Mining Data Streams-Estimating Frequency Moment

Barna Saha

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- Computing "moments" involves distribution of frequencies of different elements in the stream.
- ▶ Let f_i be the number of occurrences of the *i*th element for any $i \in [1, n]$, then the *k*th frequency moment is $F_k = \sum_i f_i^k$

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- The 1st moment is the sum of the f_is which must be the length of the stream. This is easy to calculate.
- The 2nd moment is the sum of the squares of the f_i's. It is sometimes called the *surprise number* as it measures the unevenness of the distribution of elements.
 - Suppose we have a stream of length 100.
 - Scenario 1: There are 10 elements each with frequency 10. $F_2 = 10 * 10^2 = 1000$
 - Scenario 2: There are 10 elements, 1st item has frequency 91, and rest have each frequency 1. F₂ = 91² + 9 * 1² = 8290.

Computing F_2 in Small Space

Alon-Matias-Szegedy: Linear Sketching

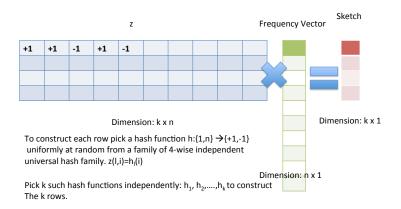
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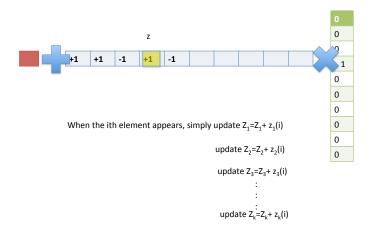
- ▶ Problem Given a stream A₁, A₂, ..., A_m where elements are coming from the universe [1, n] estimate F₂ = ∑ⁿ_{i=1} f²_i in "small space".
- Output Return an estimate \hat{F}_2 such that

$$\Pr\left(F_2(1-\epsilon) \leq \hat{F}_2 \leq (1+\epsilon)F_2\right) \geq (1-\delta)$$

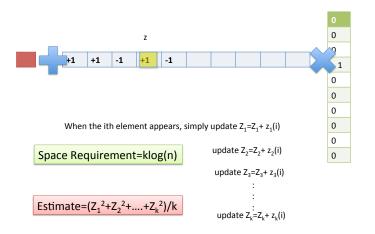
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where $\epsilon > 0$ and $\delta > 0$ are respectively the error and confidence parameters.





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Take $k = \frac{16}{\epsilon^{2}}$. $\operatorname{Prob}\left(|\hat{F}_{2} - F_{2}| > \epsilon F_{2}\right) \leq \frac{1}{8}$

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$$\bullet \text{ Take } k = \frac{16}{\epsilon^{2}}. \ Prob\left(|\hat{F}_{2} - F_{2}| > \epsilon F_{2}\right) \leq \frac{1}{8}$$

$$\bullet Prob\left(F_{2}(1 - \epsilon) \leq \hat{F}_{2} \leq (1 + \epsilon)F_{2}\right) \geq \frac{7}{8}$$

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Expectation of Z_s^2

$$Z_{s} \sim Z, s = 1, 2, ..., k$$

$$Z = \sum_{i=1}^{n} f_{i}z(i), Z^{2} = \sum_{i,j \in [1,n]} f_{i}f_{j}z_{i}z_{j}z_{j}$$

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$$E[Z^{2}] = \sum_{i,j \in [1,n]} E[f_{i}f_{j}z_{i}z_{j}] = \sum_{i} E[f_{i}^{2}z_{i}^{2}] = \sum_{i} f_{i}^{2} = F_{2}$$
since $E[z_{i}z_{j}] = 0$ if $i \neq j$ and $E[z_{i}^{2}] = 1$.

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since $E[z_{i}z_{j}] = 0$ if $i \neq j$ and $E[z_{i}^{2}] = 1$.
$$E[\hat{F}_{2}] = \frac{1}{k} \sum_{s=1}^{k} E[Z_{s}^{2}] = F_{2}$$

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 $= \sum_i f_i^4 + 6 \sum_{i,j:i < j} f_i^2 f_j^2$

since $E[z_i z_j z_k z_l] = 0$ if i < j < k < l or 3 of the terms are equal.

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$$(E[Z^2])^2 = \left(\sum_i f_i^2\right)^2 = \sum_i f_i^4 + 2\sum_{i,j:i< j} f_i^2 f_j^2$$

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$$Var(Z^2) = E[Z^4] - (E[Z^2])^2$$

► $E[Z^4] = \sum_i f_i^4 E[z_i^4] + \sum_{i,j:i < j} {4 \choose 2} f_i^2 f_j^2 E[z_i^2 z_j^2]$
 $= \sum_i f_i^4 + 6 \sum_{i,j:i < j} f_i^2 f_j^2$

since $E[z_i z_j z_k z_l] = 0$ if i < j < k < l or 3 of the terms are equal.

