COMPSCI 240: Reasoning Under Uncertainty

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Spring 2019, Section 01

Lecture 31: Review for Final Exam

Topics

- Basic counting problems
- Probability
- Discrete random variables
- Midterm Exam #1
- Continuous random variables
- Central limit theorem
- Probabilistic reasoning
- Game theory
- Midterm Exam #2
- Markov chains
- Bayesian network
- Final Exam

Overview

- Basic counting problems
 - Set theory: size of, subset, disjoint sets, partitions, power set, universal set, operations (complement, union, intersection)
 - Counting: permutations, k-permutations, combinations, partitions
- Probability
 - Probability axioms
 - Conditional probability (sequential model)
 - Multiplication rule
 - Total probability theorem
 - Bayes' rule
 - Independence
 - Conditional independence
- Discrete random variables
 - Probability mass function (PMF)
 - Common discrete RVs: uniform, Bernoulli, binomial, geometric, Poisson
 - Expectation and Variance + their properties (e.g., functions of RVs)
 - Multiple RVs (joint, marginal, conditional PMF; functions of two RVs, expectation and variance)

Problems from MIT OCW: Probabilistic Systems Analysis and Applied Probability Quiz 1 Spring 2009

Which of the following statements is NOT true? (a) If $A \subset B$, then $P(A) \leq P(B)$. (b) If P(B) > 0, then $P(A|B) \geq P(A)$. (c) $P(A \cap B) \geq P(A) + P(B) - 1$. (d) $P(A \cap B^c) = P(A \cup B) - P(B)$.

Which of the following statements is NOT true? (a) If $A \subset B$, then $P(A) \leq P(B)$. (b) If P(B) > 0, then $P(A|B) \geq P(A)$. (c) $P(A \cap B) \geq P(A) + P(B) - 1$. (d) $P(A \cap B^c) = P(A \cup B) - P(B)$.

Solution: (b)

A counter example: if we have two events A, B such that P(B) > 0 and P(A) > 0, but $A \cap B = \emptyset$, then P(A|B) = 0, but P(A) > P(A|B). It's easy to come up with examples like this: for example, take any sample space with event A such that P(A) > 0, and $P(A^c > 0)$, it follows that $P(A|A^c) = 0$, but P(A) > 0.

We throw n identical balls into m urns at random, where each urn is equally likely and each throw is independent of any other throw. What is the probability that the *i*-th urn is empty?

(a)
$$\left(1-\frac{1}{m}\right)^n$$

(b) $\left(1-\frac{1}{n}\right)^m$
(c) $\binom{m}{n} \left(1-\frac{1}{n}\right)^m$
(d) $\binom{n}{m} \left(\frac{1}{m}\right)^n$

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(d) $\binom{n}{m}\left(\frac{1}{m}\right)^n$

Solution: (a)

The probability of the *j*th ball going into the *i*th urn is 1/m. Hence, the probability of the *j*th ball not going into the *i*th urn is (1-1/m). Since all throws are independent from one another, we can multiply these probabilities: the probability of all *n* balls not going into the *i*th urn, i.e. it is empty, is $(1-\frac{1}{m})^n$.

We toss two fair coins simultaneously and independently. If the outcomes of the two coins are the same, we win; otherwise, we lose. Let A be the event that the first coin comes up heads, B be the event that the second coin comes up heads, and C be the event that we win. Which of the following statements is false?

- (a) Events A and B are independent.
- (b) Events A and C are independent.
- (c) Events A and B are *not* conditionally independent given C.
- (d) The probability of winning is 1/2.

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- (b) Events A and C are independent.
- (c) Events A and B are not conditionally independent given C.
- (d) The probability of winning is 1/2.

Solution: (b)

The sample space in this case is $\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$. The probability law is a uniform distribution over this space. We have $A = \{(H, H), (H, T)\}, B = \{(H, H), (T, H)\}, \text{ and } C = \{(H, H), (T, T)\}$. By the discrete uniform law, P(A) = P(B) = P(C) = 1/2. We also have $P(A \cap C) = 1/4$, hence $P(A \cap C) = P(A)P(C)$, and the two events are independent. Intuitively, knowing that you won adds no information about whether your coin turned up heads or not: stating this formally, we have P(A|C) = P(A).

For a biased coin, the probability of "heads" is 1/3. Let *h* be the number of heads in five independent coin tosses. What is the probability *P*(first toss is a head|*h* = 1 or *h* = 5)?

(a)
$$\frac{\frac{1}{3}(\frac{2}{3})^{4}}{5\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}$$

(b)
$$\frac{\frac{1}{3}(\frac{2}{3})^{4}}{\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}$$

(c)
$$\frac{\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}{5\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}$$

(d)
$$\frac{1}{5}$$

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(b)
$$\frac{\frac{1}{3}(\frac{2}{3})^{4}}{\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}$$

(c)
$$\frac{\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}{5\frac{1}{3}(\frac{2}{3})^{4} + (\frac{1}{3})^{5}}$$

(d)
$$\frac{1}{5}$$

Solution: (c)

Let A be the event that the first toss is a head.

$$P(A|\{H=1\} \text{ or } \{H=5\}) = \frac{P(A \cap (\{H=1\} \cup \{H=5\}))}{P(\{H=1\} \cup \{H=5\})}$$
$$= \frac{P((A \cap \{H=1\}) \cup (A \cap \{H=5\}))}{P(\{H=1\}) \cup \{H=5\})}$$
$$= \frac{P(\{H=1\}) + P(A \cap \{H=5\})}{P(\{H=1\}) + P(\{H=5\})} = \frac{(1/3)^5 + (1/3)(2/3)^4}{\binom{5}{1}(1/3)(2/3)^4 + \binom{5}{5}(1/3)^5}$$

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(a)
$$\frac{\binom{48}{22}}{\binom{52}{26}}$$

(b) $\frac{4\binom{48}{22}}{\binom{52}{26}}$
(c) $\frac{48!}{22!}\frac{52!}{26!}$
(d) $\frac{4!\binom{48}{22}}{\binom{52}{26}}$

Solution: (a)

Let A be the event that player 1 gets all aces. By the discrete uniform law,

 $P(A) = |A|/|\Omega|$

 $|\Omega| = \binom{52}{16}$ is the number of hands (26 cards from 52) player 1 can have. Additionally, once we have given player 1 all aces, then they must be given an additional 22 cards from the remaining 48 cards in the deck. Hence,

$$P(A) = \binom{48}{22} / \binom{52}{26}$$

Suppose X, Y and Z are three independent discrete random variables. Then, X and Y + Z are

- (a) always independent
- (b) sometimes independent
- (c) never independent

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Solution: (a)

Since X is independent of Y and Z, X is independent of g(Y, Z) for any function g(Y, Z), including g(Y, Z) = Y + Z.

