





















COMPUTER Straightforward Observations

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Problems

- formal proofs are long, tedious and are often hard; assertions are hard to get right; invariants are difficult to get right (need to be invariant, but also need to support overall proof strategy)
- Unsuccessful proof attempt \Rightarrow ???
- incorrect software? assertions? placement of assertion? inept prover? although failed proofs often indicate which of the above is likely to be true (especially to an astute prover)
- Deeper Issues
 - undecidability of predicate calculus \Rightarrow no way to be sure when you have a false theorem
 - there is no sure way to know when you should quit trying to prove a theorem (and change something)
- proofs are generally much longer than the software being verified ⇒ errors in the proof are more likely than errors in the software being verified





Temporal logicaugments the standard operators of propositional logic with "tense" operators "possible worlds semantics" Kripke model relativize the truth of a statement to temporal stages or states a statement is not simply true, but true at a particular state states are temporally ordered, with the type of temporal order determined by the choice of axioms. model of time partially ordered time linear temporal logic is typically extended by two additional operators, "until" and "since" discrete time branching (nondeterministic) time oundation for one of the principal approaches to verifying concurrent systems = Computational Tree Logics.

















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$\label{eq:criterion C for Test Adequacy} = C:SxE ->2^T \\ = specification-based C (s) $	ITER Testing Theo	ry	
$\begin{array}{c c} \mbox{-specification-based} & C (s) & \mbox{-specification-based} & C (x) & \mbox{-specification-based} & C (x1, x2,, xn, y1, y2,, yn) \\ \hline \mbox{-specification-based} & C (e) & \mbox{-specification-based} & C (s,e) & \mbox{-specification-based} & -specification-specificatio-specificatio-specificatio-$	■Criterion C for Test / ■C:SxE ->2 ^T	Adequacy	
$\begin{array}{l lllllllllllllllllllllllllllllllllll$	specification-based	d C (s)	"black box"
$\label{eq:combined} \begin{array}{c} C \ (e) \\ \hline \ combined \\ \hline \ C \ (s,e) \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	■interface-based	C (x1, x2, .	, xn, y1, y2,, yn)
$\label{eq:combined} \begin{array}{c} C \ (s,e) & \text{``white box''} \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	program-based	C (e)	
•Types •structural •fault-based •error-based •error-based • $\forall T_1, T_2, \dots, T_m; C(T_i, E); and D(E) \supseteq T_i \\ \forall T_i (\forall t \in T_i, E(t) = F(t)) \lor \forall T_i \\ (\exists t \in T_i E(t) \neq F(t)) \\ \bullet \forall t \in T_i, E(t) = F(t) \Rightarrow$	combined	C (s,e)	"white box"
$\forall t \in T_{i} OK(T_{i}) \Longrightarrow E = F$	 Types structural fault-based error-based 	• if specification such that P{F T_1, T_2, \dots, T_m • $\forall T_i (\forall t \in T_i, I)$ ($\exists t \in T_i E(t)$ • $\forall t \in T_i, E(t)$ $\forall t \in T_i OK($	n S defines a function F }Q, then C is <i>reliable</i> if ; C(T _i ,E); and D (E) ⊇ T E(t)= F(t)) v \forall T _i ≠ F(t)) = F(t) ⇒ T _i) ⇒ E = F



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CFG-Based Coverage Statement Coverage Path Coverage Cyclomatic-number Branch Coverage Hidden Paths Loop Guidelines Boundary - Interior Selecting paths that satisfy the criteria static selection some of the associated paths may be infeasible dynamic selection monitors coverage and displays areas that have not been satisfactorily covered

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COMPUTER Other Fault-Based techniques:

mutating test data

 instead of mutating program, mutate input
 Bart Miller did an experiment where he demonstrated that arbitrary strings caused UNIX to consistently fail
 wanted to understand why storms caused his connection to go down

©SCIENCE Putting it all together

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unit testing
integration & system testing
regression testing

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COMPUTER Unit Testing

- •What is a "Unit"?
- Traditional: a "single operation"
- •O-O: encapsulated data & operations
- Smallest testable unit = class many operations
- Inheritance

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- testing "in isolation" is impossible
- operations must be tested every place they are used





•The distance between object-oriented specification and implementation is typically small

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- gap (and therefore usefulness) of the whitebox/black-box distinction is decreasing
 But object-oriented specification describes functional behavior, while the implementation
- These techniques can be adapted to method
- testing, but are not sufficient for class testing
- Conventional flow-graph approaches
 may be inconsistent the object-oriented paradigm
 method-level control faults are not likely

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- Conventional black-box methods are useful for objectoriented systems
 - error-guessing strategies
- verification of ADTs can be adapted to objectoriented systems
- Other approaches

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- •utilize specifications integrated with the implementation as assertions
- specification integrated with the implementation as dynamic assertions
- •C++ assertions or Eiffel pre/post-conditions offer similar self-checking
- Utilize method (event) sequence information
 - usually don't have history of method invocations so can't do this with assertions

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Integrate set of classes required to respond to one input or

• Example: Event-Dispatching Thread vs. Event Handlers in

Then implement dependent classes (layer by layer, or cluster-

Simple driver classes or methods sometimes required to test

COMPUTER O-O Integration Testing

Integrate one thread at a time

Implement & test all GUI events first

Implement & test independent classes first

Add event handlers one at a time

Thread-Based Testing

Use-Based Testing

event

Java

based)

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lower layers



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