios

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“White Box” Test Data Selection

- structural
 - coverage based
- fault-based
 - e.g., mutation testing, RELAY
- error-based
 - domain and computation based
 - use representations created by symbolic execution

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