To obtain a driving license, Mina needs to pass her driving test. Every time Mina takes a driving test, with probability 1/2, she will clear the test independent of her past. Mina failed her first test. Given this, let Y be the additional number of tests Mina takes before obtaining a license. Then,

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$$E[Y] = 1$$

(b) $E[Y] = 2$
(c) $E[Y] = 0$

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(a)
$$E[Y] = 1$$

(b) $E[Y] = 2$
(c) $E[Y] = 0$

Solution: (b)

Y is defined as the number of additional tests Mina takes, so this is independent of the fact that she failed her first test. Y is a geometric RV with p = 1/2. Hence, E[Y] = 1/p = 2.

Let X_i , $1 \le i \le 4$ be independent Bernoulli random variable each with mean p = 0.1. Let $X = \sum_{i=1}^{4} X_i$. That is, X is a Binomial random variable with parameters n = 4 and p = 0.1. Then,

(a)
$$E[X_1|X=2] = 0.1$$

(b)
$$E[X_1|X=2] = 0.5$$

(c)
$$E[X_1|X=2] = 0.25$$

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- (b) $E[X_1|X=2] = 0.5$
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Solution: (b) We have $P(X_1 = 1 | X = 2) = 0.5$, because

$$P(X_1 = 1 | X = 2) = \frac{P(X_1 \cap X = 2)}{P(X = 2)} = \frac{p \cdot \binom{3}{1}p(1-p)^2}{\binom{4}{2}p^2(1-p)^2} = \frac{\binom{3}{1}}{\binom{4}{2}} = 0.5$$

Note that $\binom{4}{2}p^2(1-p)^2$ is the probability of seeing 2 heads out of 4 tosses, and $\binom{3}{1}p(1-p)^2$ is the probability of seeing 1 head in the last 3 tosses. Hence,

$$E[X_1|X=2] = 1 \cdot P(X_1=1|X=2) + 0 \cdot P(X_1=0|X=2) = 0.5$$

Lectures' summaries

How do we reason under uncertainty?

- Using Probability Theory
- Main idea: Assign each event a measure between 0 to 1: to signify its likelihood
- Then proceed very carefully or our intuitions and observations will not match

Set theory

Back to basics: Set theory

- A set is a collection of objects, which are the elements of the set
- If S is a set and x is an element of S, we write $x \in S$.
- If x is not an element of S, we write x ∉ S. A set can have no elements, in which case it is called the empty set, denoted by Ø.
- Apple ∈ { Orange, Apple, Pear } Strawberry ∉ { Orange, Apple, Pear }

Back to basics: Set theory



• Two ways of writing a set down:

$$S = \{1, 2, 3, 4, 5, 6\}$$

or

 $S = \{x | x \text{ is a possible outcome of a throw of a die}\}$

"The collection of all elements that satisfy a certain condition is a set"

Set theory

- Size of a set S is denoted by |S|
- $|\{ \text{ Orange, Apple, Pear } \}| = 3$
- S is a subset of T, S ⊂ T, means every element of S is also an element of T:

 $\forall x \in S, x \in T$

- $\blacktriangleright \ \{ \mathsf{Apple, Pear} \ \} \subset \{ \ \mathsf{Orange, Apple, Pear} \ \}$
- { Orange, Apple, Pear } \subset { Orange, Apple, Pear }
- ▶ {Apple, Banana } $\not\subset$ { Orange, Apple, Pear }
- If $S \subset T$ and $T \subset S$ then,

$$S = T$$

Universal Set

- Ω: contains all objects that could conceivably be of interest in a particular context.
- In the context of coin tossing, $\Omega = \{H, T\}$.
- In the context of dice, $\Omega=\{1,2,3,4,5,6\}.$

Set operations

- Complement: $S^c = \{x \in \Omega | x \notin S\}$ Example: $\Omega = \{1, 2, 3, 4, 5, 6\}$; $S = \{2, 5\}$ $S^c = \{1, 3, 4, 6\}$ Note that, $\Omega^c = \emptyset$
- The union of two sets S and T is the set of all elements that belong to S or T (or both), and is denoted by S ∪ T.

$$S \cup T = \{x | x \in S \text{ or } x \in T\}$$

• The intersection of two sets S and T is the set of all elements that belong to both S and T, and is denoted by $S \cap T$.

$$S \cap T = \{x | x \in S \text{ and } x \in T\}$$

Power Set

By default: $\emptyset \subset S \subset \Omega$. **Power Set**: Set of all subsets

 $S = \{1, 2, 3\}$ $2^{S} = \{ \emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, \{1, 2, 3\} \}$

Disjoint Set

S and *T* are **disjoint** if $S \cap T = \emptyset$

 S_1, S_2, \ldots, S_n forms a **partition** of S if S_i and S_j are disjoint for any $i \neq j$ and $S_1 \cup S_2 \cup \cdots \cup S_n = S$.

Venn Diagram



Courtesy: Textbook

Venn Diagram - Partitions

- In (e), *S*, *T*, and *U* **do not** form partitions of *W*. However, *S*, *T*, *U*, and $(S \cup T \cup U)^C$ form partitions of *W*.
- In (f), S, T, and U form partitions of W.

Similarly,

- In (a),(b) and (c), S and T do not form partitions of W.
 However, (S ∪ T) and (S ∪ T)^C form partitions of W.
- In (d), T and T^C ∩ S form partitions of S. Furthermore, S and S^C form partitions of W.