$$(E[Z^{2}])^{2} = \left(\sum_{i} f_{i}^{2}\right)^{2} = \sum_{i} f_{i}^{4} + 2\sum_{i,j:i < j} f_{i}^{2} f_{j}^{2}$$
$$Var(Z^{2}) = 4\sum_{i,j:i < j} f_{i}^{2} f_{j}^{2} \le 2F_{2}^{2}$$

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Variance of \hat{F}_2

$$\begin{aligned} Var(\hat{F}_2) &= Var(\frac{1}{k}\sum_{s=1}^{k}Z_s^2) \\ &= \frac{1}{k^2}Var(\sum_{s=1}^{k}Z_s^2)) \text{ since } Var(aX) = a^2Var(X) \text{ for any constant } \\ &= \frac{1}{k^2}\sum_{s=1}^{k}Var(Z_s^2) \leq \frac{1}{k^2}2kF_2^2 = \frac{2F_2^2}{k} \end{aligned}$$

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Boosting Confidence by Median

We have

$$Prob\left(F_2(1-\epsilon) \leq \hat{F}_2 \leq (1+\epsilon)F_2\right) \geq \frac{7}{8}$$

We want

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► Take t independent estimates

$$H_1 = \hat{F}_2^{-1}, H_2 = \hat{F}_2^{-2}, ..., H_t = \hat{F}_2^{-t}$$

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► Take *t* independent estimates

$$H_1 = \hat{F}_2^{\ 1}, H_2 = \hat{F}_2^{\ 2}, ..., H_t = \hat{F}_2^{\ t}$$

• Return the median of H_1 , H_2 ,..., H_t .

- Suppose there is an Algorithm that returns an estimate *F̂* of a true estimate *F* such that |*F̂* − *F*| is small with probability ⁷/₈.
- How can we design an algorithm that will return an estimate G of F such that |G − F| is small with probability 99/100? (In general 1 − δ)

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- Suppose there is an Algorithm that returns an estimate *F̂* of a true estimate *F* such that |*F̂* − *F*| is small with probability ⁷/₈.
- How can we design an algorithm that will return an estimate G of F such that |G − F| is small with probability 99/100? (In general 1 − δ)
- Run s = 2 log ²/_δ + 1 independent copies of the Algorithm to obtain estimates Ê¹, Ê², ..., Ê^s. Set G = median^s_{i=1}Êⁱ.

What is the probability that the median is a bad estimate?

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- What is the probability that the median is a bad estimate?
- ► Either all L^s/2 copies with estimate below G are bad or, L^s/2 copies with estimate above G are bad. That is there are log ²/_δ copies that are at least bad for G to be a bad estimate.

- What is the probability that the median is a bad estimate?
- ► Either all \[\[\frac{s}{2}\]\] copies with estimate below G are bad or, \[\[\frac{s}{2}\]\] copies with estimate above G are bad. That is there are log \[\[\frac{2}{\delta}\] copies that are at least bad for G to be a bad estimate.

• Show that the probability of Median to be bad is $\leq \delta$

For k > 2, the best bound known is Õ(n^{1-2/k} log 1/δ) barring poly(1/ϵ) factor. There is an almost matching lower bound of Ω(n^{1-2/k}).

- For k < 2, the best bound known is $\tilde{O}(\frac{1}{\epsilon^2} \log \frac{1}{\delta})$.
- The algorithms use clever combination of sketching and hashing

Sketching as a Versatile Tool

- Estimating entropy, quantiles, heavy hitters, fitting histograms etc.
- Applications beyond streaming: dimensionality reduction, nearest neighbors, anomaly detection, statistics over social network.
- Not only useful for small-space algorithm design, but also for fast running time, distributed processing etc.

Sketching as a Versatile Tool

A different linear sketch

- Instead of ±1, let r_i be i.i.d. random variables from N(0,1)
- Consider

- We still have that $E[Z^2] = \sum_i x_i^2 = ||x||_2^2$, since: - $E[r_i] E[r_i] = 0$ - $E[r_i^2] = variance of r_i, i.e., 1$
- As before we maintain $\mathbf{Z}=[Z_1 \dots Z_k]$ and define $Y = ||\mathbf{Z}||_2^2 = \sum_i Z_i^2 \quad \text{(so that } \mathbb{E}[Y]=k||x||_2^2 \text{)}$
- We show that there exists C>0 s.t. for small enough ε>0

$\Pr[|Y - k||x||_{2}^{2} \ge \epsilon k ||x||_{2}^{2}] \le \exp(-C \epsilon^{2} k)$

Slide from Piotr Indyk's course on Streaming, Sketching and Compressed Sensing

Sliding Window Model

▶ Only the last *W* items matter where *W* is the window size.

Sliding Window Model

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Can you extend Bloom Filter, FM sketch in this setting?

Sliding Window Model

Only the last W items matter where W is the window size.

- Can you extend Bloom Filter, FM sketch in this setting?
- Can you extend Count-Min sketch or linear sketching techniques in this setting?

Decaying Window Model

► No fixed window size, but older items have less importance.

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