k-means, k-means++

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- 25 years ago Llyod proposed a simple *local search* algorithm that is still very widely used today.
- A 2002 survey of data mining techniques states that it "is by far the most popular clustering algorithm used in scientific and industrial applications."

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- ► Convergence could be slow: *kⁿ* possible clusterings.
- Lloyd's k-means algorithm has polynomial smoothed running time.

Illustration of k-means clustering

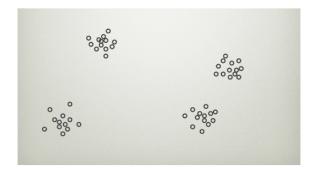


Figure: Convergence to Local Optimum

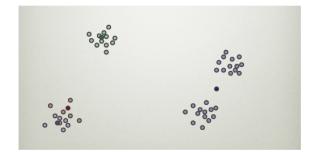
By Agor153 - Own work, CC BY-SA 3.0, https://commons.wikimedia.org/w/index.php?curid=19403547

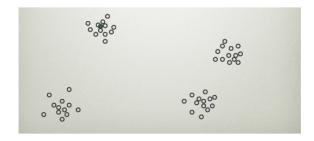
Drawbacks of k-means algorithm

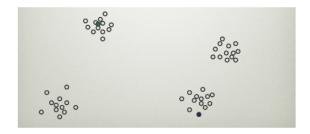
- Euclidean distance is used as a metric and variance is used as a measure of cluster scatter.
- The number of clusters k is an input parameter: an inappropriate choice of k may yield poor results. That is why, when performing k-means, it is important to run diagnostic checks for determining the number of clusters in the data set.
- Convergence to a local minimum may produce results far away from optimal clustering



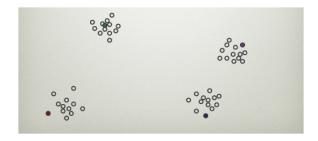
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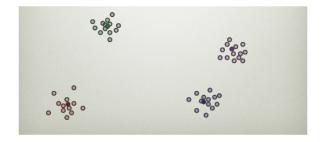




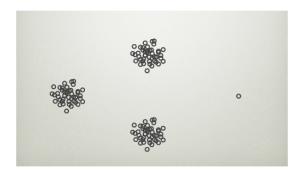




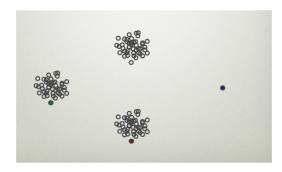




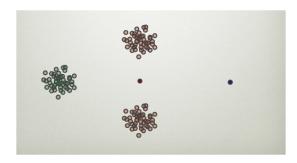
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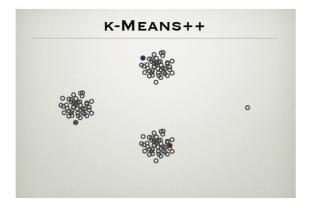


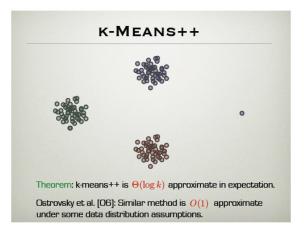
Interpolate between the two methods:

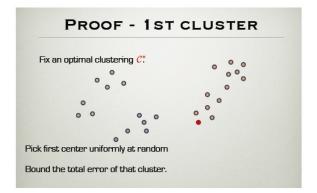
Let D(x) be the distance between x and the nearest cluster center. Sample x as a cluster center proportionately to $(D(x))^2$.

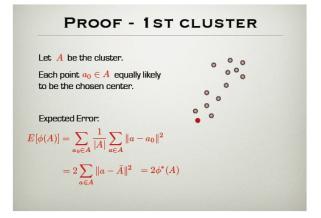
k-means++ returns clustering C which is log *k*-competitive.

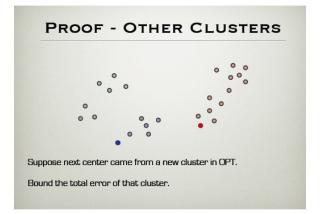
In the class we will show that if the cluster centers are chosen from each optimal cluster then k-means++ is 8-competitive.

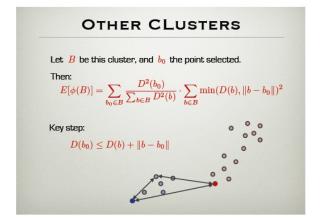




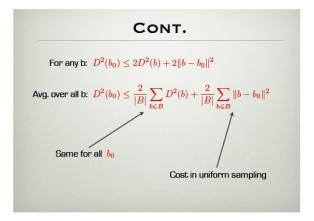








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CONT.

For any b: $D^2(b_0) \le 2D^2(b) + 2\|b - b_0\|^2$

Avg. over all b:
$$D^2(b_0) \leq rac{2}{|B|} \sum_{b \in B} D^2(b) + rac{2}{|B|} \sum_{b \in B} \|b - b_0\|^2$$

Recall:

$$E[\phi(B)] = \sum_{b_0 \in B} \frac{D^2(b_0)}{\sum_{b \in B} D^2(b)} \cdot \sum_{b \in B} \min(D(b), \|b - b_0\|)^2$$
$$\leq \frac{4}{|B|} \sum_{b_0 \in B} \sum_{b \in B} \|b - b_0\|^2 = 8\phi^*(B)$$

WRAP UP

If clusters are well separated, and we always pick a center from a new optimal cluster, the algorithm is 8- competitive.

Intuition: if no points from a cluster are picked, then it probably does not contribute much to the overall error.

Formally, an inductive proof shows this method is $\Theta(\log k)$ competitive.