Set Algebra

Using the above definitions, we can show that:

- Intersection Commutativity $S \cap T = T \cap S$
- Union Commutativity $S \cup T = T \cup S$
- Intersection Associativity $S \cap (T \cap U) = (S \cap T) \cap U$
- Union Associativity $S \cup (T \cup U) = (S \cup T) \cup U$
- Intersection Distributivity $S \cap (T \cup U) = (S \cap T) \cup (S \cap U)$
- Union Distributivity $S \cup (T \cap U) = (S \cup T) \cap (S \cup U)$

Summary: Sets

- A set is a collection of objects, which are the elements of the set
- $x \in S$, $x \notin S$, empty set \emptyset , number of elements in a set |S|
- Subset: $S \subset T$
- Universal set Ω , set complement: $S^c = \{x \in \Omega | x \notin S\}$
- Set union $S \cup T = \{x | x \in S \text{ or } x \in T\}$, intersection $S \cap T = \{x | x \in S \text{ and } x \in T\}$
- Power Set: Set of all subsets
- Disjoint sets $S \cap T = \emptyset$
- Partition of a set: S_i and S_j are disjoint for any $i \neq j$ and $S_1 \cup S_2 \cup \cdots \cup S_n = S$

Model of Probability
Model of Probability

A probabilistic model is a mathematical description of an uncertain situation. Two fundamental elements of a probabilistic model are

- Sample Space Ω : all possible outcomes of an experiment
- Probability Law:

$$A \subset \Omega; \quad P(A),$$

where A is an **event** (a set of possible outcomes) and P(A) is a non-negative number presenting the **likelihood** of observing the event A.

Probabilistic model involves an **experiment**, which produces an **event** from the **sample space**.



Probability Laws

- Probability represents likelihood of any outcomes or of any set of possible outcomes.
- The probability law assigns to every event A, a number P(A), call the **probability** of A.

Axioms of Probability

• Nonnegativity:

 $P(A) \geq 0$

• Additivity: For any two disjoint sets A and B,

$$P(A \cup B) = P(A) + P(B)$$

Holds for infinitely many disjoints events A_1, A_2, A_3, \ldots

$$P(\cup_i A_i) = \sum_i P(A_i).$$

Normalization:

 $P(\Omega) = 1$

Discrete Probability Models

If Ω consists of a finite number of possible outcomes, we are dealing with discrete probability models. For example,

- Coin Toss
- Dice Rolling

For discrete probabilistic models, the probability law is specified by the probabilities of the events that consists of a single element (that are disjoint by nature).

$$A = \{s_1, s_2, \dots, s_n\} \subset \Omega$$
$$P(\Omega) = P(\{s_1, s_2, \dots, s_n\}) = P(s_1) + P(s_2) + \dots + P(s_n)$$

Uniform Discrete Model

If Ω is finite and all possible outcomes are equally likely, it is a **uniform discrete model**. Then, the probability of each element of Ω has the probability of 1

 $|\Omega|$

More generally, $\forall A \subset \Omega$

$$P(A) = \frac{|A|}{|\Omega|}$$

Uniform Discrete Model - Example

Throwing a fair die is an example of a uniform discrete model. $\Omega = \{1, 2, 3, 4, 5, 6\}$ Uniform model:

$$P(\{i\}) = \frac{1}{|\Omega|} = \frac{1}{6}$$

for i = 1, 2, 3, 4, 5, 6. *A*: even number shows up

$$A = \{2, 4, 6\}$$
$$|A| = 3$$
$$P(A) = \frac{|A|}{|\Omega|} = \frac{3}{6} = \frac{1}{2}.$$

Conditional Probability

Conditional Probabilities

Conditional probability provides us with a way to reason about the outcome of an experiment based on **partial information** or **observations**.

Consider rolling a fair die. What is the probability that the outcome is 6 **given that** we know that the outcome is an even number.

• Suppose that you rolled a die while blindfolding yourself. Your friend next to you told you that the number is even. Does that change your probability space?

We can express this conditional probability using P(A|B): conditional probability of A given B, where P(B) > 0. In the above example,

- $A = \{ \text{ The outcome is } 6 \}$
- *B* = { The outcome is an even number }

Conditional Probabilities

- A new probability space to be defined.
- The universe (sample space) has been changed to B
- The probability has now to be normalized by P(B)

Definition of conditional probability,

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{|A \cap B|}{|B|}$$

- If A and B are disjoint, i.e., A ∩ B = Ø, then P(A|B) = 0.
 Why?
 - ▶ In the case of disjoint A and B, $A \cap B = \emptyset$.
 - Which means, $P(A \cap B) = 0$. So P(A|B) = 0.

New probability space $P(\cdot|B)$

Verify that the axioms of probability are satisfied!

- Nonnegativity: $P(A|B) = \frac{P(A \cap B)}{P(B)} \ge 0$ since $P(A \cap B) \ge 0$
- Additivity: For any two disjoint sets A and C, show that $P(A \cup C|B) = P(A|B) + P(C|B)$.

$$P(A \cup C|B) = \frac{P((A \cup C) \cap B)}{P(B)}$$
$$= \frac{P((A \cap B) \cup (C \cap B)))}{P(B)} = \frac{P(A \cap B) + P(C \cap B)}{P(B)}$$
$$= P(A|B) + P(C|B).$$

• Normalization: New sample space is *B*.

.

$$P(B|B) = \frac{P(B \cap B)}{P(B)} = \frac{P(B)}{P(B)} = 1$$

Example

Let us have two unfair coin tosses where the joint probability has

 $P({HH}) = 1/2$ $P({HT}) = 1/4$ $P({TH}) = 1/8$ $P({TT}) = 1/8$

What is the probability that we have exactly one H given that the second toss shows H?

Define A and B first.

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(\{TH\})}{P(\{HH, TH\})} = \frac{1/8}{1/2 + 1/8} = \frac{1}{5}.$$

Another Exercise

Example: Throw of two dice. Each of the 36 outcomes are equally likely

- $A = \max$ of two dice is less than 5
- $B = \min$ of the two dice is greater than 1

What is P(A|B)?

Another Exercise

Example: Throw of two dice. Each of the 36 outcomes are equally likely

- $A = \max$ of two dice is less than 5
- $B = \min$ of the two dice is greater than 1

What is P(A|B)?

- $P(A) = \frac{16}{36}$
- $P(B) = \frac{25}{36}$
- $P(A \cap B) = \frac{9}{36}$
- $P(A|B) = \frac{9}{25}$

Sequential Model for Conditional Probabilities

Many experiments have a sequential characteristic: the future outcomes depending on the past.

For example, consider an example involving three coin tosses.

- The first toss is unbiased (fair): P(H) = 0.5 and P(T) = 0.5.
- Based on the outcome of the first toss, the second toss is biased towards that outcome by 60%.
 - ► For example, if the outcome of the first toss is H, then the second toss has P(H) = 0.6 and P(T) = 0.4.
- Based on the outcome of the second toss, the third toss is biased towards that outcome by 70%.

Let us draw a tree-based sequential description.

Sequential Model for Conditional Probabilities

How to setup a tree-based sequential description and use it?

- 1. Leaves represent events of interest, which occur in a sequential manner
- 2. Branches represent the conditional probability
- 3. The probability of the end-leaf can be computed by multiplying conditional probabilities from the root.

Sequential Model for Conditional Probabilities



Multiplication Rule

• We learned conditional probability

$$P(A|B) = rac{P(A \cap B)}{P(B)},$$

which can be re-written as

$$P(A \cap B) = P(B)P(A|B) = P(A)(B|A)$$

• Now, what about

$$P(A \cap B \cap C) = ?$$

Multiplication Rule

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which can be re-written as

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• Now, what about

$$P(A \cap B \cap C) = P((A \cap B) \cap C)$$

= $P(D \cap C)$, where $D = (A \cap B)$
= $P(D)P(C|D)$
= $P(A \cap B)P(C|A \cap B)$
= $P(A)P(B|A)P(C|A \cap B)$

These are other equivalent results for $P(A \cap B \cap C)$.

Multiplication Rule

In general,

$$P(\bigcap_{i=1}^{n} A_{i}) \equiv P(A_{1} \cap A_{2} \cap \dots \cap A_{n})$$

= $P(A_{1})P(A_{2}|A_{1})P(A_{3}|A_{1} \cap A_{2}) \dots P(A_{n}|\bigcap_{i=1}^{n-1} A_{i})$

Total Probability Theorem and Bayes' Rule

Total Probability Theorem

- Let A_1, A_2, \ldots, A_n form a partition of Ω and $P(A_i) > 0$
- Then, for any event *B*, we have

$$P(B) = P(A_1 \cap B) + P(A_2 \cap B) + \dots + P(A_n \cap B)$$

= $P(A_1)P(B|A_1) + P(A_2)P(B|A_2) + \dots + P(A_n)P(B|A_n).$

Bayes' Rule

Let A_1, A_2, \ldots, A_n partition Ω and $P(A_i) > 0$. For any B such that P(B) > 0,

$$P(A_i|B) = \frac{P(A_i)P(B|A_i)}{P(B)}$$

= $\frac{P(A_i)P(B|A_i)}{P(A_1)P(B|A_1) + P(A_2)P(B|A_2) + \dots + P(A_n)P(B|A_n)}$

Independence

Independence

- Consider flipping a fair coin twice in a row.
- If we know the coin is fair, does knowing the result of the first flip give us any information about the result of the second flip?
- What's the probability the coin comes up heads on the second flip?
- What's the probability the coin comes up heads on the second flip given that it came up heads on the first flip?

Probabilistic Independence

- Intuitively, when knowing that one event occurred doesn't change the probability that another event occurred or will occur, we say that the two events are *probabilistically independent*.
- We say that two events A and B are independent if and only if (iff)

 $P(A \cap B) = P(A)P(B)$.

and this implies that P(A|B) = P(A) and P(B|A) = P(B).

Rolling Two Dice

• **Question:** Suppose you roll two fair four sided dice. Are the events *A* = "maximum is less than 3" and *B*= "sum is greater than 3" independent?



• Answer 2: Formally,

$$P(A \cap B) = \frac{1}{16}$$
, $P(A) = \frac{1}{4}$ and $P(B) = \frac{13}{16}$

Since $\frac{1}{16} \neq \frac{1}{4} \cdot \frac{13}{16}$, the events are not independent.

An Event and Its Complement

- Question: Are A and A^c independent if 0 < P(A) < 1?
- **Answer 1:** Intuitively, no. If you know A happens, then you know A^C does not happen.
- Answer 2: Formally, $P(A \cap A^C) = P(\emptyset) = 0$. If 0 < P(A) < 1, then

 $P(A)P(A^{C}) \neq 0$.

Independence of Three Events

• Three events A, B, and C are independent iff:

$$P(A \cap B) = P(A) P(B)$$
$$P(A \cap C) = P(A) P(C)$$
$$P(B \cap C) = P(B) P(C)$$
$$P(A \cap B \cap C) = P(A) P(B) P(C)$$

- First three conditions imply that any two events are independent (known as *pairwise independence*)
- *Pairwise independence* does not imply the *independence of all events*.
- Suppose we have a finite collection of events $A_1, A_2, ..., A_n$. These events are said to be independent iff

$$P\left(\cap_{i\in\mathcal{S}}A_i
ight)=\prod_{i\in\mathcal{S}}P(A_i), ext{ for every subset }\mathcal{S} ext{ of } \{1,2,...,n\}$$

Conditional Independence

• A and B are conditionally independent given C iff

 $P(A \cap B \mid C) = P(A \mid C) P(B \mid C)$

- This is equivalent to $P(A | B \cap C) = P(A | C)$, assuming that P(B | C) > 0.
 - If C is given, additional information of knowing B has occurred does not change the conditional probability of A.
- This is equivalent to $P(B \mid A \cap C) = P(B \mid C)$, assuming that $P(A \mid C) > 0$.
 - If C is given, additional information of knowing A has occurred does not change the conditional probability of B.

Counting

Counting and Discrete Probability Laws

• If $\boldsymbol{\Omega}$ is finite and all outcomes are equally likely, then

$$P(A) = \frac{|A|}{|\Omega|}$$

- The calculation of probabilities often involve **counting** the number of outcomes in various events.
- Sometimes it's challenging to compute |A| and $|\Omega|$ and they are too large work out by hand. . .
- We covered different counting methods:
 - Permutations

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- k-Permutations
- Combinations
- Partitions

The Counting Principle

• Consider a sequential process with *s* stages. At each stage *i*, there are *n_i* possible results. How many outcomes does the process have?



• How many possible outcomes are possible from a sequence of *s* stages?

The Counting Principle

• Consider a sequential process with *s* stages. At each stage *i*, there are *n_i* possible results. How many outcomes does the process have?



• How many possible outcomes are possible from a sequence of *s* stages?

$$n_1 \times n_2 \times \cdots \times n_s = \prod_{i=1}^s n_i.$$

Counting Permutations

- Let S be a set of n objects.
- Consider an *n*-stage experiment where at each stage we choose one object without replacement.

We pick objects until there's no more objects to pick.

- This process produces an **ordering** or **permutation** of the *n* objects.
 - ▶ For example, if n = 3 and S = {a, b, c}, one ordering can be bac.
- This is an *n* stage process. We have $s_1 = n$, $s_2 = n 1$,..., $s_n = 1$.
- By the counting principle, the number of permutations is

$$n(n-1)(n-2)\cdots 1 = n!$$

• For permutations, order matters, i.e., $abc \neq bac$.

Counting *k*-Permutations

- Let S be a set of n objects.
- Consider a k-stage experiment where k ≤ n. At each stage we choose one object without replacement.
 - We pick only k objects.
- This process produces an ordering of the k objects, which is also called a k-permutation.
 - ▶ For example, if n = 3, k = 2, and S = {a, b, c}, one possible 2-permutation is ba and another is ab.
- This is a k-stage process where $s_1 = n$, $s_2 = n 1$,..., $s_k = n k + 1$.
- By the counting principle, the number of permutations is

$$n(n-1)(n-2)\cdots(n-k+1) = \frac{n!}{(n-k)!}$$

• Order also matters for *k*-permutations.

Counting Combinations

- Let S be a set of n objects. How many subsets of size k are there?
- The number of k-permutations is n!/(n k)! but this over counts the number of subsets, e.g., ab and ba are different 2-permutations of {a, b, c}, but the same subset {a, b}.

Order does NOT matters for combinations.

• k! different k-permutations belong to the same subset of k objects, so the number of "k-combinations" is

$$\frac{\frac{n!}{(n-k)!}}{k!} = \frac{n!}{(n-k)!k!},$$

which is denoted $\binom{n}{k}$, pronounced as "*n* choose *k*".

• Note that $\binom{n}{0} = 1$
Counting Partitions

- A combination divides items into one group of k and one group of n − k. Thus, a combination can be viewed as a partition of the set in two.
- Consider an experiment where we divide n objects into ℓ groups with sizes n₁, n₂, ..., n_ℓ such that n = ∑^ℓ_{i=1} n_i.
- How many partitions are there?
- There are $\binom{n}{n_1}$ ways to choose the objects for the first partition. This leaves $n n_1$ objects. There are $\binom{n-n_1}{n_2}$ ways to choose objects for the second partition. There are $\binom{n-n_1-n_2-\ldots-n_{\ell-1}}{n_\ell}$ ways to choose the objects for the last group.

Counting Partitions

• Using the counting principle, the number of partitions is thus:

$$\binom{n}{n_1} \cdot \binom{n-n_1}{n_2} \cdots \binom{n-n_1-n_2-\dots-n_{\ell-1}}{n_\ell}$$
$$= \frac{n!}{n_1!(n-n_1)!} \cdot \frac{(n-n_1)!}{n_2!(n-n_1-n_2)!} \cdots \frac{(n-n_1-n_2-\dots-n_{\ell-1})!}{n_\ell!(n-n_1-n_2-\dots-n_\ell)!}$$

• Note that
$$(n - n_1 - n_2 - ... - n_\ell)! = 0! = 1.$$

• Canceling terms yields the final result:

$$\frac{n!}{n_1!\cdots n_\ell!}$$

Summary of Counting Problems

Structure	Description	Order Matters	Formula
Permutation	Number of ways to order <i>n</i> objects	Yes	<i>n</i> !
k-Permutation	Number of ways to form a se- quence of size k using k dif- ferent objects from a set of n objects	Yes	$\frac{n!}{(n-k)!}$
Combination	Number of ways to form a set of size k using k different ob- jects from a set of n objects	No	$\frac{n!}{k!(n-k)!}$
Partition	Number of ways to partition n objects into ℓ groups of size $n_1,, n_\ell$	No	$\frac{n!}{n_1!\dots n_\ell!}$

The Binomial Law

- If we toss n coins, what's the probability of seeing k heads, denoted as P_n(k)? (without exhaustively enumerating all sequences?)
- Any single sequence of length *n* with *k* heads has probability

$$p^k(1-p)^{n-k}$$
 .

• But how many different sequences of length *n* contain *k* heads?

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

where $\binom{n}{0} = 1$.

• Thus,

$$P_n(k) = \binom{n}{k} p^k (1-p)^{n-k}.$$

The Binomial Law

• The following equation is often called the **binomial probabilities**.

$$P_n(k) = \binom{n}{k} p^k (1-p)^{n-k},$$

where $\binom{n}{k}$ is referred to as **binomial coefficient**.

Discrete random variables and Probability mass functions

Random Variables Give An Easy Way to Specify Events

If we have a function X : Ω → ℝ, we can use it to construct a different event for each value of x ∈ ℝ:

$$\{X = x\} = \{o | o \in \Omega \text{ and } X(o) = x\}$$

In the dice example, the event {X = x} is the set of outcomes
 o ∈ Ω that are mapped to the the same value x by the
 function X.

For example,

$$\{X = 2\} = \{(1, 2), (2, 1), (2, 2)\}$$
$$\{X = 3\} = \{(1, 3), (2, 3), (3, 3)(3, 1), (3, 2)\}$$
$$\{X = 1\} = \{(1, 1)\}$$

Discrete Random Variables and Probability

- A random variable is called **discrete** if its input (sample space) is either finite or countably infinite.
- We can compute the probability of an event {X = x} by decomposing it into atomic events and using the probability rule:

$$P(X = x) = p_X(x) = P(\{o | o \in \Omega \text{ and } X(o) = x\})$$

- Probability law: A function p_X(x) that maps event to a number between 0 and 1 that satisfies the probability axioms:
 - 1. Nonnegativity: $p_X(x) \ge 0, \forall x$.
 - 2. Normalization: $\sum_{x} p_X(x) = 1$.

Example: Maximum of Dice Rolls

For example, in the event of {X = 2} for the dice rolling example where X(r₁, r₂) = max(r₁, r₂)

$$P(X = 2) = P(\{(1, 2), (2, 1), (2, 2)\})$$

= $P((1, 2)) + P((2, 1)) + P((2, 2)) = 3/16$

• We can work out the probability for all possible values of x:



In general...

- The probability associated with the event {X = x} for each element x ∈ ℝ of a discrete random variable X is referred to as the probability mass function or PMF of the random variable.
- The PMF is denoted by P(X = x) or $p_X(x)$.



The x-axis represents all possible outcomes of the event
 The y-axis represents the associated probabilities

Common Discrete Random Variables

Discrete Uniform Random Variables

- A *discrete uniform random variable X* with range [a, b] takes on any integer value between (and including) *a* and *b* with the same probability
- For example, the random variable that maps a fair six-sided dice roll to the number that comes up is a uniform random variable with a = 1, b = 6 and P(X = k) = 1/6 for k = 1, ..., 6.
- The PMF of a discrete uniform random variable X is

$$P(X = k) = \frac{1}{b - a + 1}$$
 for $k = a, ..., b$

• Used to model probabilistic situations where each of the values *a*, ..., *b* are equally likely.

Bernoulli Random Variables

- Suppose we have an experiment with two outcomes H and T. H happens with probability p and T with probability 1 - p, 0
- We define a random variable X such that X(H) = 1 and X(T) = 0.
- This is called a Bernoulli random variable X that takes the two values 0 or 1.
- Its PMF looks like

$$P(X = k) = \begin{cases} 1 - p & \text{if } k = 0\\ p & \text{if } k = 1 \end{cases}$$

• You can also define X(H) = 0 and X(T) = 1, with P(X = 1) = p' = 1 - p

Bernoulli Random Variables: Examples

- Whether a coin lands heads or tails.
- Whether a server is online or offline.
- Whether an email is spam or not.
- Whether a pixel in a black and white image is black or white.
- Whether a patient has a disease or not.

Binomial Random Variable

- A binomial random variable is the combination of independent and identically distributed Bernoulli random variables
- Suppose we flip *n* coins independently, where each coin has probability *p* of being heads
- The set of outcomes is:

$$\Omega = \{(TTT \dots TT), (TTT \dots TH), \dots, (HHH \dots HH)\}$$

• Define a random variable X where for each $o \in \Omega$,

X(o) = "the number of heads in outcome o"

• We're already shown that $P(X = k) = \binom{n}{k} p^k (1-p)^{n-k}$.

Binomial Random Variables: Examples

- The number of heads in N coin tosses.
- The number of servers that fail in a cluster of N servers.
- The number of games a football team wins in a season of *N* games (assuming i.i.d.).
- The number of True/False questions you get correct if you guess each of *N* questions.

Geometric Random Variables

- Suppose we flip a biased coin repeatedly until it lands heads. Let X be the number of tosses needed for a head to come up for the first time.
- The PMF of a geometric random variable X is

$$P(X = k) = (1 - p)^{k-1} \cdot p$$
 for $k = 1, 2, 3, ...$

- Used to model the number of repeated independent trials up to (and including) the *first "successful" trial*.
- Example: the number of patients we test before the first one we find who has a given disease.

Geometric Random Variables: Example

- Products made by a machine have a 3% defective rate.
- What is the probability that the first defect occurs in the fifth item inspected?

$$P(X = k) = (1 - p)^{k-1} \cdot p = (1 - 0.03)^{5-1} \cdot 0.03 = 0.0265 \dots$$

• A *Poisson random variable X* is a random variable that has the following PMF

$$P(X=k)=e^{-\lambda}rac{\lambda^k}{k!}$$
 for $k=0,1,2,\ldots$

- The Poisson distribution is one of the most widely used probability distributions.
- Built based on Taylor series: $e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$.
- Think about Poisson RV as a framework that provides approximation of a real-life random variable as a function of λ.

• Think about Poisson RV as a framework that provides approximation of different PMFs as a function of λ .



- It is generally used in scenarios where we are counting the occurrences of certain events within an interval of time or space.
 - The number of typos in a book with n words.
 - The number of cars that crash in a city on a given day.
 - The number of phone calls arriving at a call center per minute etc.
- λ represents the expected number of events (we will learn more about this).
 - The average number of typos in a book.
 - The average number of car crash per day.
 - The average number of phone calls per minute.

Poisson Random Variables: Example

- Suppose that the number of phone calls arriving at a call center per minute can be modeled by a discrete Poisson PMF.
- In average, the call center receives 10 calls.
- What is the probability that the center will receive 5 calls?

$$P_X(k) = e^{-\lambda} \frac{\lambda^k}{k!}$$

 $P_X(k) = e^{-10} \frac{10^5}{5!} = 0.0378...$

- A Poisson PMF with λ = np is a good approximation for a binomial PMF with very small p and very large n if k ≪ n
 - A bionomial RV X is the number of heads (k) in the n-toss sequence, where the coin comes up a head with probability p.
- Example: n = 100 and p = 0.01 for the binomial r.v. where as $\lambda = np$ for the Poisson r.v.



• Poisson PMF provides much simpler models and calculations: $\binom{n}{k}p^k(1-p)^{n-k}$ vs. $e^{-\lambda}\frac{\lambda^k}{k!}$

Summary: Discrete Random Variables

• Uniform: For
$$k = a, \ldots, b$$
:

$$P(X=k)=\frac{1}{b-a+1}$$

• **Bernoulli:** For k = 0 or 1:

$$P(X = k) = \begin{cases} 1 - p & \text{if } k = 0\\ p & \text{if } k = 1 \end{cases}$$

• **Binomial:** For $k = 0, \ldots, N$

$$P(X = k) = \binom{N}{k} p^{k} (1-p)^{N-k}$$

- Geometric: For $k = 1, 2, 3, ..., P(X = k) = (1 p)^{k-1} \cdot p$
- **Poisson:** $P(X = k) = e^{-\lambda} \frac{\lambda^k}{k!}$ for k = 0, 1, 2, ...

Expectation and Variance

Expected Value

• For a random variable X, the expected value is defined to be:

$$E[X] = \sum_{x \in \mathbb{R}} x P(X = x)$$

i.e., the probability-weighted average of the possible values of X.

- *E*[*X*] is also called the **expectation** or **mean** of *X*.
- Why do we care to know about the expected value?
- Given a certain PMF, what is the "average" outcome that I am expecting to have?
- For example, if I bet the same amount of money on roulette and play it for a long-term period, how much do I expect to make?

Expected Value: Question

• Expectation:

$$\mathsf{E}[X] = \sum_{k \in \mathbb{R}} k \, \mathsf{P}(X = k)$$

• If X maps to {1,2,6} and

P(X = 1) = 1/3 , P(X = 2) = 1/2 , P(X = 6) = 1/6

then $E[X] = 1 \cdot \frac{1}{3} + 2 \cdot \frac{1}{2} + 6 \cdot \frac{1}{6} = 2.33...$

Expectations of Common Random Variables

- Uniform on $\{a, a + 1, ..., b\}$: $E[X] = \frac{a+b}{2}$
- **Bernoulli:** $E[X] = (1 p) \cdot 0 + p \cdot 1 = p$
- **Binomial:** $E[X] = \sum_{k=0}^{n} k \cdot {n \choose k} p^{k} (1-p)^{n-k} = np$
- **Geometric:** $E[X] = \sum_{k=1}^{\infty} k \cdot (1-p)^{k-1} p = \frac{1}{p}$
- Poisson: $E[X] = \sum_{k=0}^{\infty} k \cdot \frac{e^{-\lambda}}{k!} \lambda^k = \lambda$

Properties of Expectation

• Linearity of Expectation: If *a* and *b* are any real values, then the expectation of *aX* + *b* is:

$$E[aX+b] = a \cdot E[X] + b$$

• Expectation of Expectation: Applying the expectation operator more than once has no effect. E[E[X]] = E[X] since E[X] is already a constant.

Variance

• **Definition**: Variance measures how far we expect a random variable to be from its average:

$$\operatorname{var}(X) = E[(X - E[X])^2] = \sum_k (k - E[X])^2 \cdot P(X = k)$$

• An equivalent definition is

$$\operatorname{var}(X) = E[X^2] - E[X]^2$$

• **Definition**: we generally define the **nth moment** of X as $E[X^n]$, the expected value of the random variable X^n .

Variance of Common Random Variables

• **Bernoulli:** var[X] = p(1 - p)

• Binomial:
$$var[X] = np(1-p)$$

• Geometric:
$$var[X] = \frac{1-p}{p^2}$$

• Uniform:
$$var[X] = \frac{(b-a+1)^2-1}{12}$$

• **Poisson:**
$$var[X] = \lambda$$

Standard Deviation

• The term **standard deviation** simply refers to the positive square root of the variance, which always exists and is also positive:

$$\mathsf{std}(X) = \sqrt{\mathsf{var}(X)}$$

- The standard deviation is **also** a measure of dispersion around the mean.
- One reason that people like to report standard deviations instead of variances is that **the units are the same as** *X*.
- $var(X) = E[(X E[X])^2] vs. std(X) = \sqrt{E[(X E[X])^2]}$
- Example 1: If X is height in feet, then var(X) has units in square feet while std(X) again has units in feet.

• If X is a random variable and $f : \mathbb{R} \to \mathbb{R}$ then

$$Y = f(X)$$

is also a random variable with PMF:

$$P(Y = k) = P(f(X) = k) = \sum_{o \in \Omega \text{ with } f(X(o)) = k} P(o)$$

• Example, let X represent an outcome from a 6 sided fair die where

$$P(X=i)=1/6, \forall i.$$

Suppose that you will receive money that is the square of the outcome, and we define a r.v. Y as the amount of money.

• This function Y = f(X) can be expressed as

$$Y = X^2$$

• Note that Y is also a random variable, whose PMF looks like.



• Expectation of Y = f(X):

$$E[Y] = \sum_{y} yP(Y = y) = \sum_{y} yP(X = f^{-1}(y))$$
$$= \sum_{x} f(x)P(X = x)$$

• For the previous example,

$$E[X] = 1 \times 1/6 + 2 \times 1/6 + \dots + 6 \times 1/6 = 3.5$$
$$E[Y] = 1^2 \times 1/6 + 2^2 \times 1/6 + \dots + 6^2 \times 1/6 = \$15.2$$
Functions of Random Variables

• Variance of Y:

$$var[Y] = E[(Y - E[Y])^{2}] = \sum_{k \in \{1,4,\dots,36\}} (k - E[Y])^{2} \cdot P(Y = k)$$

$$= \sum_{k \in \{1,4,\dots,36\}} (k - E[Y])^{2} \cdot P(X = f^{-1}(k))$$

$$= (1 - E[Y])^{2} P(X = \sqrt{1}) + (4 - E[Y])^{2} P(X = \sqrt{4}) + \cdots$$

• For the previous example,

$$E[X] = 1 \times 1/6 + 2 \times 1/6 + \dots + 6 \times 1/6 = 3.5$$
$$E[Y] = 1^2 \times 1/6 + 2^2 \times 1/6 + \dots + 6^2 \times 1/6 = \$15.2$$

• Then, the variance for Y is

$$var[Y] = (1^2 - 15.2)^2 \times 1/6 + (2^2 - 15.2)^2 \times 1/6 + \cdots$$

+ $(6^2 - 15.2)^2 \times 1/6 = 149.1$

Example: Linear function

$$\operatorname{var}[Y] = \operatorname{var}[aX + b]$$

$$= \sum_{k} (ak + b - E[aX + b])^{2} P(X = k)$$

$$= \sum_{k} (ak + b - aE[X] - b)^{2} P(X = k)$$

$$= \sum_{k} (ak - aE[X])^{2} P(X = k)$$

$$= a^{2} \sum_{k} (k - E[X])^{2} P(X = k)$$

$$= a^{2} \operatorname{var}[X].$$

Multiple Random Variables

Multiple Random Variables

- Consider two random variables, X and Y associated with the same experiment.
- For $x, y \in \mathbb{R}$, we can define events of the form

$$\{X = x, Y = y\} = \{X = x\} \cap \{Y = y\}$$

• The probabilities of these events give the **joint PMF** of X and Y:

 $p_{X,Y}(x,y) = P(X = x, Y = y) = P(X = x \text{ and } Y = y) = P(\{X = x\} \cap \{Y = y\})$

• Useful for describing **multiple properties** over the outcome space of a single experiment, e.g., pick a random student and let X be their height and Y be their weight.

Tabular Representation of Joint PMFs

P(X,Y)								
X\Y	Y = 1	<i>Y</i> = 2	<i>Y</i> = 3	<i>Y</i> = 4				
X = 1	0.1	0.1	0	0.2				
<i>X</i> = 2	0.05	0.05	0.1	0				
<i>X</i> = 3	0	0.1	0.2	0.1				

- e.g., P(X = 2, Y = 3) = ?, P(X = 3, Y = 1) = ?, ...
- Given the joint PMF, can we compute P(X = x) and P(Y = y)?

$$p_X(x) = P(X = x) = \sum_y P(X = x, Y = y)$$

 $p_Y(y) = P(Y = y) = \sum_x P(X = x, Y = y)$

 If we start with the joint PMF of X and Y, we say p_X(x) is the marginal PMF of X and p_Y(y) is the marginal PMF of Y.

Computing Marginals from the Joint Distribution

• Suppose Y takes the values y_1, y_2, \ldots, y_N , then

$$\{Y = y_1\}, \{Y = y_2\}, \dots, \{Y = y_N\}$$

form partitions of Ω_Y .

• Hence, $\{X = x\}$ can be partitioned into

$$\{X = x\} \cap \{Y = y_1\}, \{X = x\} \cap \{Y = y_2\}, \dots, \{X = x\} \cap \{Y = y_N\}$$

Therefore,

$$P(X = x) = P(\{X = x\})$$

= $P(\{X = x\} \cap \{Y = y_1\}) + P(\{X = x\} \cap \{Y = y_2\})$
...+ $P(\{X = x\} \cap \{Y = y_N\})$
= $\sum_{y} P(\{X = x\} \cap \{Y = y\}) = \sum_{y} P(X = x, Y = y)$

Marginal PMFs

P(X,Y)							
X\Y	1	2	3	4		Х	P(X)
1	0.1	0.1	0	0.2		1	0.4
2	0.05	0.05	0.1	0		2	0.2
3	0	0.1	0.2	0.1		3	0.4

Marginal PMFs



Y	1	2	3	4	
P(Y)	0.15	0.25	0.3	0.3	



What's the value of P(X = 2, Y = 3)?

- A: 0
- B: 0.1
- C: 0.05
- D: 0.2
- E: 1



What's the value of P(X = 2, Y = 3)?

A: 0

- B: 0.1
- C: 0.05
- D: 0.2
- E: 1

Answer is B.



What's the value of P(X = 3)?

- A: 0.1
- **B**: 0.4
- C: 0.05
- D: 0.6
- E: 1



What's the value of P(X = 3)?

- A: 0.1
- B: 0.4
- C: 0.05
- D: 0.6
- E: 1

Answer is D.

Conditional PMFs

• Conditional PMF of X given Y:

$$P(X = i | Y = j) = P(\{X = i\} | \{Y = j\}).$$

• Compute *P*(*X*|*Y*) using the definition of conditional probability:

$$P(X = i | Y = j) = \frac{P(X = i, Y = j)}{P(Y = j)}$$

since for any two events A, B we have $P(A|B) = \frac{P(A \cap B)}{P(B)}$.

- The conditional probability P(X = i | Y = j) is the joint probability P(X = i, Y = j) normalized by the marginal P(Y = j).
- An equivalent definition of independence is X and Y are independent if

for all
$$i, j$$
, $P(X = i | Y = j) = P(X = i)$

Conditional PMFs

P(X,Y)								
X\Y 1 2 3 4								
1	0.1	0.1	0	0.2				
2	0.05	0.05	0.1	0				
3	0	0.1	0.2	0.1				

Y	1	2	3	4	
P(Y)	0.15	0.25	0.3	0.3	

P(X Y)								
$X \setminus Y$	4							
1	0.66	0.4	0	0.66				
2	0.33	0.2	0.33	0				
3	0	0.4	0.66	0.33				

Functions of Two Random Variables

Given two random variables X and Y and a function $f : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$,

$$Z=f(X,Y)$$

is a new random variable.

For example, pick random students and let X be their height and Y be their weight. If we define Z as the Body Mass Index (BMI) where

$$\mathsf{BMI}=\mathsf{weight}\;(\mathsf{lb})/(\mathsf{height}\;(\mathsf{in}))^2 imes703.$$

That is,

$$Z = f(X, Y) = Y/X^2 \times 703.$$

Then, Z is also a random variable.

Functions of Two Random Variables

The PMF of Z can be expressed as

$$p_Z(z) = \sum_{\{(x,y)|f(x,y)=z\}} p_{X,Y}(x,y).$$

For example, let us define a new random variable $Z = X \times Y$ where the joint PMF of X and Y is

P(X,Y)							
X\Y 1 2 3 4							
1	0.1	0.1	0	0			
2	0	0.05	0.1	0.05			
3	0.1	0.2	0.2	0.1			

Then, the PMF of Z looks like

Ζ	1	2	3	4	6	8	9	12
P(Z)	0.1	0.1	0.1	0.05	0.3	0.05	0.2	0.1

Expectation and Variance of Two Random Variables

• The expected value and variance of Z can be respectively computed as

$$E[Z] = \sum_{z} zP(Z = z) = \sum_{x,y} f(x,y)P(X = x, Y = y)$$
$$= \sum_{x} \sum_{y} f(x,y)P(X = x, Y = y)$$
$$= \sum_{y} \sum_{x} f(x,y)P(X = x, Y = y)$$

and

$$var(Z) = E[Z^2] - E[Z]^2.$$

• If X and Y are **independent**, for all x, y

$$P(X = x, Y = y) = P(X = x)P(Y = y).$$

Linearity of Expectation

• Lemma: Given two random variables X, Y, and Z = X + Y then

$$E[Z] = E[X + Y] = E[X] + E[Y]$$

• Lemma: If X and Y are independent then

E[XY] = E[X]E[Y]var(X + Y) = var(X) + var(Y)

Multiple Random Variables

• Given random variables X_1, X_2, \ldots, X_N and a function $f : \mathbb{R} \times \mathbb{R} \times \ldots \times \mathbb{R} \to \mathbb{R}$,

$$Z = f(X_1, X_2, \ldots, X_N)$$

is a new random variable.

• Linearity of Expectation: If $Z = \sum_{i=1}^{N} X_i$,

$$E[Z] = E\left[\sum_{i=1}^{N} X_i\right] = \sum_{i=1}^{N} E[X_i]$$

• Independence: If X_1, \ldots, X_N are independent,

$$P_{X_1,\cdots,X_N}(x_i,\cdots,x_N) = \prod_{i=1}^N P_{X_i}(x_i)$$

• Linearity of Variance: If $Z = \sum_{i=1}^{N} X_i$ and all X_i are independent,

$$var[Z] = var\left(\sum_{i=1}^{N} X_i\right) = \sum_{i=1}^{N} var[X_i]$$